

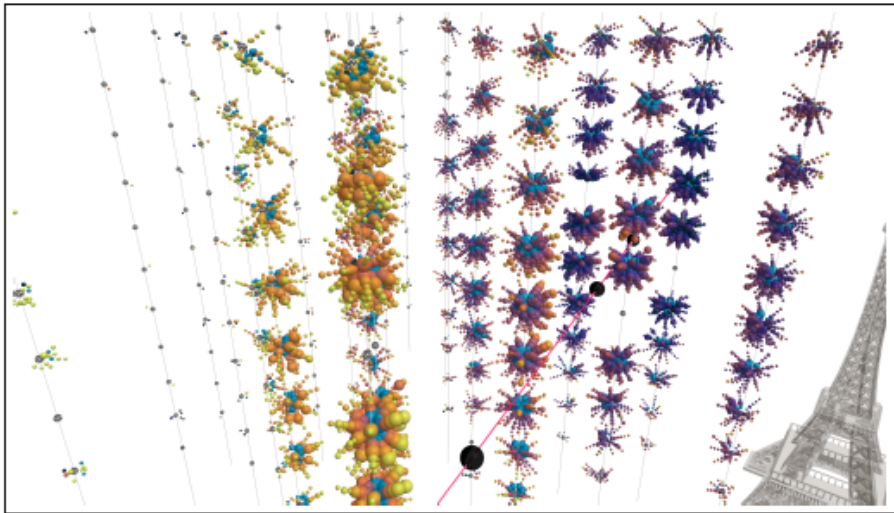
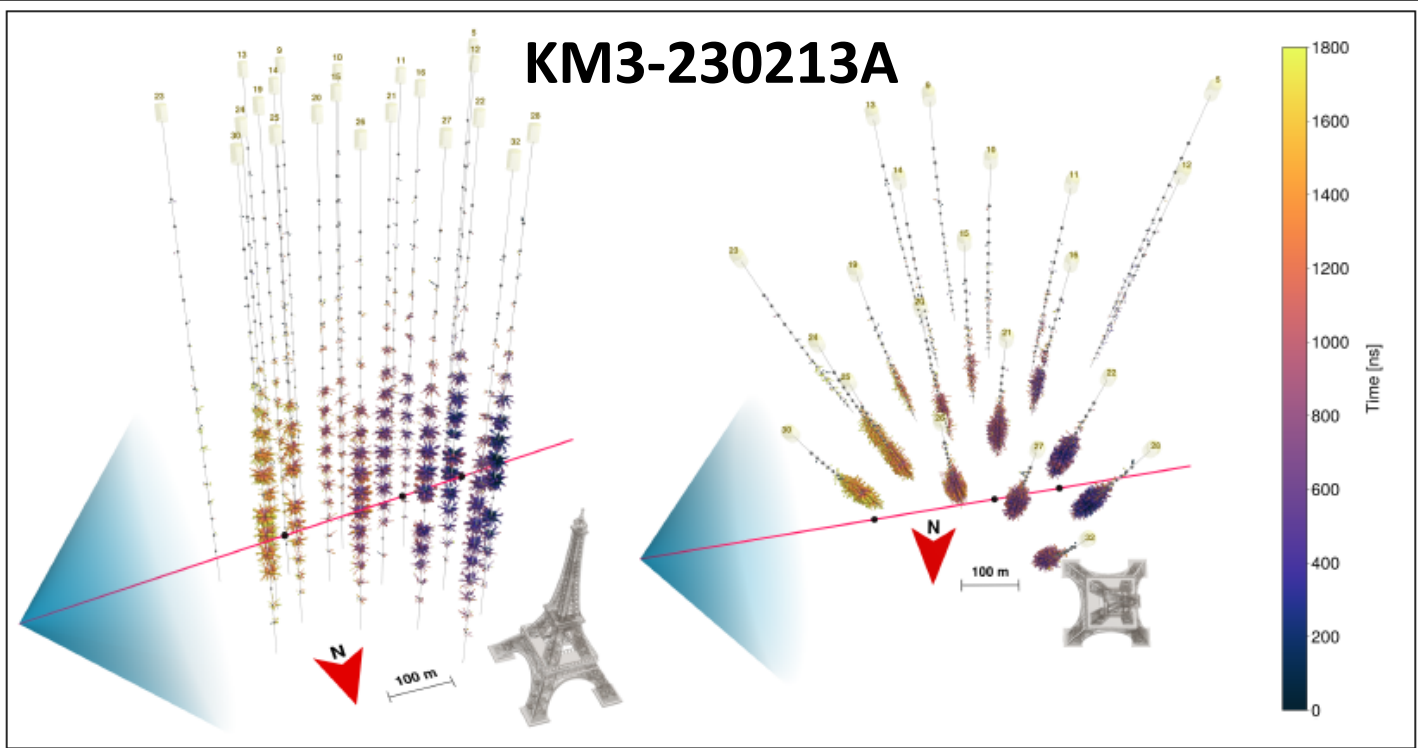
KM3-230213A

Nikhef topical lectures

Maarten de Jong (Nikhef/Leiden University)

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<https://www.nytimes.com/2025/02/12/science/astrophysics-universe-neutrinos.html>

<https://www.washingtonpost.com/science/2025/02/12/neutrino-cosmos-universe-astronomers/>

<https://www.scientificamerican.com/article/the-most-energetic-neutrino-ever-seen-makes-a-mediterranean-splash/>

<https://edition.cnn.com/2025/02/12/science/energetic-neutrino-particle-detection/index.html>

<https://www.reuters.com/science/high-energy-cosmic-neutrino-detected-under-mediterranean-sea-2025-02-12/>

<https://www.newscientist.com/article/2468121-record-breaking-neutrino-spotted-tearing-through-the-mediterranean-sea/>

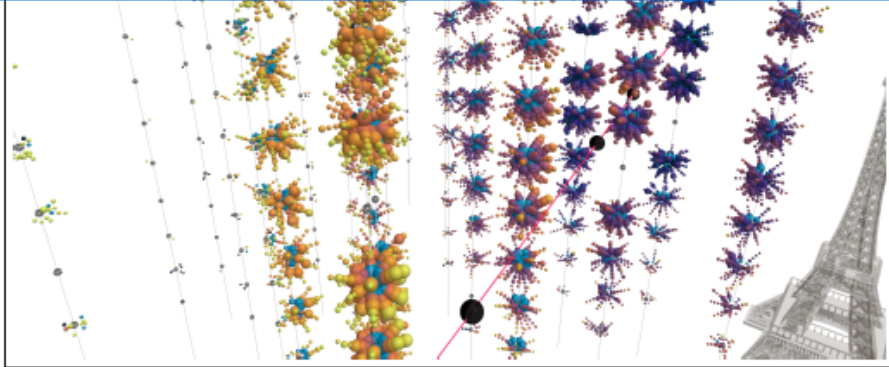
<https://physics.aps.org/articles/v18/35>

<https://abcnews.go.com/Technology/wireStory/deep-sea-neutrino-telescope-spots-energetic-ghost-particle-118738655>

<https://apnews.com/article/high-energy-neutrino-ghost-particle-c8177a5eabdca2fd045d92e872e1fb1>

<https://www.straitstimes.com/world/europe/high-energy-cosmic-neutrino-detected-under-mediterranean-sea>

<https://www.economist.com/science-and-technology/2025/02/12/a-neutrino-telescope-spots-the-signs-of-something-cataclysmic>



