

Reconstruction

Maarten de Jong

Reconstruction $\equiv$ Fit of model parameters to data

Introduction

1. Precision of estimation of parameters increases with more information
2. For a given set of data (i.e. amount of information),
maximum likelihood yields smallest variance of parameters
3. Science output of KM3NeT relies on reconstruction

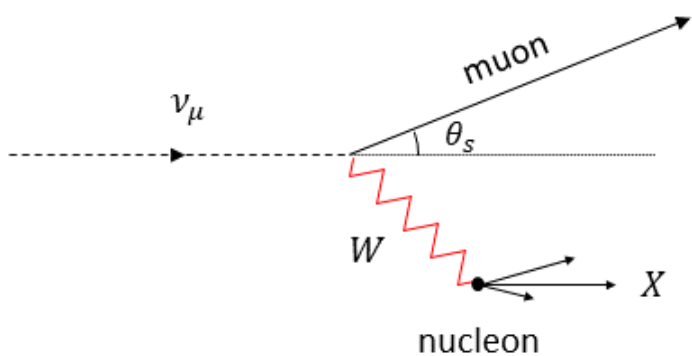
Introduction

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PDF describing data

“golden” channel

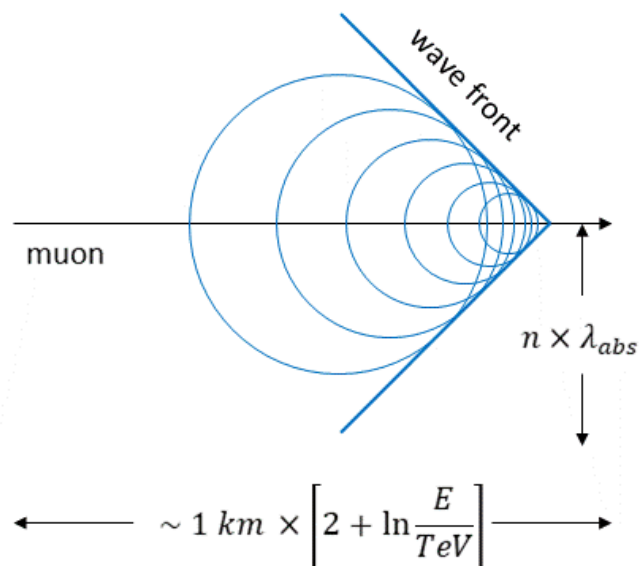
neutrino interaction



$$\theta_s \sim \delta\theta$$

+

Cherenkov light



=

1. Target mass

overcome small cross section

2. Transparency

sparse sensor array

3. Muon range

good angular resolution

Me & muon reconstruction

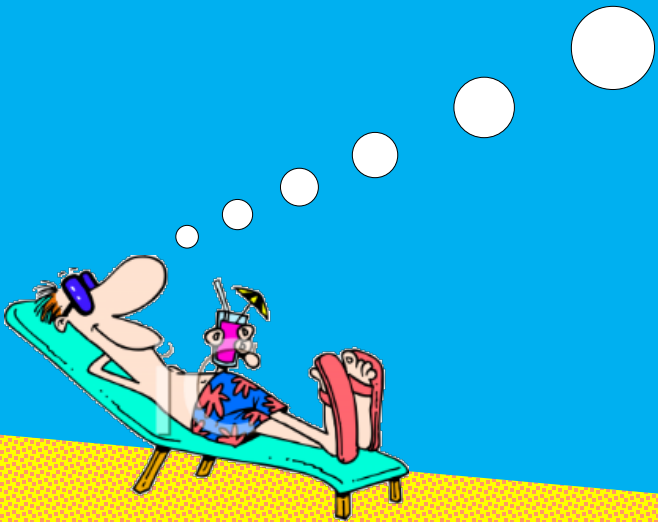
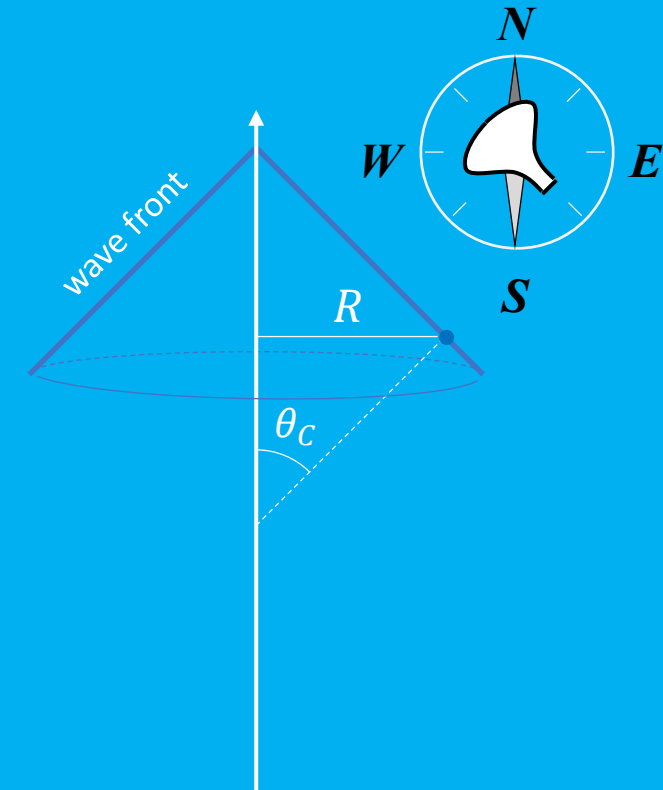
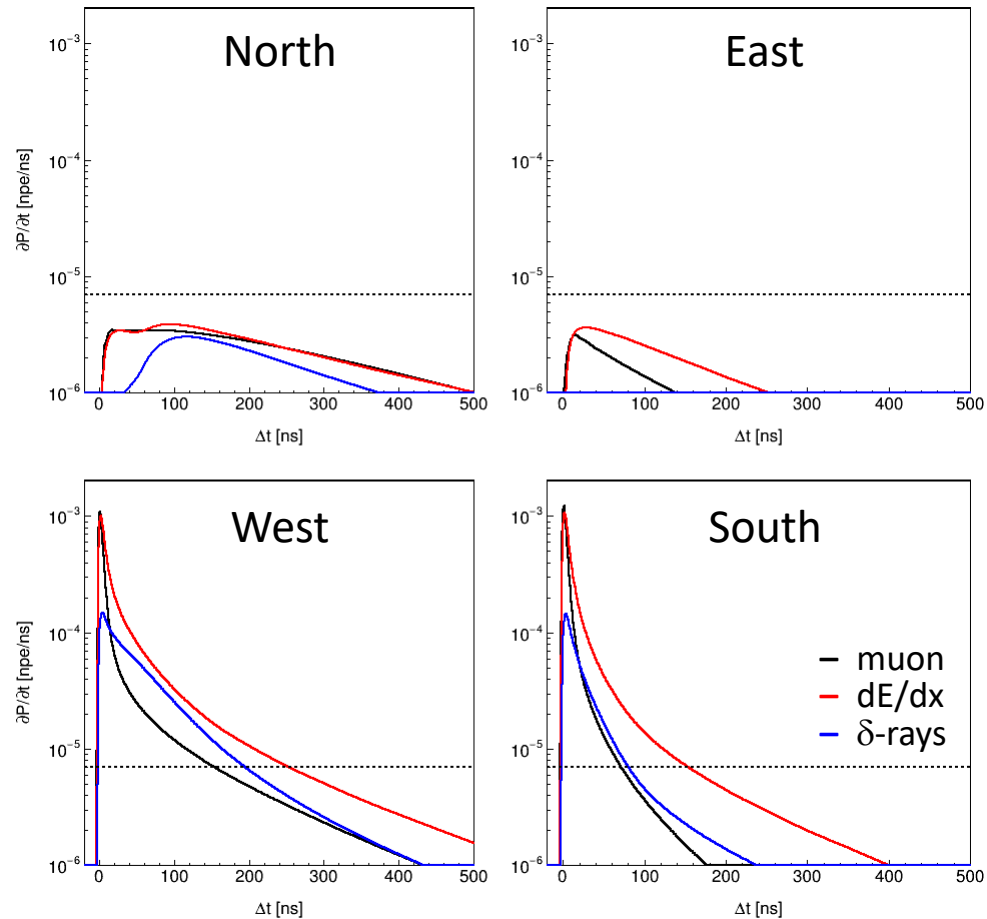
- *Muoproduction of J/ψ -mesons and the gluon distribution in nucleons,*[¶]
PhD thesis, M. de Jong
- Track reconstruction for the Chorus experiment[§]
- Track reconstruction for KM3NeT/ARCA and KM3NeT/ORCA

[¶] Track reconstruction near muon beam to cover small angle scattering.

[§] Track reconstruction incorporating multiple-Coulomb scattering in co-variance matrix (20% more events in physics target).