The international journal of science / 13 February 2025

nature

COSMIC CATCHER

Deep-sea telescope detects
neutrino with highest energy
ever recorded

Vol. 638 No. 8080
13 February 2025

Recap

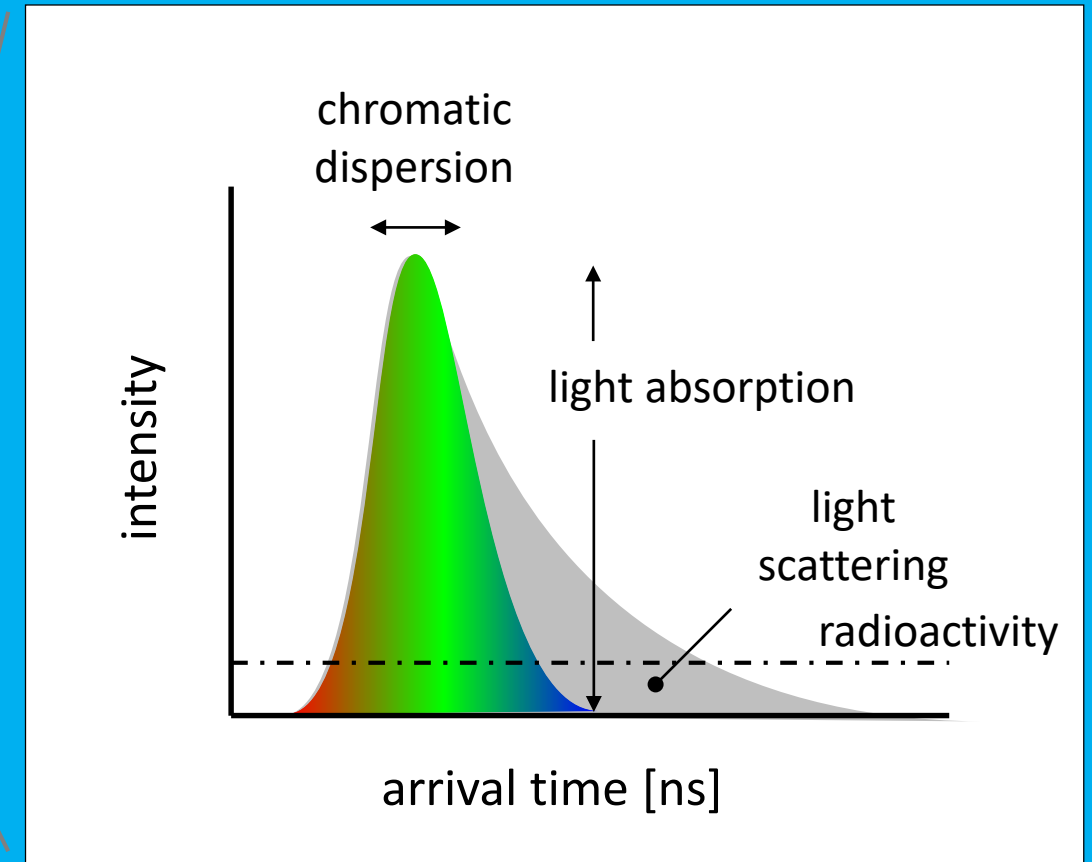
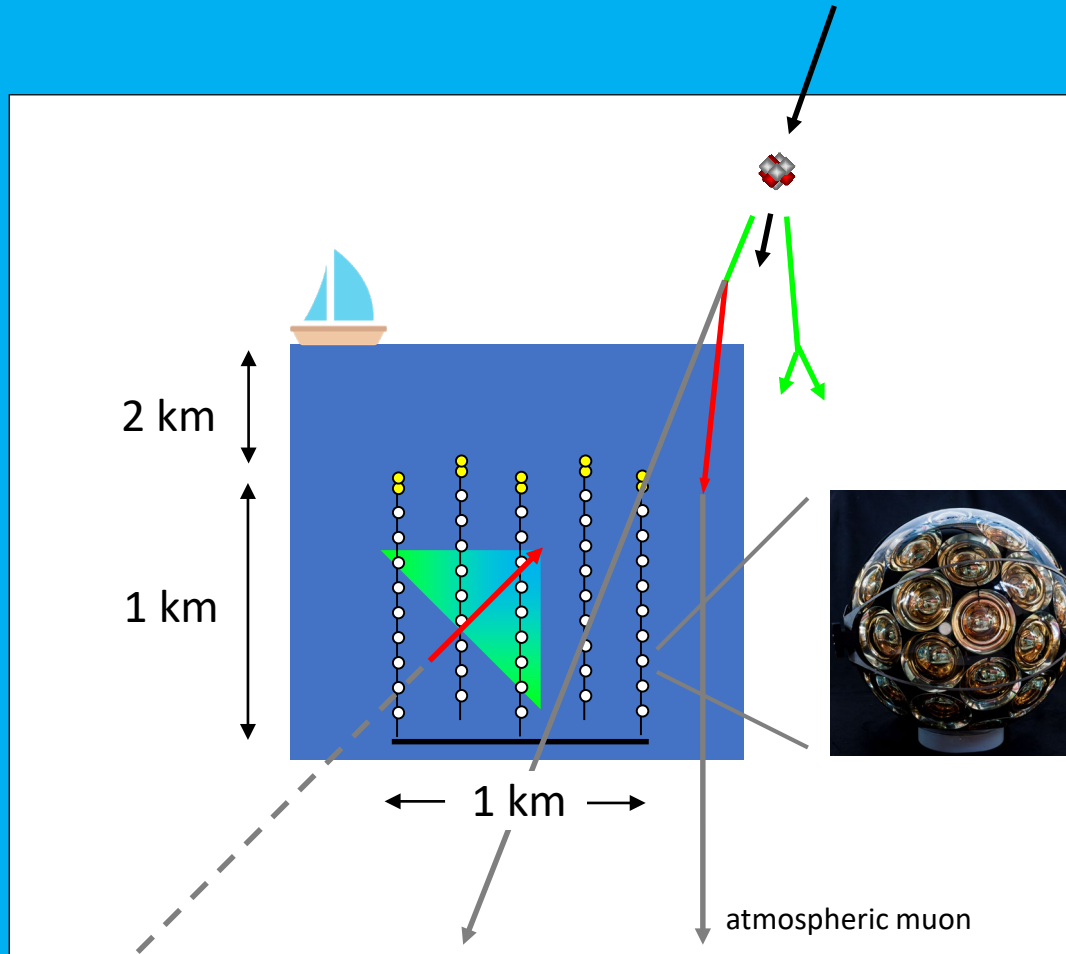
1. Precision of estimation of parameters increases with more information
2. For a given set of data (i.e. amount of information),
maximum likelihood yields smallest variance of parameters
3. If data are normally distributed and χ^2 depends linearly on parameters,
smallest χ^2 can be obtained by solving matrix equation $Ax = b$
4. Else, determination of maximum likelihood involves iterative procedure