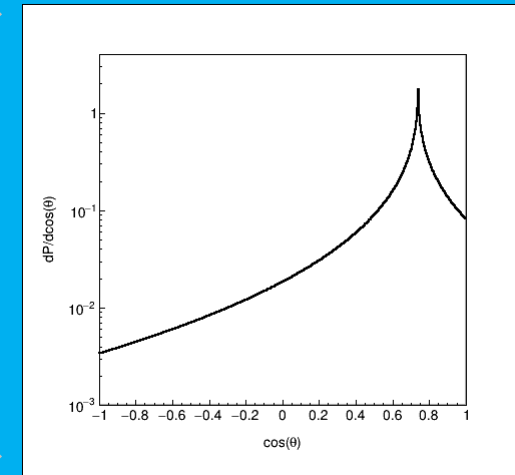
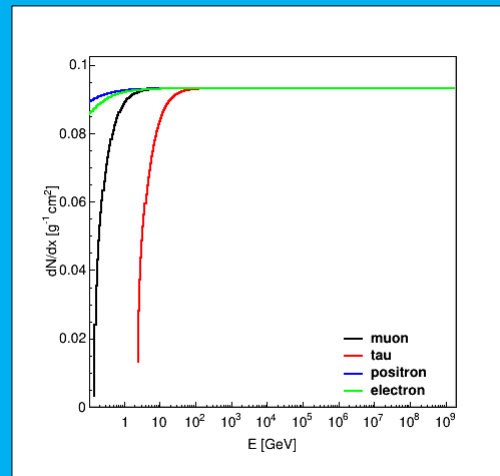
Model

PDF of Cherenkov light

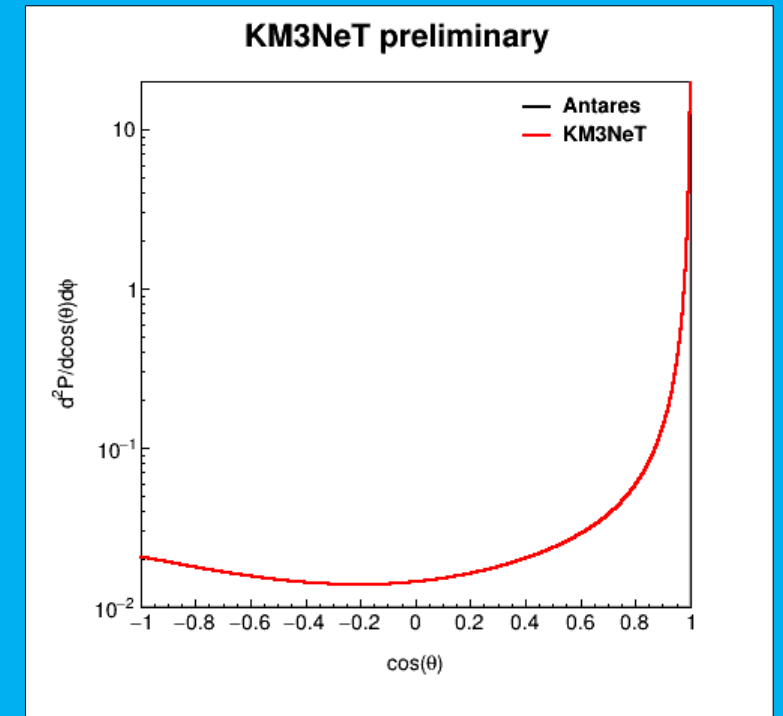
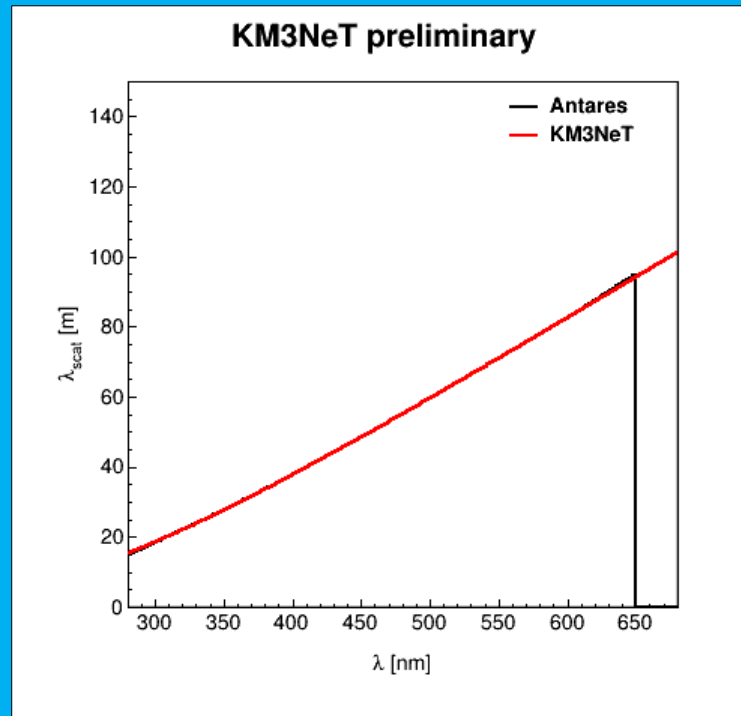
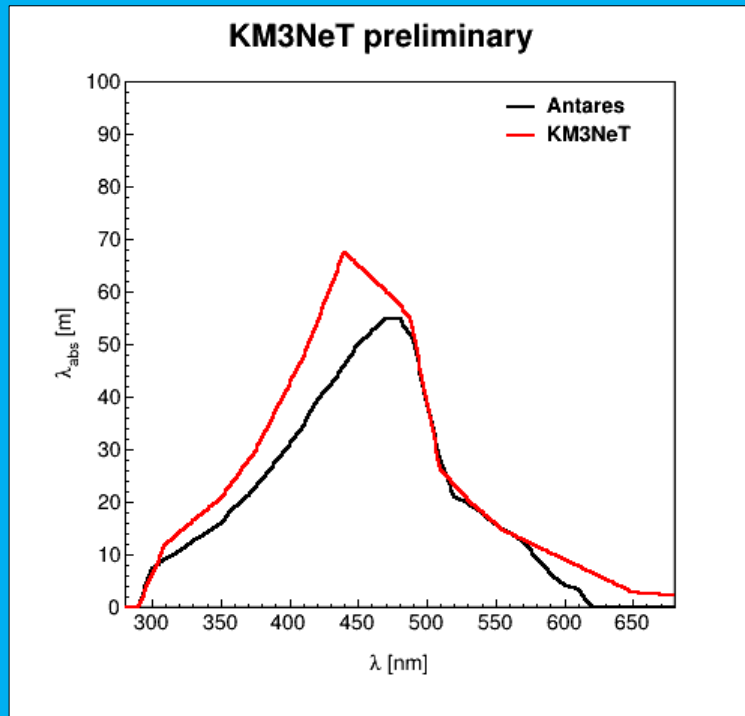


Light generation

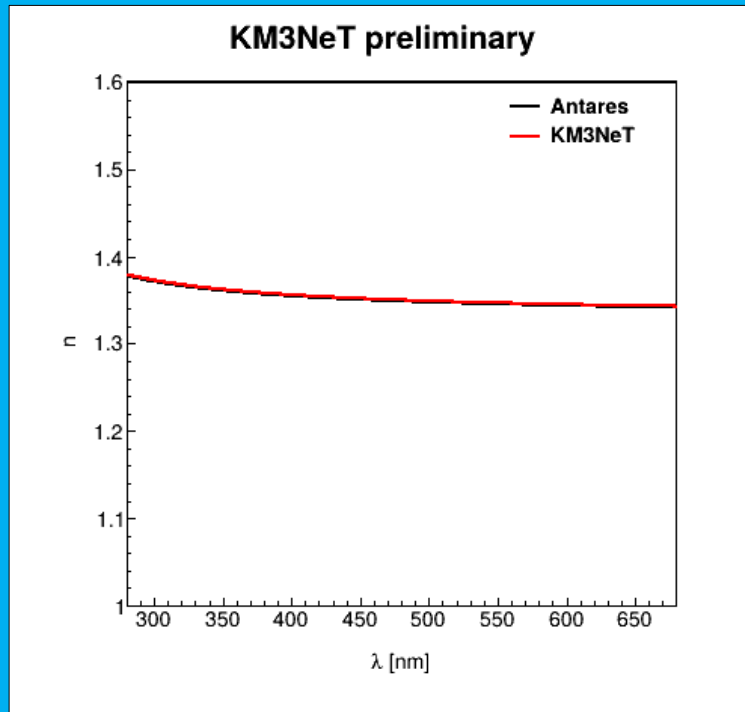
- Cherenkov formula: $\frac{\partial^2 N}{\partial x \partial \lambda} = \frac{10^9}{\lambda^2} \times 2\pi \times \alpha_{EM} \times (1 - n^{-2})$
- Muon energy loss: $-\frac{dE}{dx} = a + bE$
- EM particle shower: $1 \text{ GeV} \equiv 4.73 m$
- δ -rays:



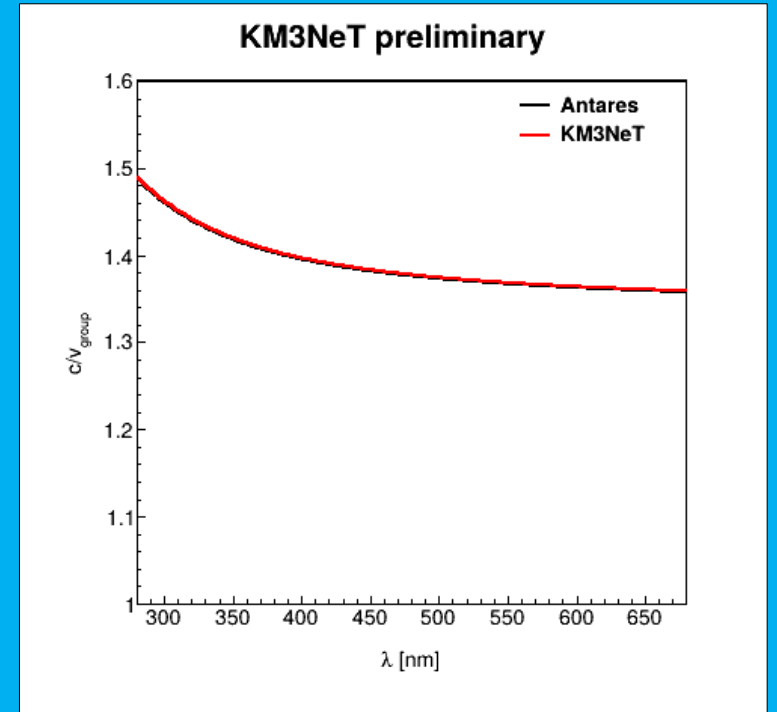
Light propagation (1/2)



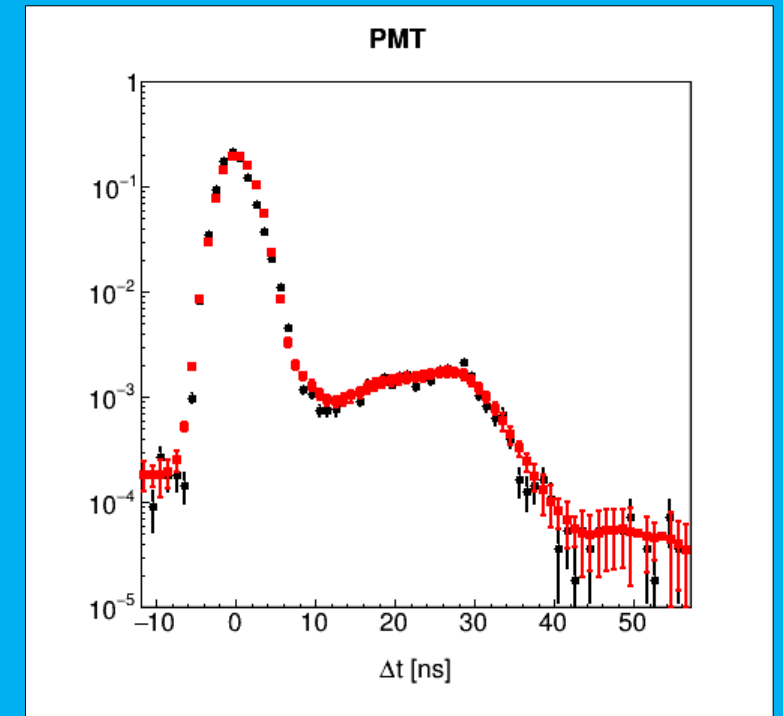
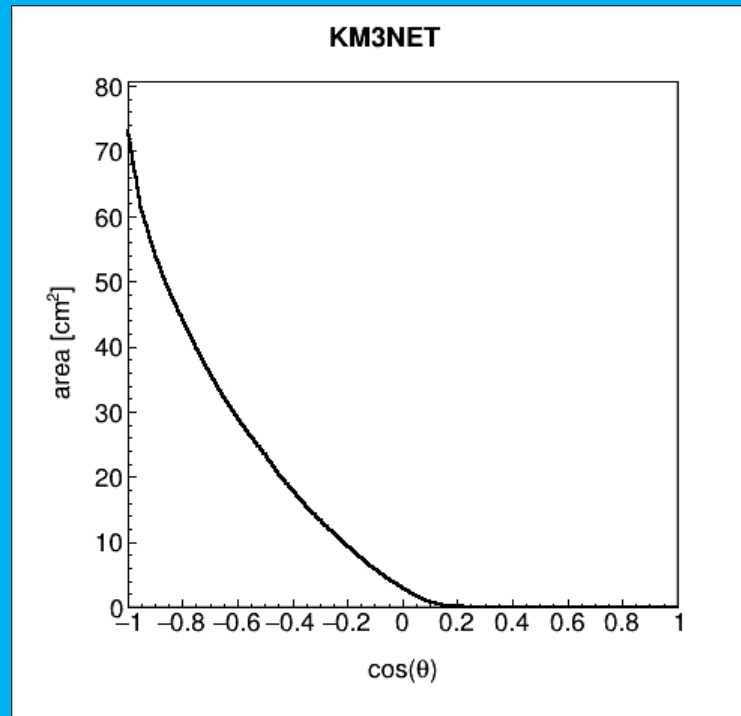
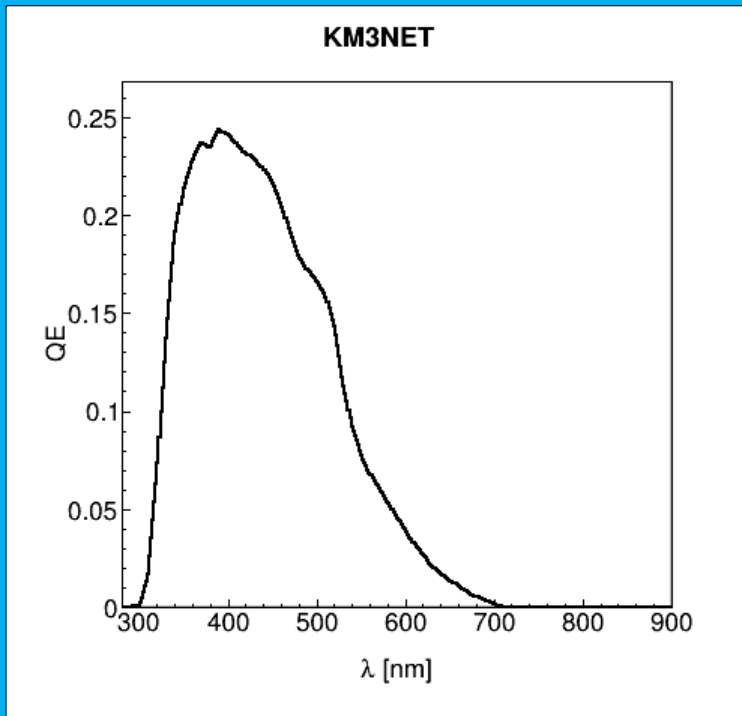
Light propagation (2/2)