PDF describing data

$$\nabla \chi^2 = \nabla f \times \frac{\partial \chi^2}{\partial f}$$

cosmic ray

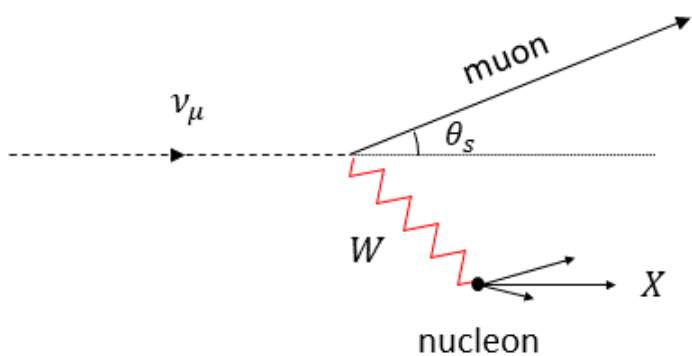
KM3NeT neutrino telescope



cosmic neutrino

“golden” channel

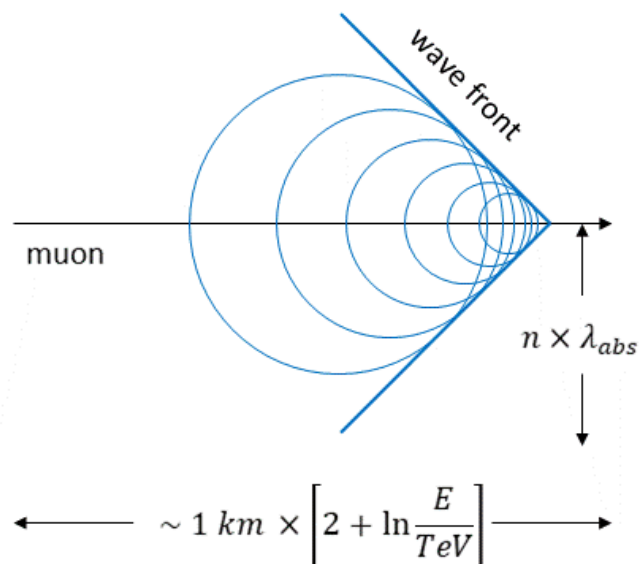
neutrino interaction



$$\theta_s \sim \delta\theta$$

+

Cherenkov light



=

1. Target mass

overcome small cross section

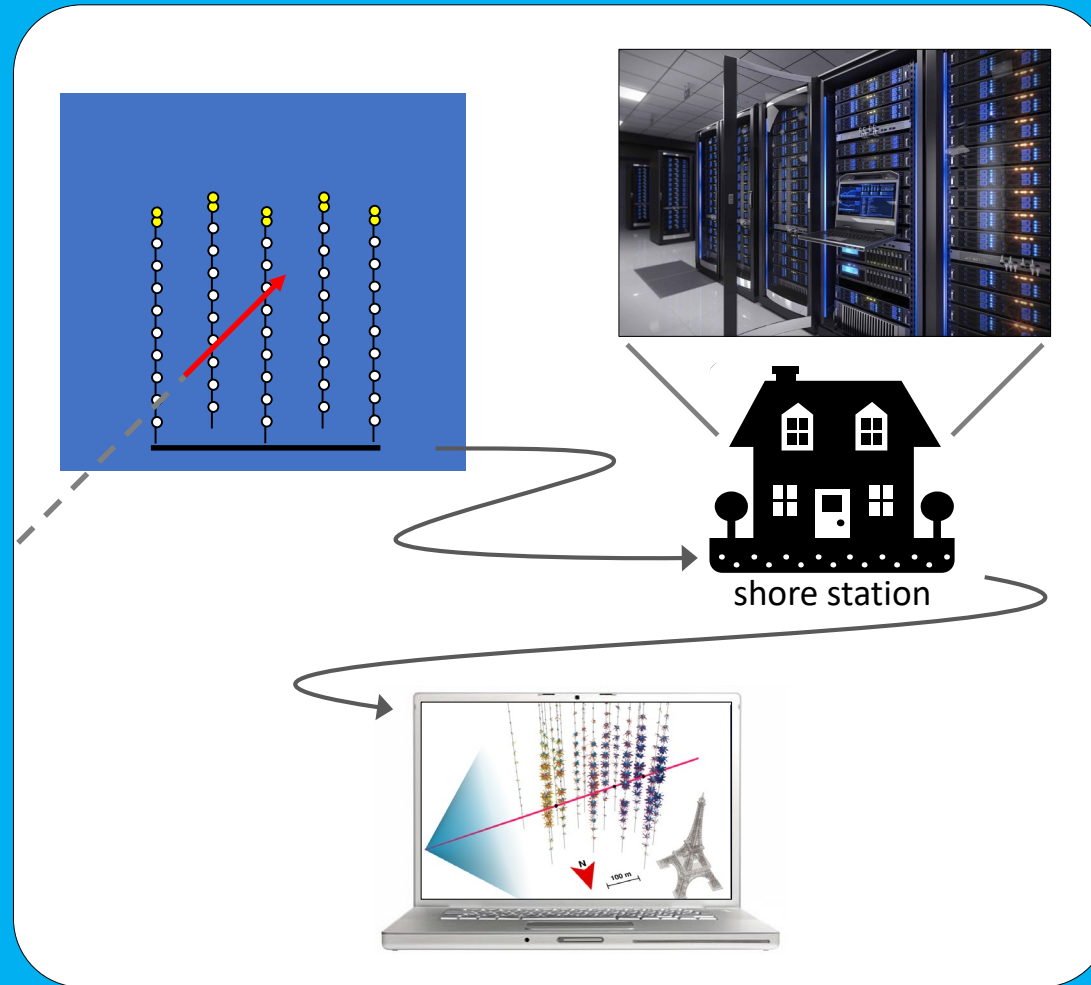
2. Transparency

sparse sensor array

3. Muon range

good angular resolution

All-data-to-shore



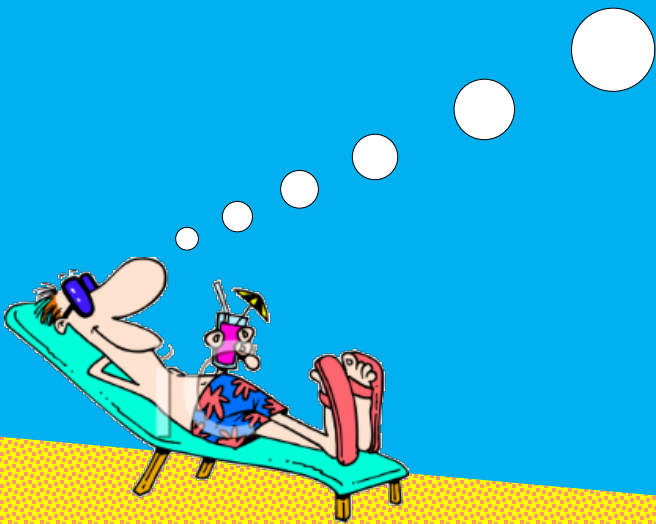
25 Gb/s



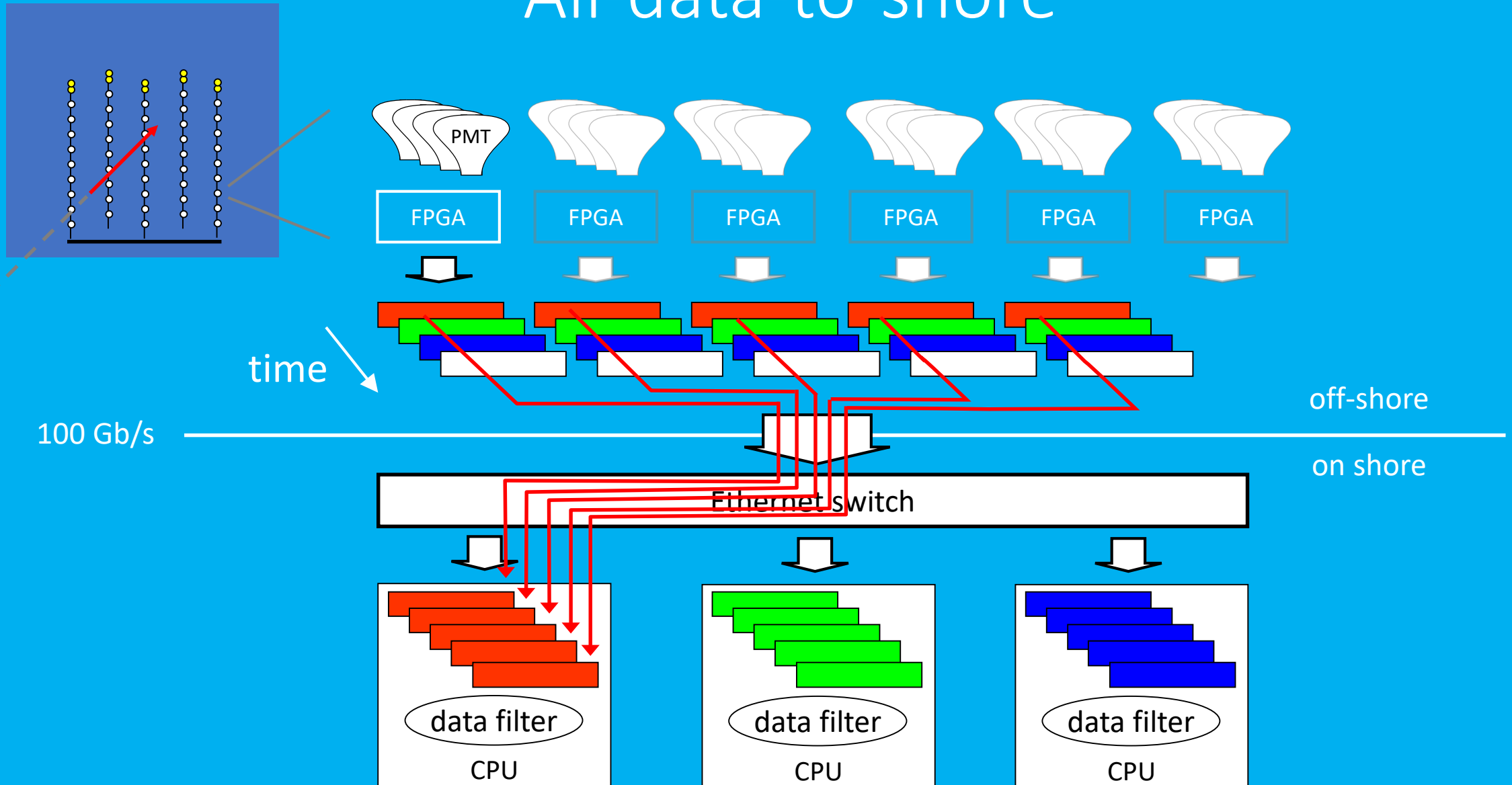
“something happens”



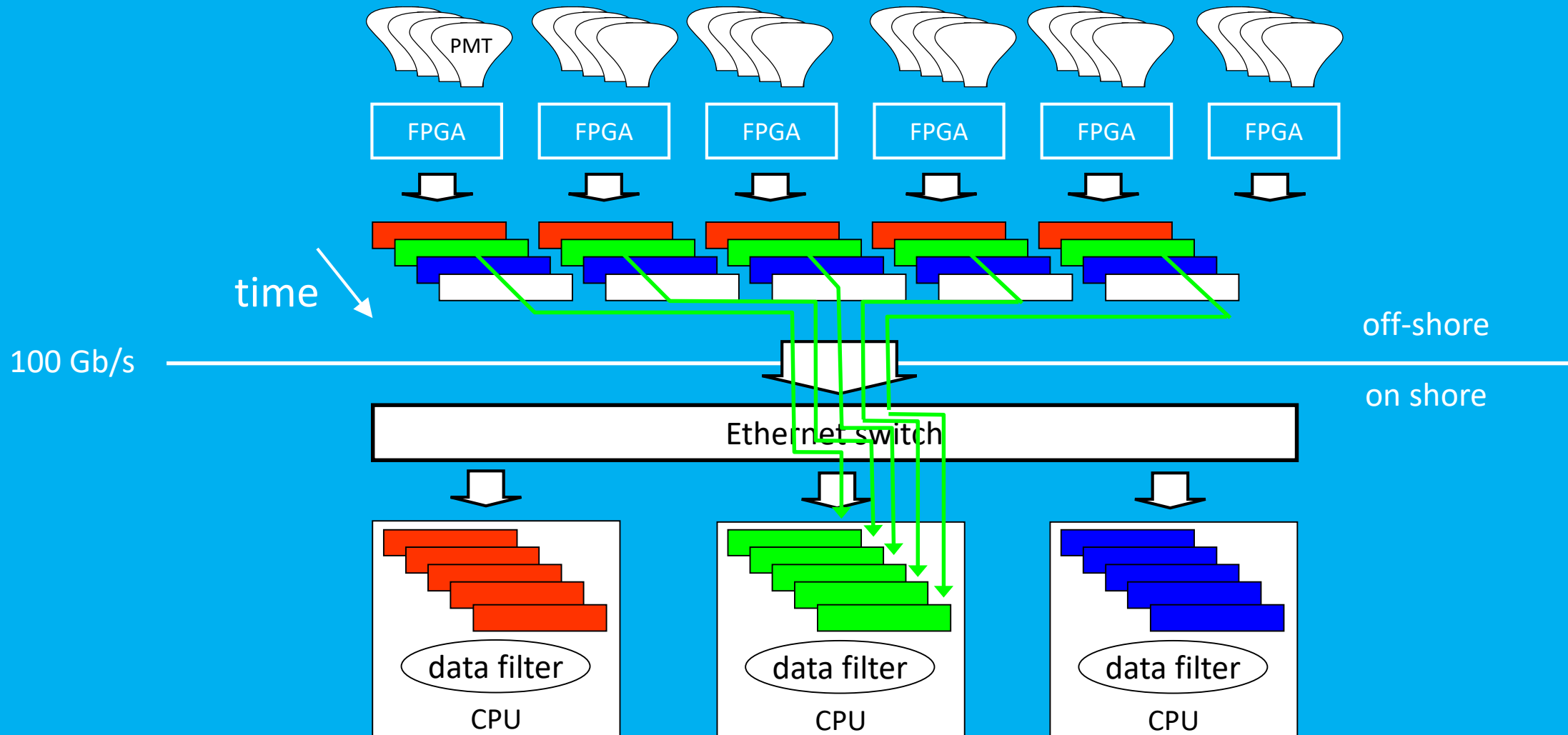
10 Mb/s



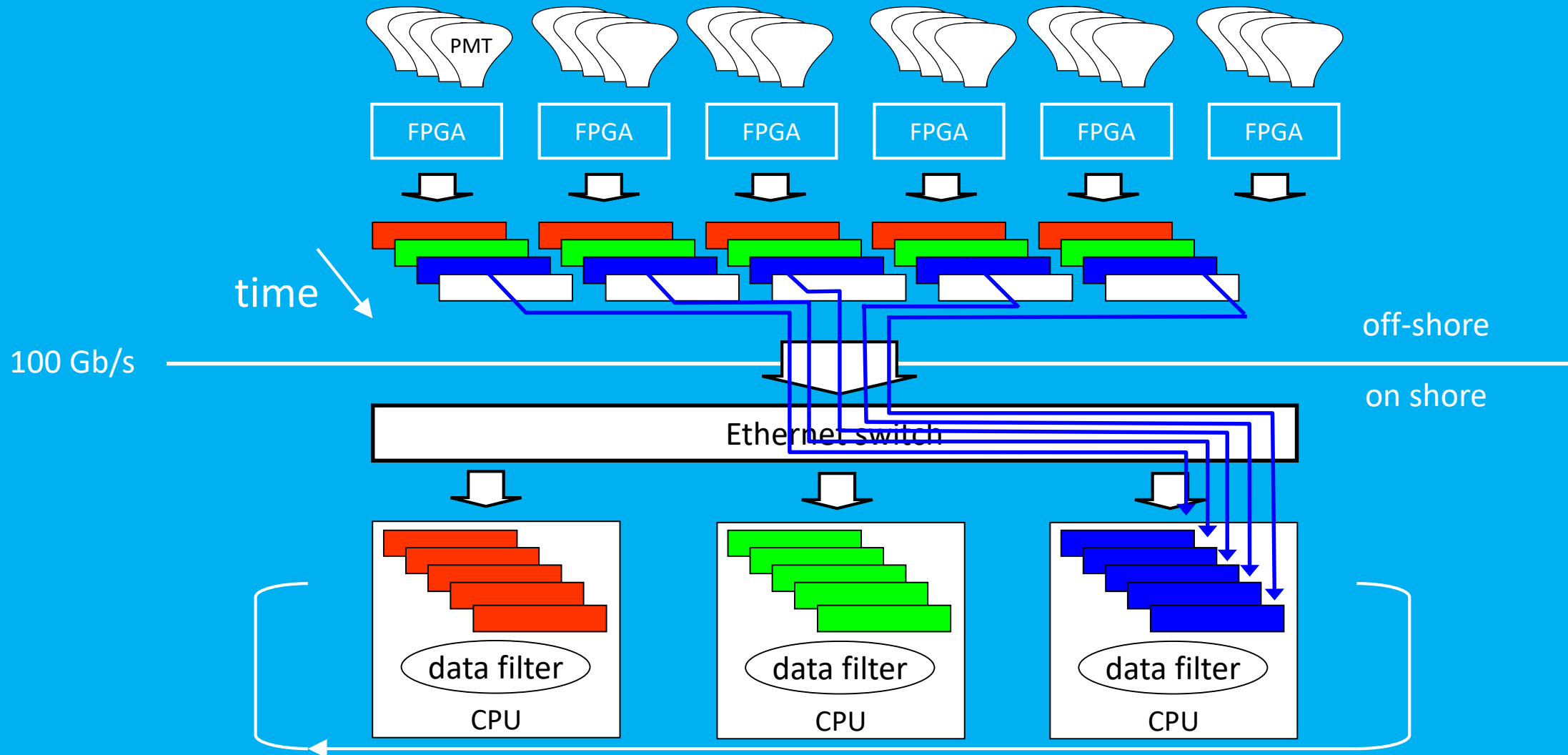
All-data-to-shore



All-data-to-shore



All-data-to-shore



Data filter

- Level 1
 - local coincidence of two (or more) L0 hits in same optical module
 - typical time window 20 ns
- Level 2
 - subset of L1 hits with additional criteria
 - typical opening angle between PMTs $\leq 90\text{ deg.}$
 - typical time window 15 ns
- Level 3
 - minimal subset of L2 hits that are causally related
 - typical minimal number of L2 hits is 5 (= 10 photo-electrons)
 - write “snapshot” to disk (no loss of data)