$$\Rightarrow \frac{\partial n}{\partial \lambda} \neq 0 \Rightarrow$$



Light detection



a posteriori correction

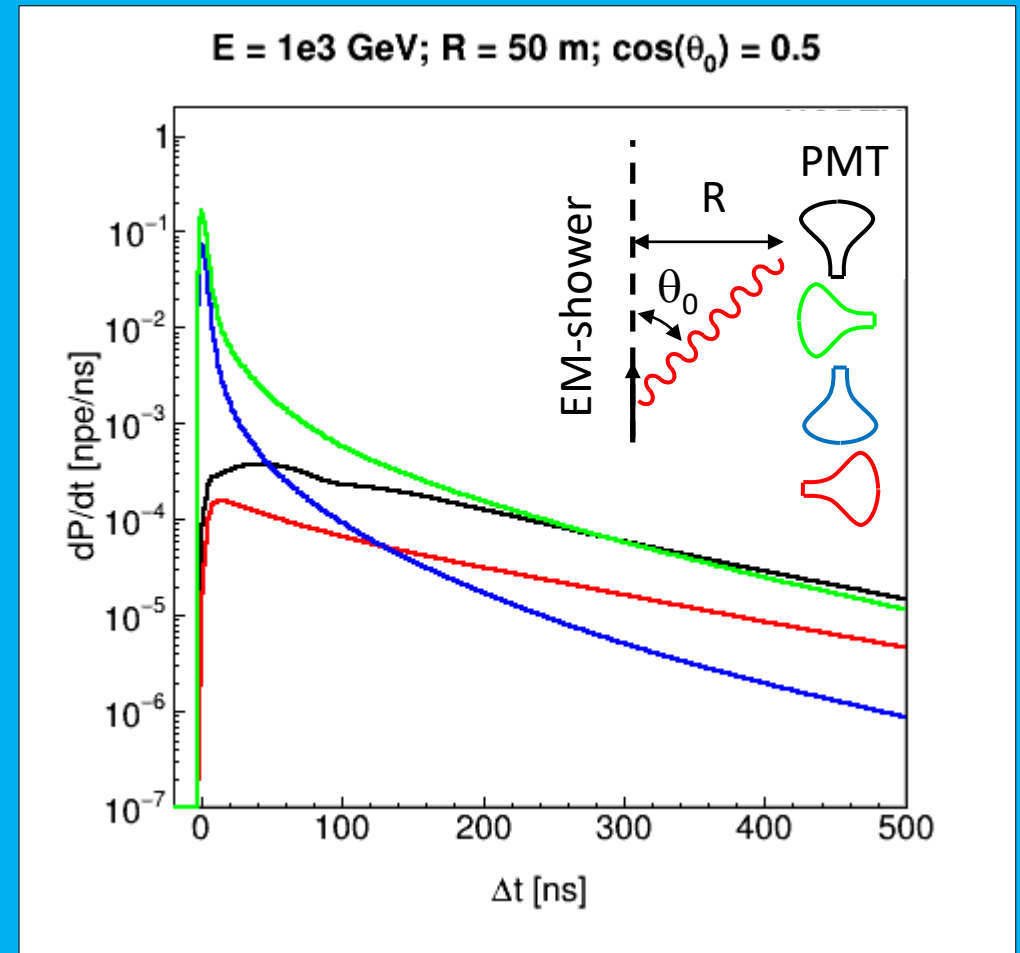
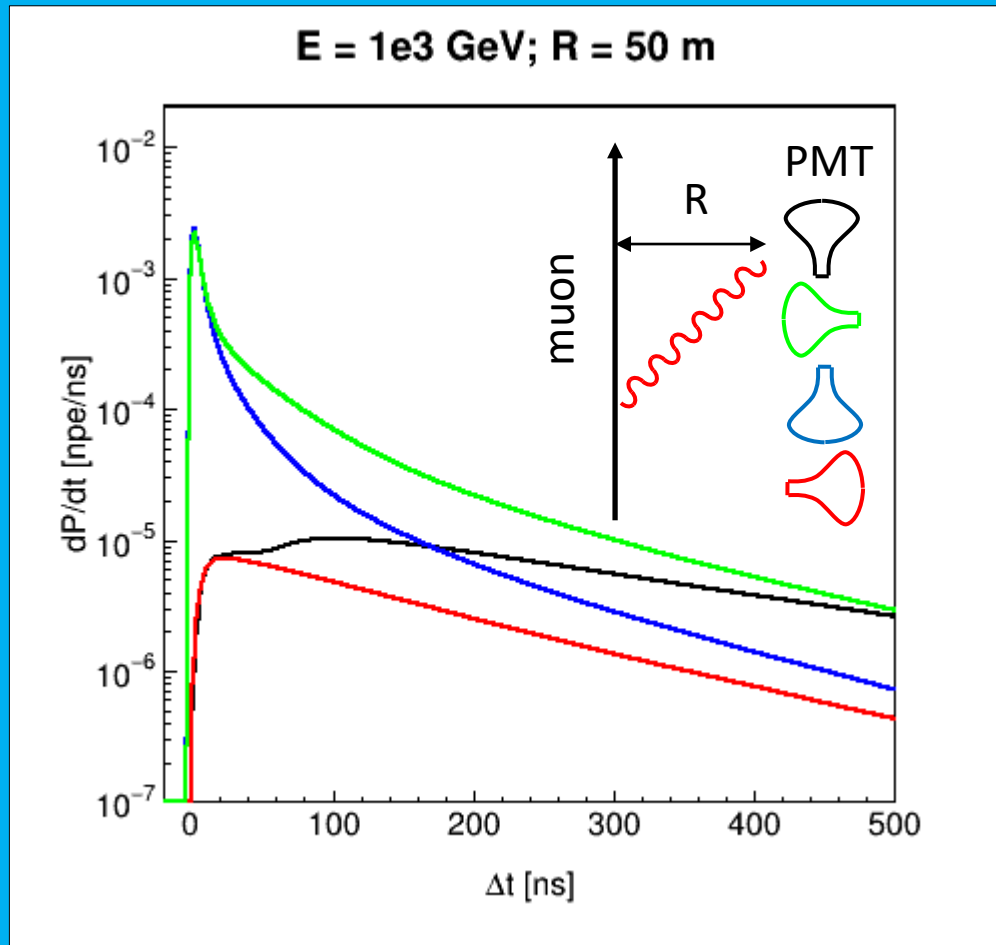
PDF (1/2)

- PDF of arrival time of Cherenkov light involves numerical integration
 - usually done with Monte Carlo technique
 - can efficiently be calculated from first principles when scattering length is much larger than absorption length (see [documentation](#), Maarten and Emanuel)

$$\frac{d\mathcal{P}}{dt} = \iiint d\lambda dz d\phi_0 \frac{1}{2\pi} \frac{dN}{dx} \frac{1}{\lambda_s} \left(\frac{\partial t}{\partial u} \right)^{-1} \varepsilon(\cos \theta_\odot) QE(\lambda) e^{-d/\lambda_{att}} \frac{dP_s}{d\Omega_s} d\Omega$$

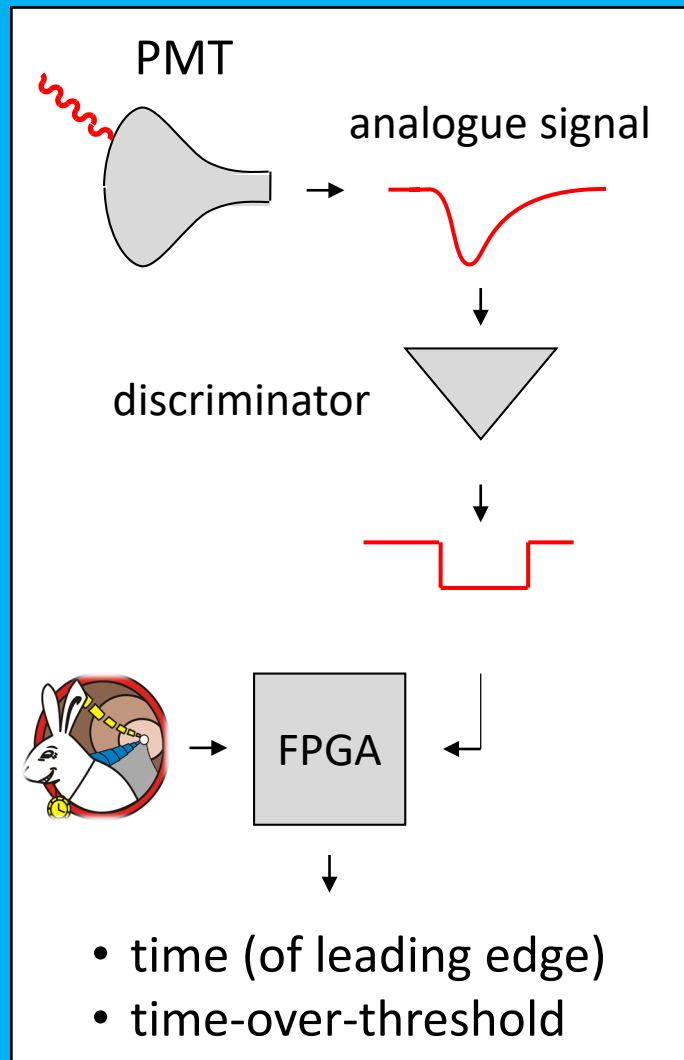
$\frac{\partial N_s}{\partial u}$ $\frac{1}{1 - \cos \theta_s}$

PDF (2/2)



data

Off-shore signal processing



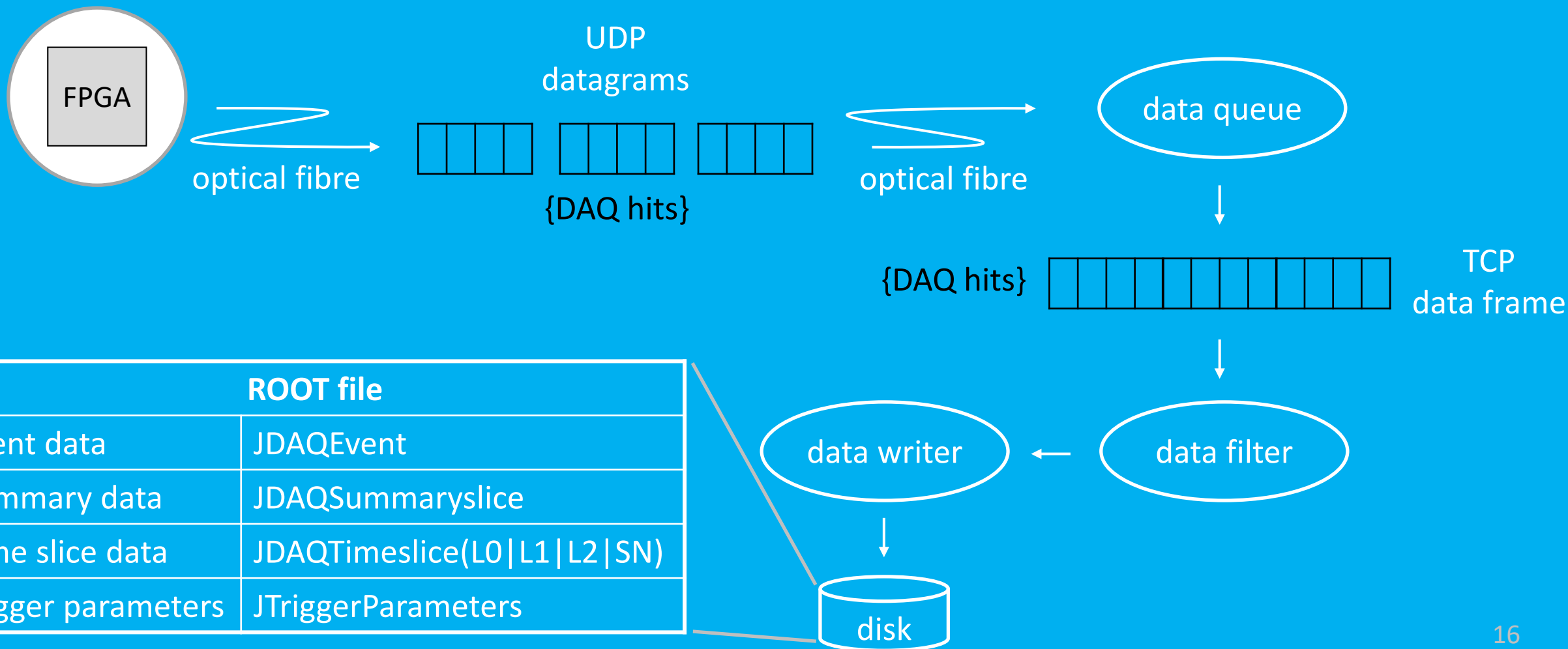
3" PMT	
QE	0.25
TTS	1.5 ns
gain	10^6
gain spread	0.3