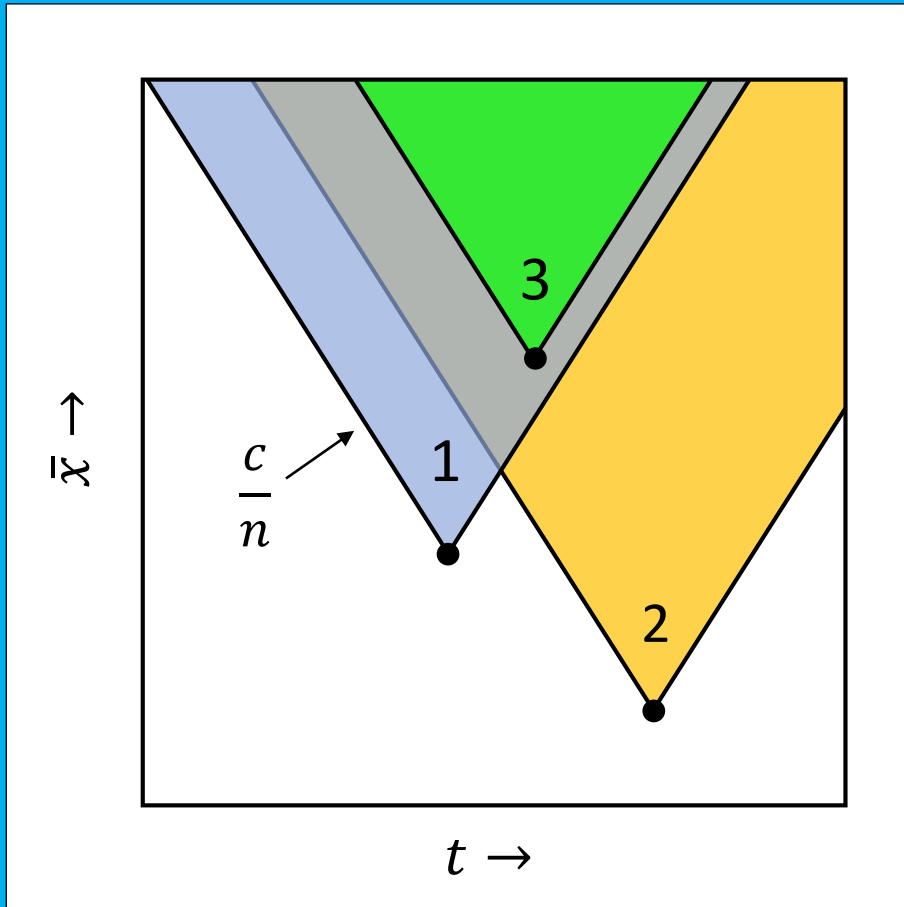


100% purity
photon counting

$$\frac{c}{n} |\Delta t| \leq |\Delta \vec{x}|$$

causality

Causality



- hit (1,3) and (2,3) are causally related
- hit (1,2) are not causally related ☹️



$n!$ problem



“clique” algorithm (n^2)

number of modules

L2 rate

time window

$$R(m) \simeq \binom{N}{m} \times r \times (r\Delta T)^{m-1}$$

number of coincidences

$$\simeq \frac{N^m}{m!} \times r \times (r\Delta T)^{m-1}$$

$$= \frac{1}{m!} \times (Nr) \times (Nr\Delta T)^{m-1}$$

total rate

probability of coincidence



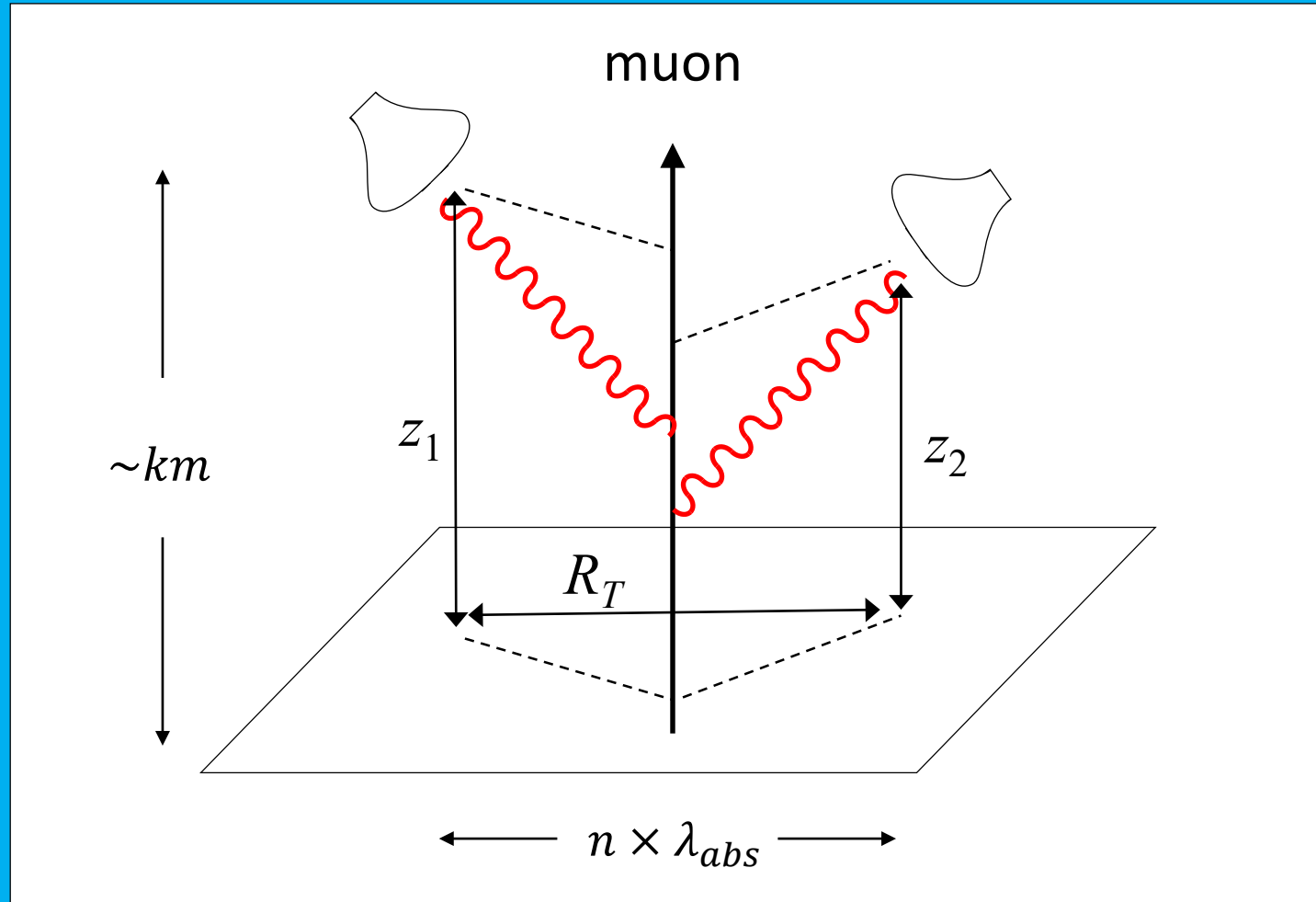
$$N \cong 2000$$

$$r \cong 1 \text{ kHz}$$

$$\Delta T \cong 10 \text{ } \mu\text{s}$$

$$P \gg 1$$

Beaming



Beaming

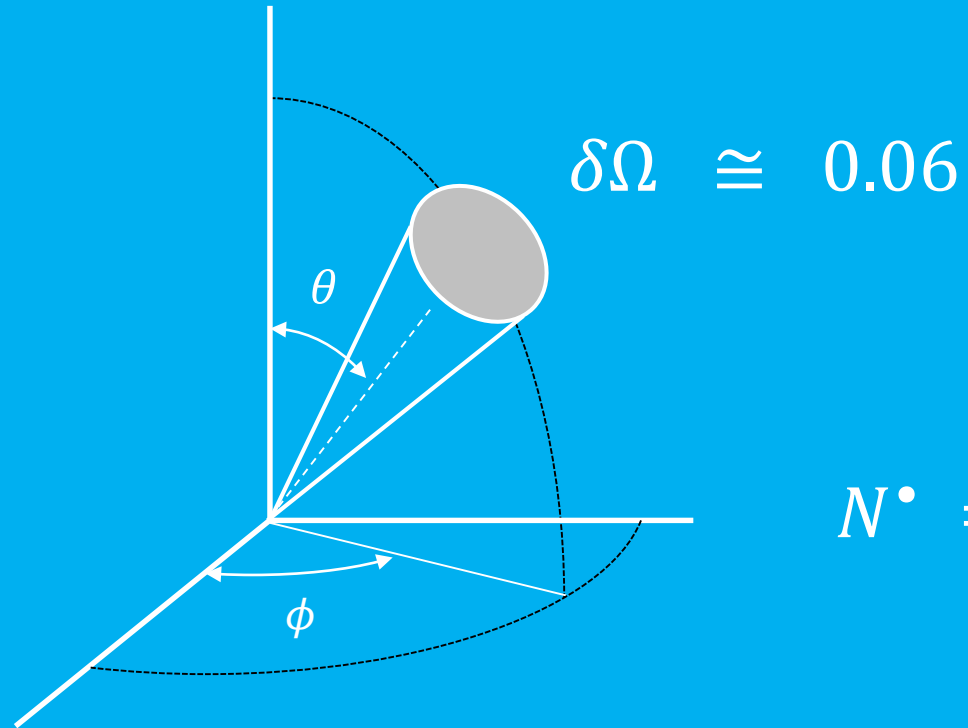
$$R(m) \simeq \frac{1}{m!} \times Nr \times (Nr\Delta T)^{m-1}$$