discriminator	
threshold	0.20 p.e.

DAQ hit		
PMT		1B
time	1 ns	4B
time-over-threshold	1 ns	1B

On-shore signal processing

optical module



Data processing (1/3)

- Level-0 (L0)
 - L0 hit = calibrated DAQ hit (time as well as position and orientation of PMT)
- Level-1 (L1)
 - L1 hit = coincidences of two (or more) L0 hits in the same optical module within a predefined time window (usually around 10 ns)
- Level-2 (L2)
 - L2 hit = L1 hit with additional constraints (e.g. space angle between PMT axes)
- Supernova (SN)
 - SN hit = L1 hit with additional constraints (e.g. multiplicity of L0 hits)

Data processing (2/3)

- Time slice
 - container of all DAQ hits according level-n selection

- Summary data
 - rate information per PMT (1B)
 - PMT status information (1b)
 - high-rate veto, FIFO (almost) full, etc.

```
// histogram binning
static int          JDAQRate::getN();
static const double* JDAQRate::getData();

// histogram filling
double JDAQSummaryFrame::getRate(const int tdc);
double JDAQSummaryFrame::getWeight(const int tdc);
```

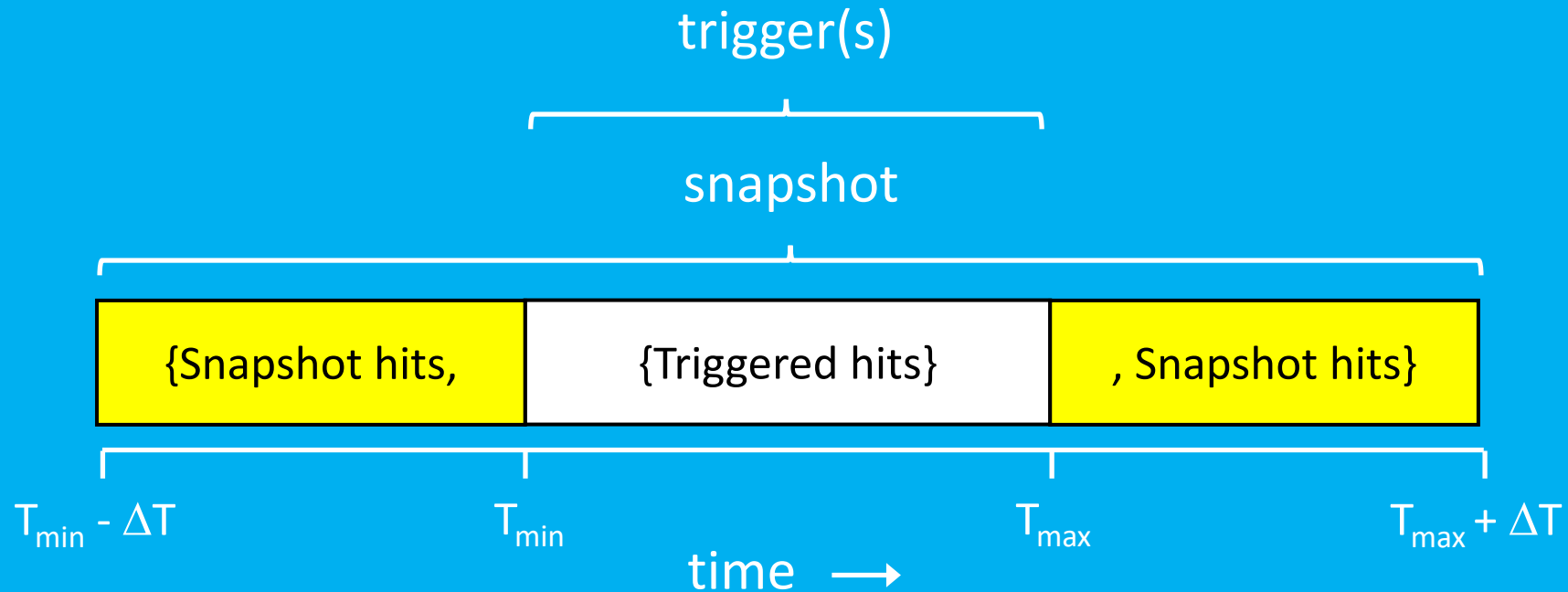
- Trigger parameters
 - configuration of real-time data filter

Data processing (3/3)

- Event
 - cluster of hits
 - normal: cluster of causally related L2 hits
 - mixed: cluster of one L2 hit with causally related L0 hits
- Note that
 - different triggers can be applied to the same data → trigger mask
 - same event can be triggered multiple times → number of overlays
 - cluster algorithm is known in literature as “*clique*” → also useful in analysis
 - you can trigger on anything (incl. external signals) → augment science scope

Event
=
Minimal set of causally related hits
a.k.a. triggered hits

Event data



snapshot[¶] = All raw data between $[T_{\min} - \Delta T, T_{\max} + \Delta T]$

[¶] $\Delta T = nD/c$ (where D corresponds to size of detector)

Reconstruction (1a/3)

Arrival time[¶]

$$t_j \cong t_0 + c \left(\Delta z + \frac{R}{\tan \theta_C} \right) \quad \text{muon}$$
$$t_j \cong t_0 + c(nD) \quad \text{EM-shower}$$

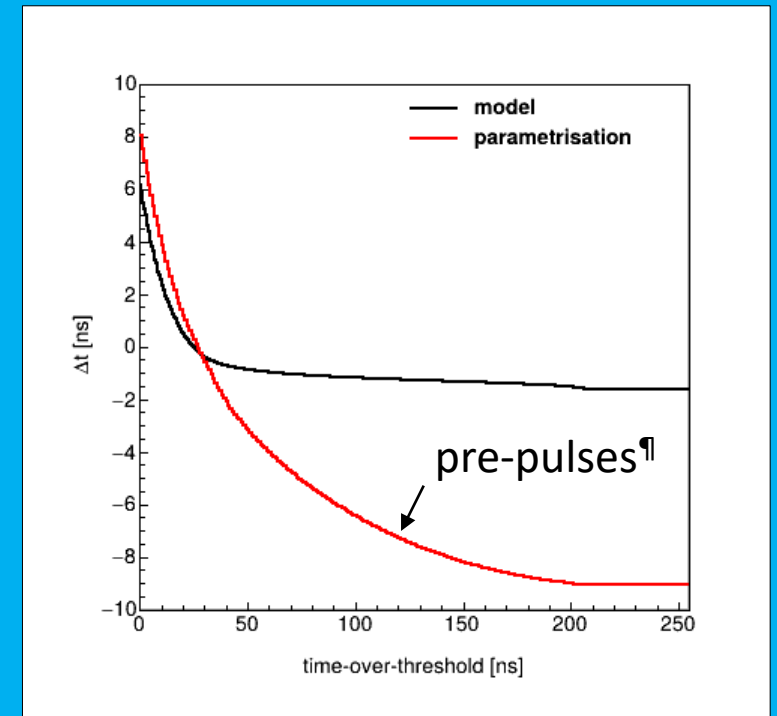
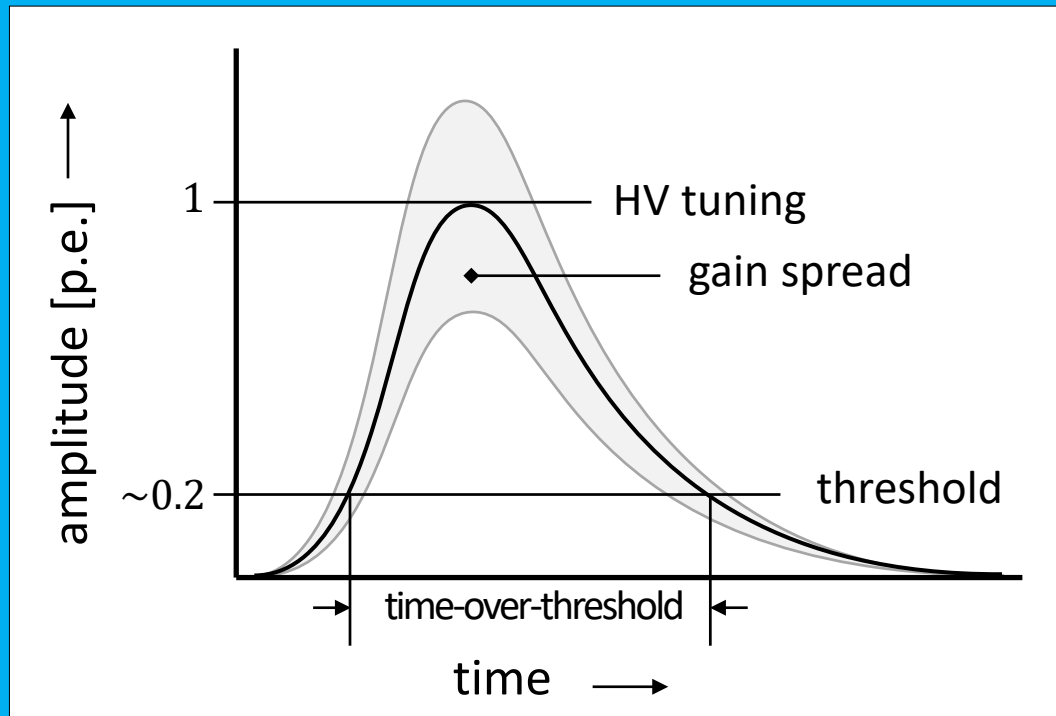
→ problem is non-linear