$$\Delta T = \frac{n}{c} D \Rightarrow \frac{1}{c} R_T \tan \theta_c$$
$$N \times \left(\frac{R_T}{D} \right)^2$$

$$R'(m) \simeq (10^{-3} - 10^{-2})^{m-1} \times R(m)$$

Full sky coverage

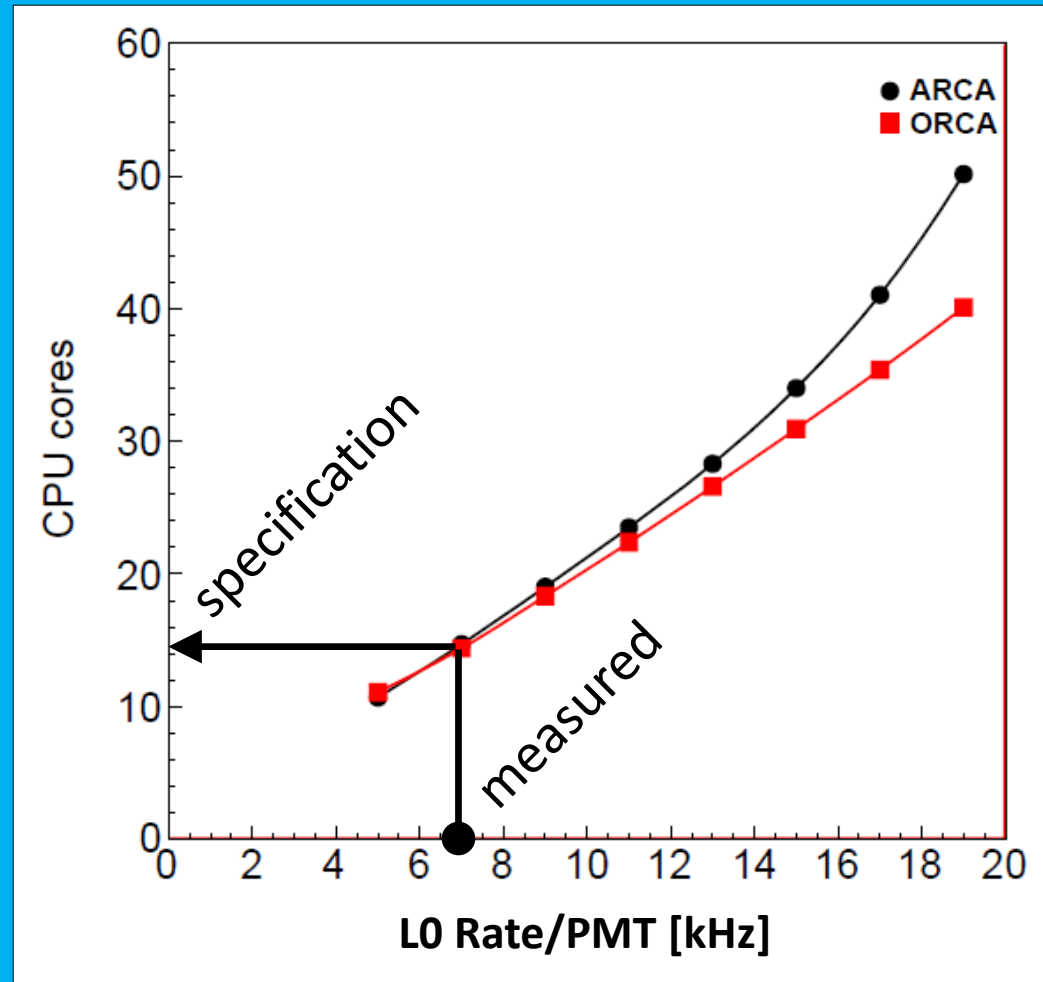


$$N^{\bullet} = \frac{4\pi}{\delta\Omega} \simeq 200$$

$$R'' \simeq N^{\bullet} \times R'$$

$$\simeq N^{\bullet} \times (10^{-3} - 10^{-2})^{m-1} \times R \ll R$$

CPU usage



Start value problem

$$5D = 3D \otimes 2D$$

position-time direction



linear fit (x_0, y_0, t_0)

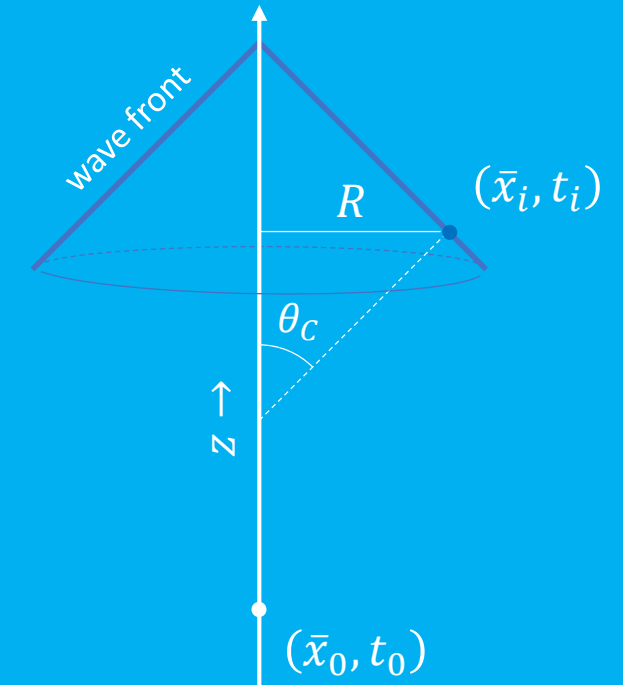


scan (θ, φ)

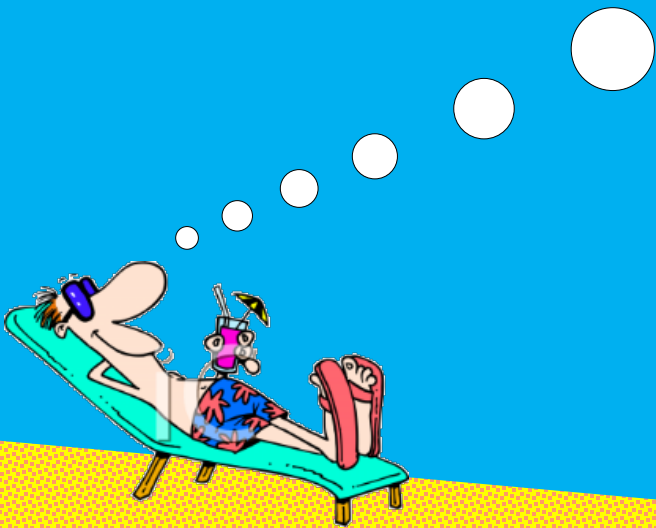
$$\begin{aligned} \bar{t}_j^2 - \bar{t}_i^2 - 2(\bar{t}_j - \bar{t}_i) \bar{t}_0 = \\ x_j^2 - x_i^2 - (x_j - x_i) x_0 + \\ y_j^2 - y_i^2 - (y_j - y_i) y_0 \end{aligned}$$

$$\bar{t}_i \equiv \frac{ct_i}{\tan \theta_c} - \frac{z_i}{\tan \theta_c}$$

$$\bar{t}_0 \equiv \frac{ct_0}{\tan \theta_c}$$



$$ct_i \cong ct_0 + \Delta z + R \tan \theta_c$$



Linear fit

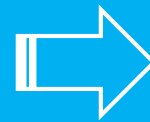
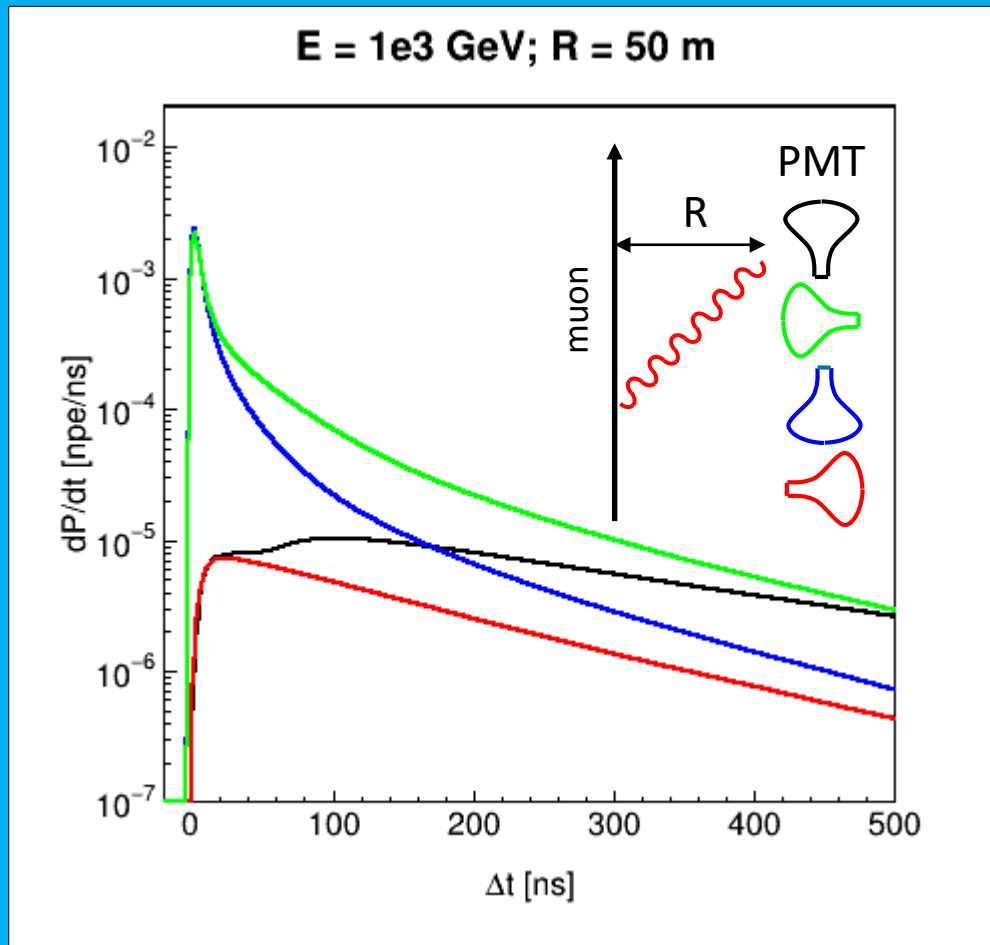
$$y = H \theta$$

$(n \times 1)$ $(n \times k)$ $(k \times 1)$

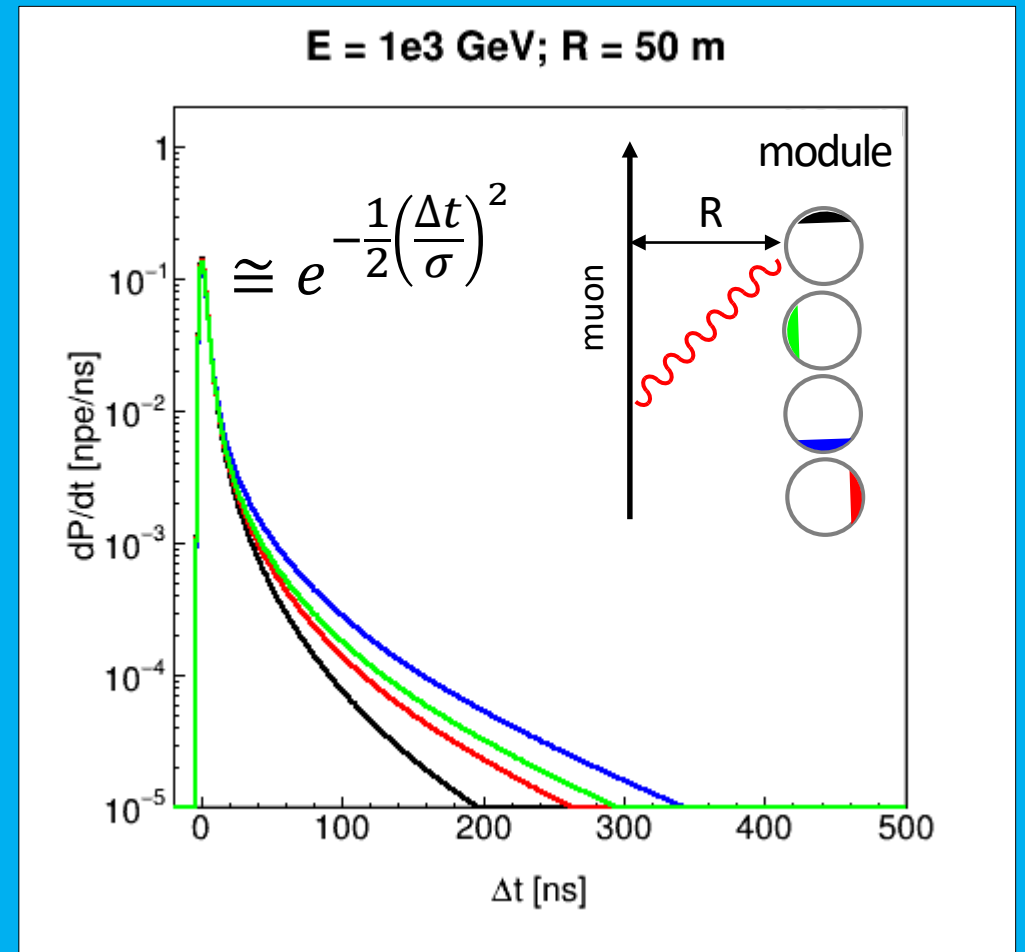
1 (0) solution

Gaussian PDF

L0



L1



Scan (θ, φ)

1° grid of directions



keep N best solutions

Which N best?

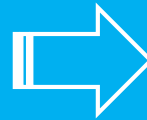
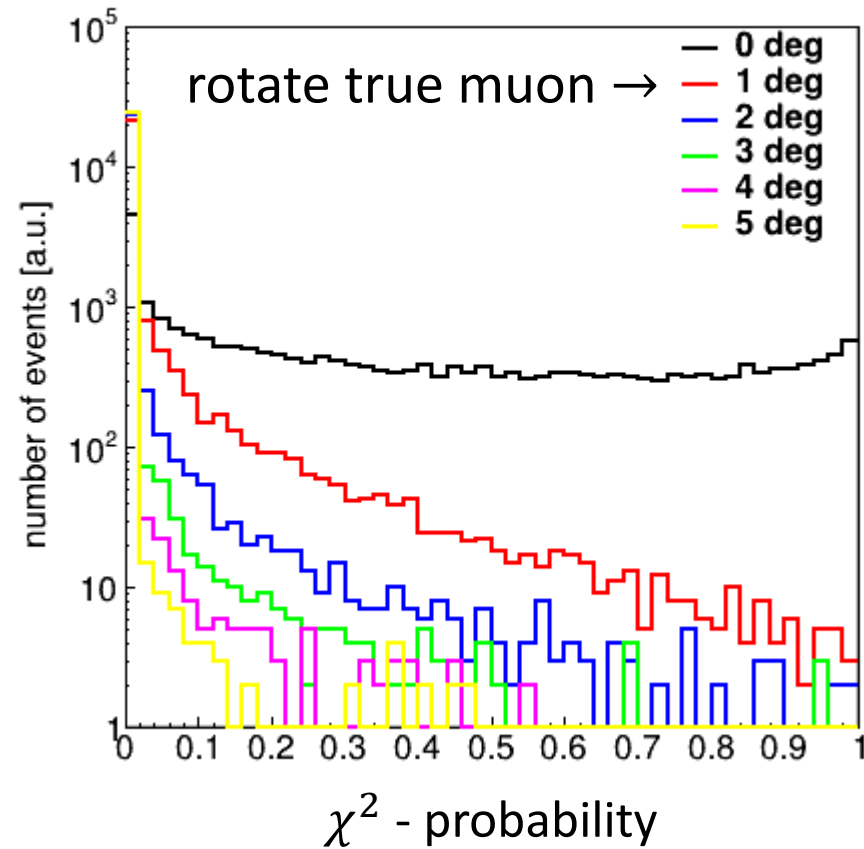
$$\hat{\theta} = (H^T V^{-1} H)^{-1} H^T V^{-1} y$$

$(k \times 1)$ $(k \times n)$ $(n \times n)$ $(n \times k)$ $(k \times n)$ $(n \times n)$ $(n \times 1)$