- ✓ in absence of light scattering, problem can partially be linearized when pairs of hits are considered (e.g. pairs of L1-hits)
 - (x_0, y_0, t_0) of muon in a given direction (see [documentation](#))
 - (x_0, y_0, z_0, t_0) of EM-shower (see [documentation](#))

[¶] Arrival time $\equiv$ shortest optical path.

Reconstruction (1b/3)

PMT analogue pulse



[¶] See slide 11.

Reconstruction (2/3)

1. calibration

- DAQ hit → calibrated time (and time-over-threshold)
- module identifier and PMT → PMT position and orientation

2. determination of start values of model parameters (a.k.a. prefit)

- linear fit(s) of (simplified) model to biased selection of data

3. determination of intermediate values of model parameters

- M-estimator fit of (simplified) model to biased selection of data

4. determination of final values of model parameters

- maximum likelihood fit using PDF of model to unbiased selection of data[¶]

[¶] Selection of hits should be unbiased with respect to PDF.

Reconstruction (3/3)

- Model parameters
 - orthogonalisation (following rotation of primary axis to z-axis)
 - muon trajectory $(x_0, y_0, t_0, T_x, T_y[, E [, B_y]])$ → next slides
 - shower $(x_0, y_0, z_0, t_0, T_x, T_y[, E [, B_y]])$ → Víctor; J. Seneca, T. van Eden
- PDF
 - contains as-much-as-possible knowledge of the detector response to particles
 - Cherenkov light production
 - light absorption, scattering and dispersion
 - PMT QE, angular acceptance and TTS
 - electronics (discriminator, TDC, etc.)
 - background rates, high-rate veto, etc.

Start value problem

$$5D = 3D \otimes 2D$$

position-time

direction



linear fit $(\mathbf{x}_0, \mathbf{y}_0, \mathbf{t}_0)$

scan (θ, φ)

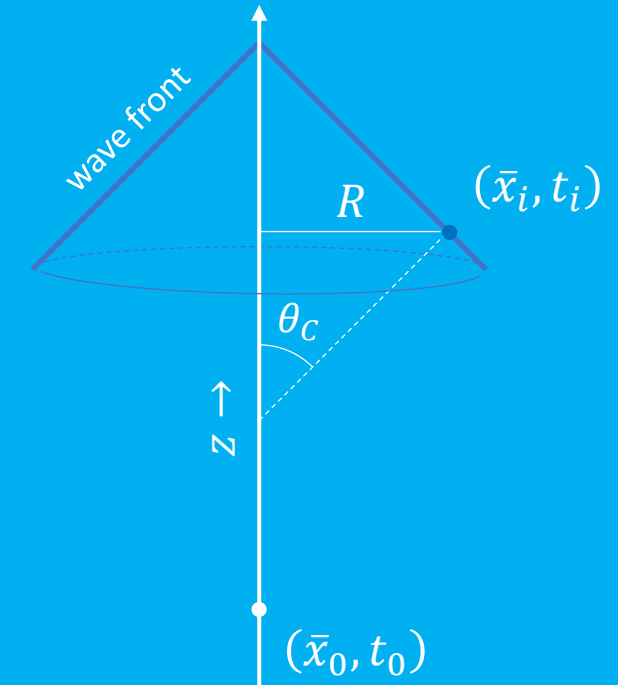
$$\bar{t}_j^2 - \bar{t}_i^2 - 2(\bar{t}_j - \bar{t}_i) \bar{t}_0 =$$

$$x_j^2 - x_i^2 - (x_j - x_i) x_0 +$$

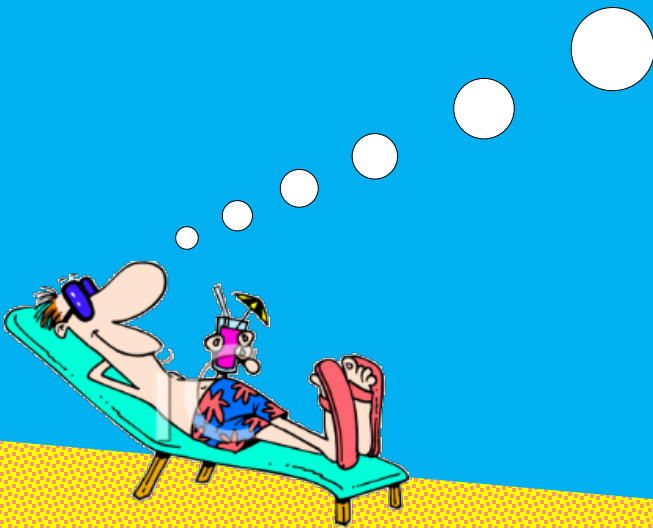
$$y_j^2 - y_i^2 - (y_j - y_i) y_0$$

$$\bar{t}_i \equiv \frac{ct_i}{\tan \theta_c} - \frac{z_i}{\tan \theta_c}$$

$$\bar{t}_0 \equiv \frac{ct_0}{\tan \theta_c}$$



$$ct_i \cong ct_0 + \Delta z + R \tan \theta_c$$



Linear fit (1a/4)

$$\underset{(n \times 1)}{y} = \underset{(n \times k)}{H} \underset{(k \times 1)}{\theta}$$

Linear fit (1b/4)

$$\hat{\theta} = (H^T V^{-1} H)^{-1} H^T V^{-1} y$$

$(k \times 1)$ $(k \times n)$ $(n \times n)$ $(n \times k)$ $(k \times n)$ $(n \times n)$ $(n \times 1)$

$$V = \begin{pmatrix} \sigma_1^2 & \cdots & 0 \\ \vdots & \ddots & \vdots \\ 0 & \cdots & \sigma_n^2 \end{pmatrix} \iff V_{ij} += \delta \alpha^2 \frac{\partial y_i}{\partial \alpha} \frac{\partial y_j}{\partial \alpha}$$

Linear fit (2/4)

```
JOmega3D omega (parameters.gridAngle_deg * JMATH::PI/180.0);

for (JOmega3D_t::const_iterator dir = omega.begin(); dir != omega.end(); ++dir) {

    const JRotation3D R(*dir);

    for (buffer_type::iterator i = data.begin(); i != data.end(); ++i) {
        i->rotate(R);
    }

    buffer_type::iterator __end = clusterizeWeight(data.begin(), data.end(), match1D);

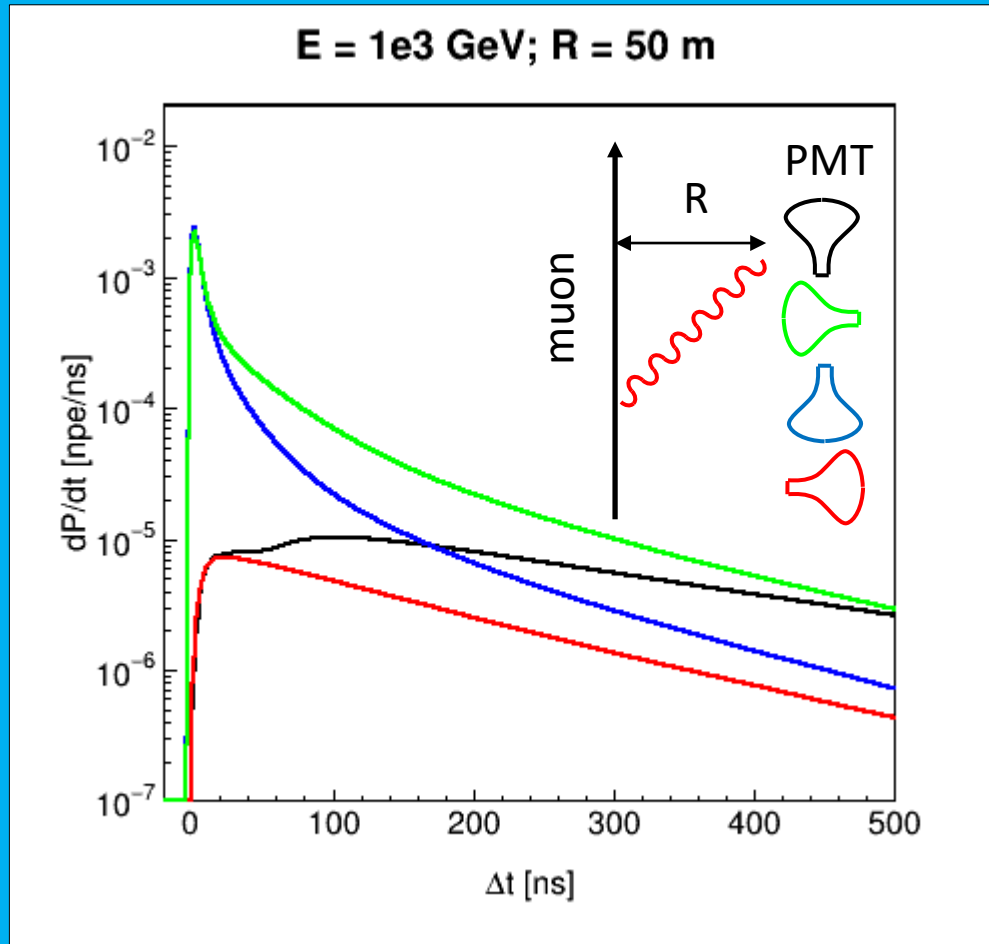
    ...
}
```

Linear fit (3/4)

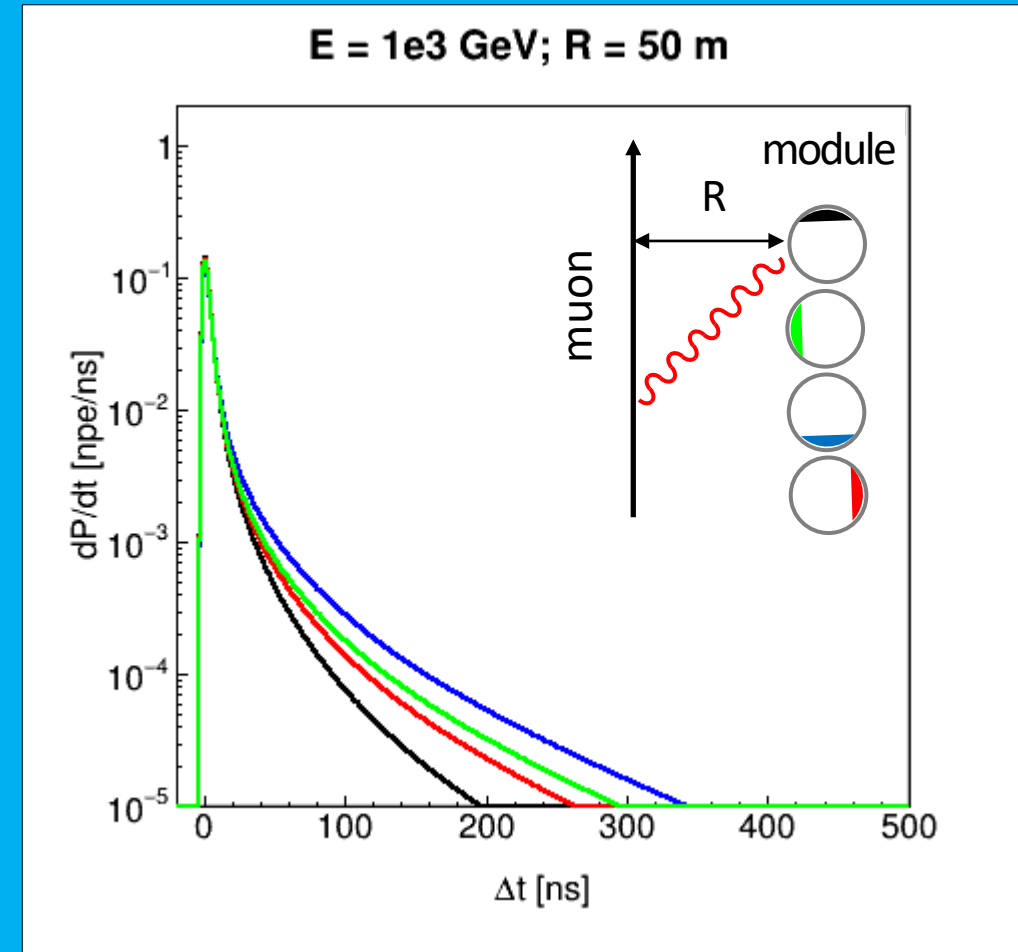
```
JMatrixNZ V;  
JVectorNZ Y;  
  
for (JOmega3D_t::const_iterator dir = omega.begin(); dir != omega.end(); ++dir) {  
  
    ...  
  
    JEstimator<JLine1Z> tz(data.begin(), __end);  
  
    V.set(tz, data.begin(), __end, gridAngle_deg, sigma_ns);  
    Y.set(tz, data.begin(), __end);  
  
    V.invert();  
  
    double y = getChi2(Y, V);  
  
    ...  
}
```

Linear fit (4a/4)

L0

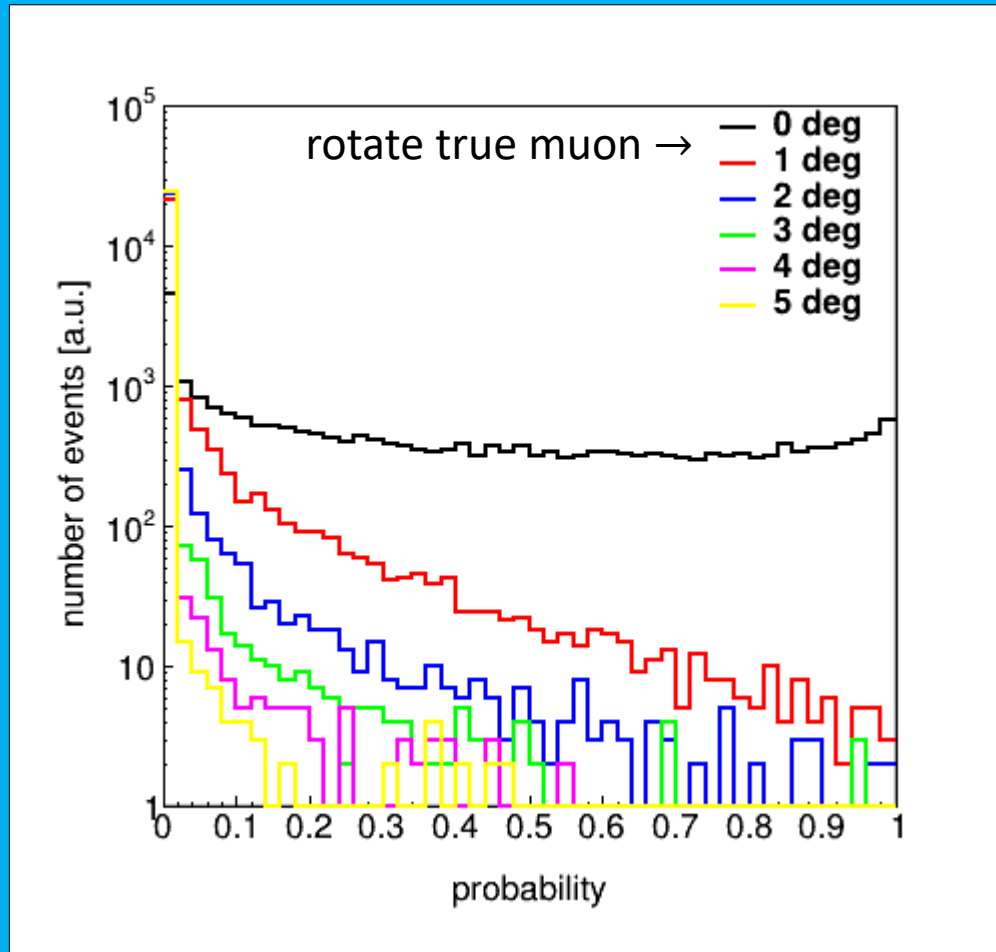


L1

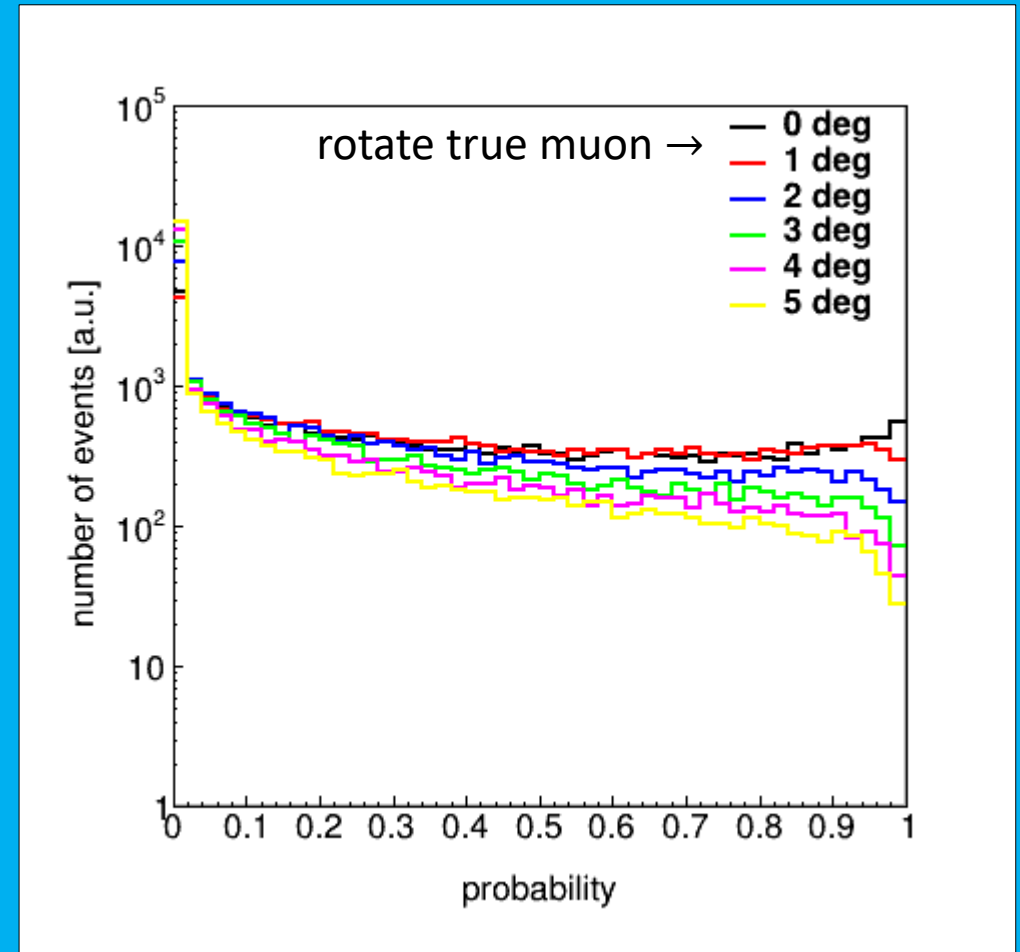


Linear fit (4b/4)

w/o co-variances



with co-variances



Final fit (1/3)

```
for (JEvt::const_iterator track = in.begin(); track != in.end(); ++track) {  
  
    const JRotation3D  R (getDirection (*track));  
    const JLine1Z      tz(getPosition  (*track).rotate(R), track->getT());  
  
    const JModel<JLine1Z> match(tz, roadWidth_m, JRegressor_t::T_ns, Z_m);  
  
    for (buffer_type::const_iterator i = data.begin(); i != data.end(); ++i) {  
  
        JHitWO hit(*i, summary.getRate(i->getPMTIdentifier()));  
  
        hit.rotate(R);  
  
        if (match(hit)) {  
            buffer.push_back(hit);  
        }  
    }  
    ...  
}
```

Final fit (2/3)

```
JRegressor<JLine3Z, JGandalf> regressor(pdf_file, parameters.TTS_ns);

for (JEvt::const_iterator track = in.begin(); track != in.end(); ++track) {

    ...

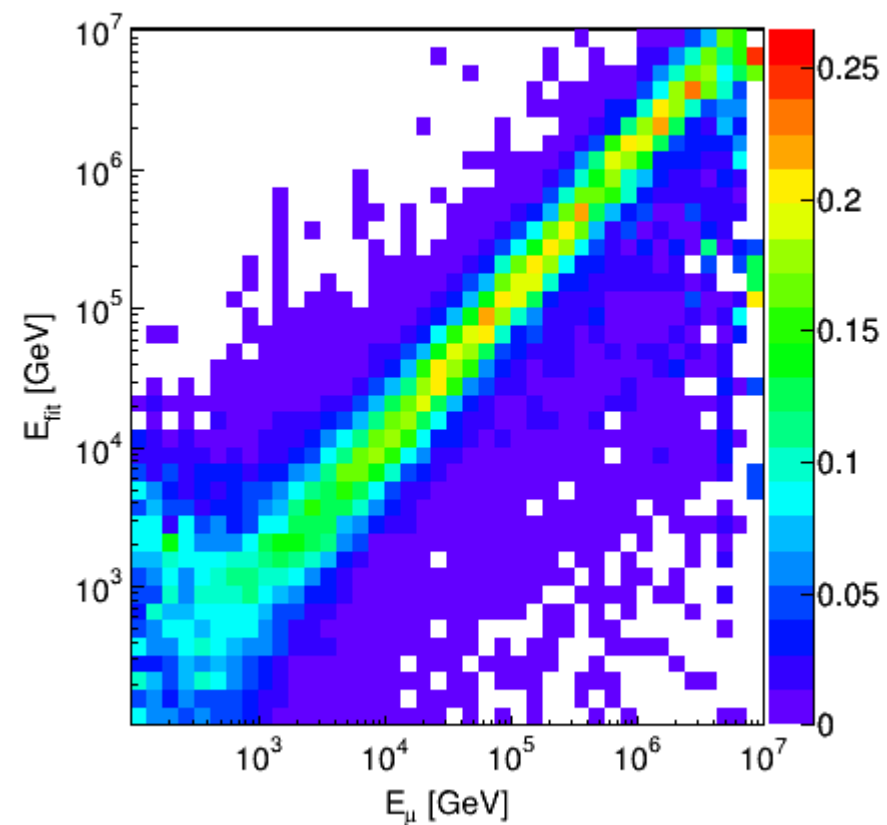
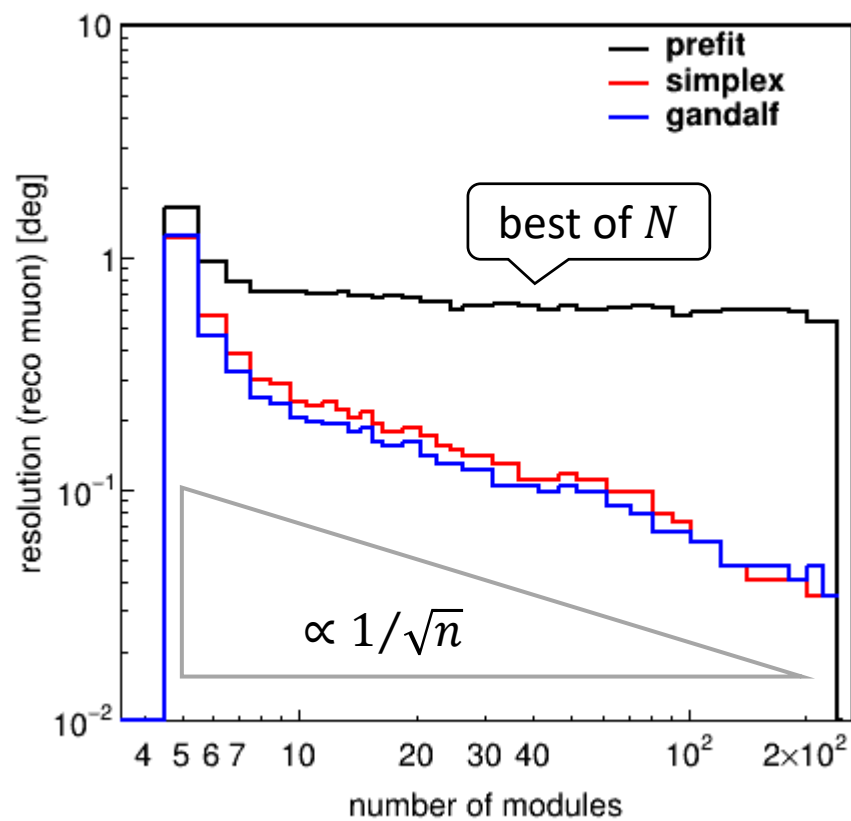
    double chi2 = regressor(tz, buffer.begin(), buffer.end());

    JTrack3D tb(regressor.value);

    tb.rotate_back(R);

    ...
}
```

Final fit (3/3)



Food for thoughts

- How well describes the model our data?
- T_x and T_y are orthogonal parameters ($\Omega \leq 2\pi$)
- ORCA: implement simultaneous fit of muon track + vertex shower?
- ARCA: implement explicitly stochastic energy losses of muon?
- Machine learning?