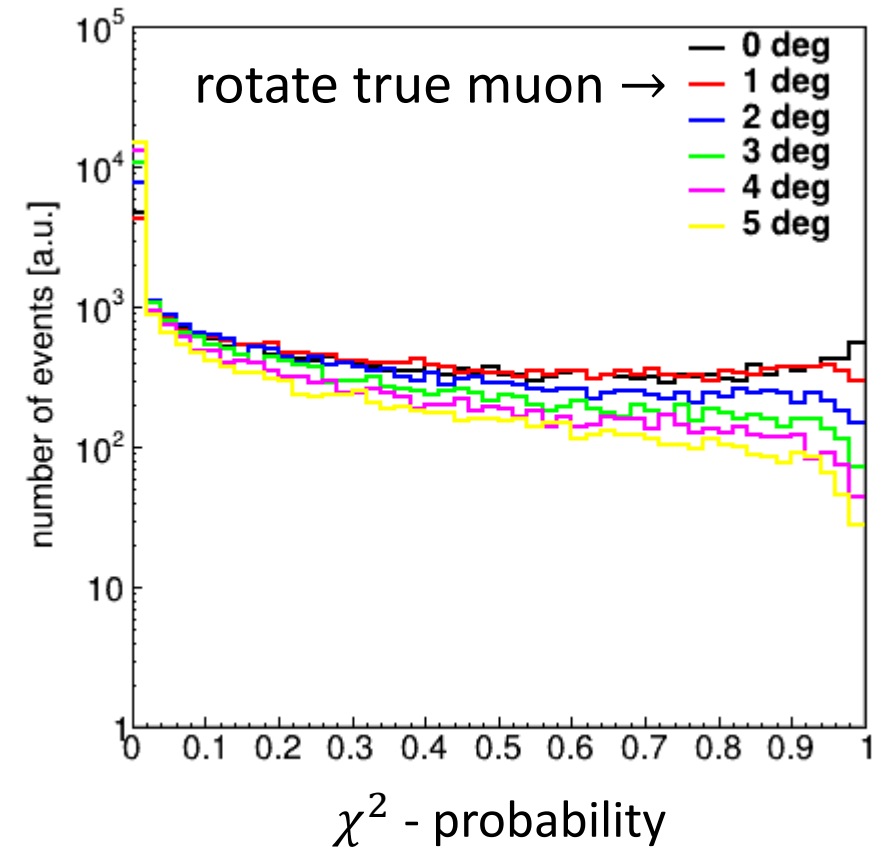
$$V = \begin{pmatrix} \sigma_1^2 & \cdots & 0 \\ \vdots & \ddots & \vdots \\ 0 & \cdots & \sigma_n^2 \end{pmatrix} \xRightarrow{\text{grid angle}} V_{ij} += \delta\alpha^2 \frac{\partial t_i}{\partial \alpha} \frac{\partial t_j}{\partial \alpha}$$

Which N best?

w/o co-variances

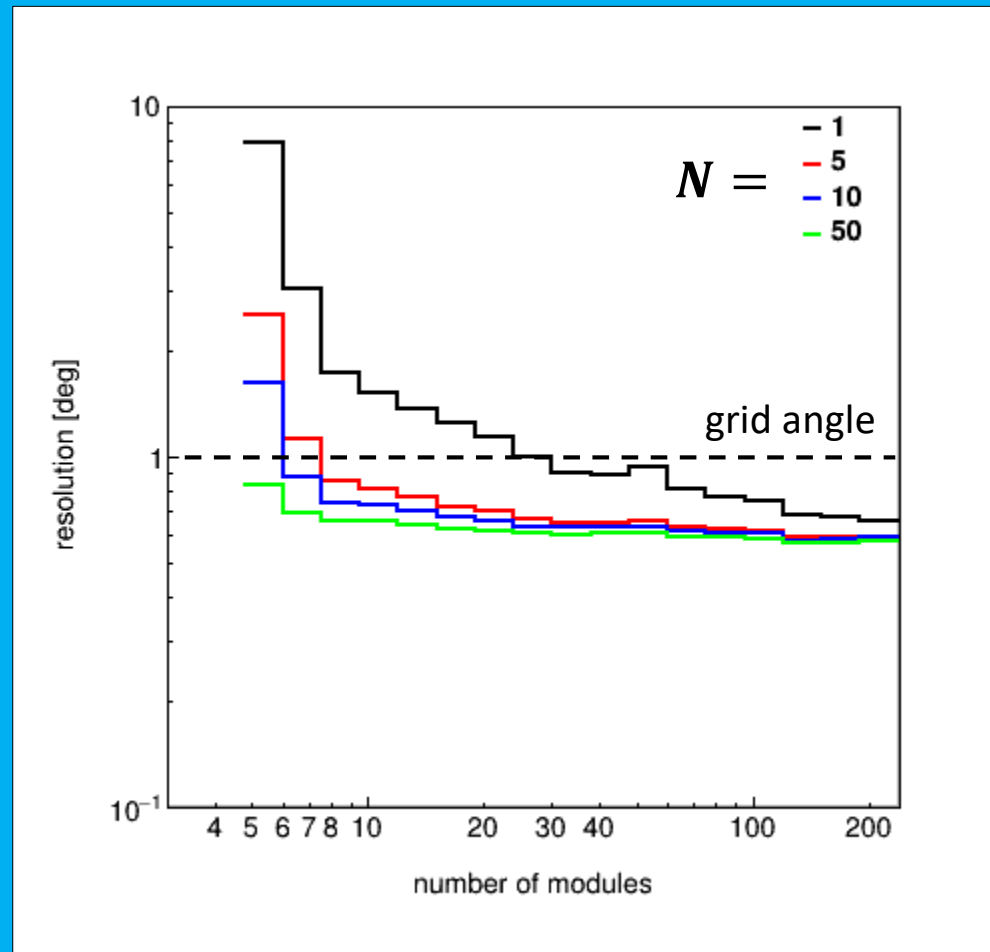


with co-variances



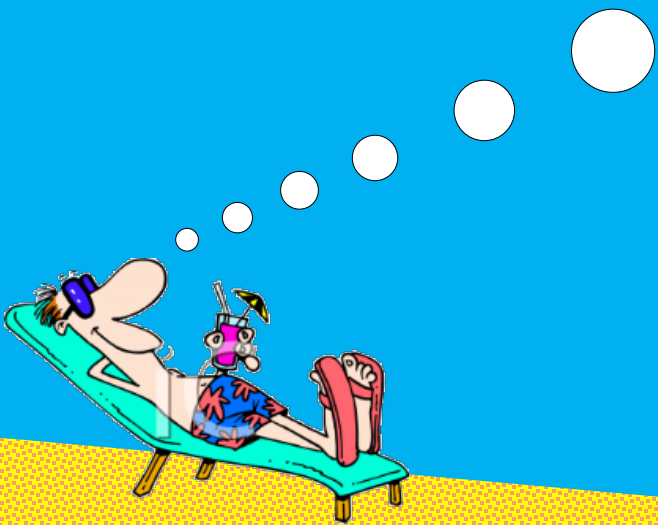
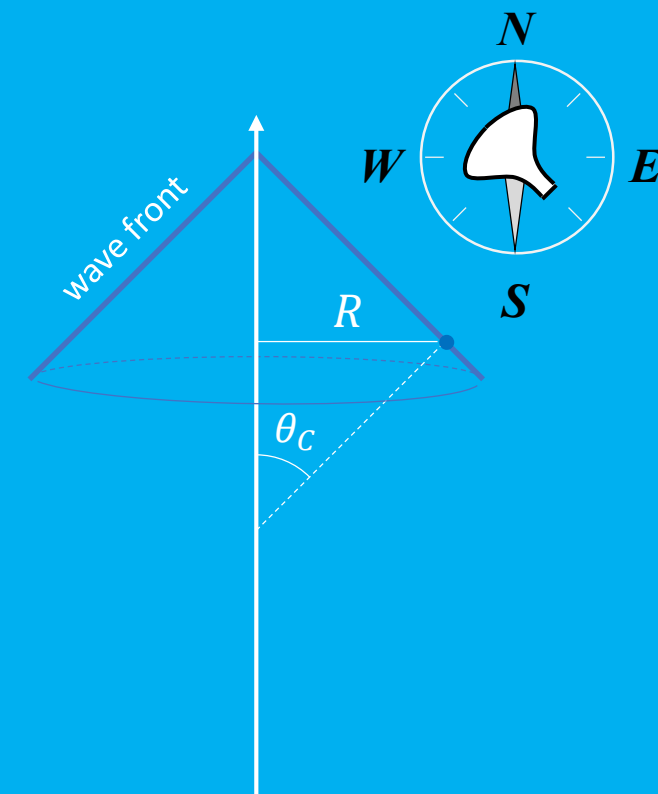
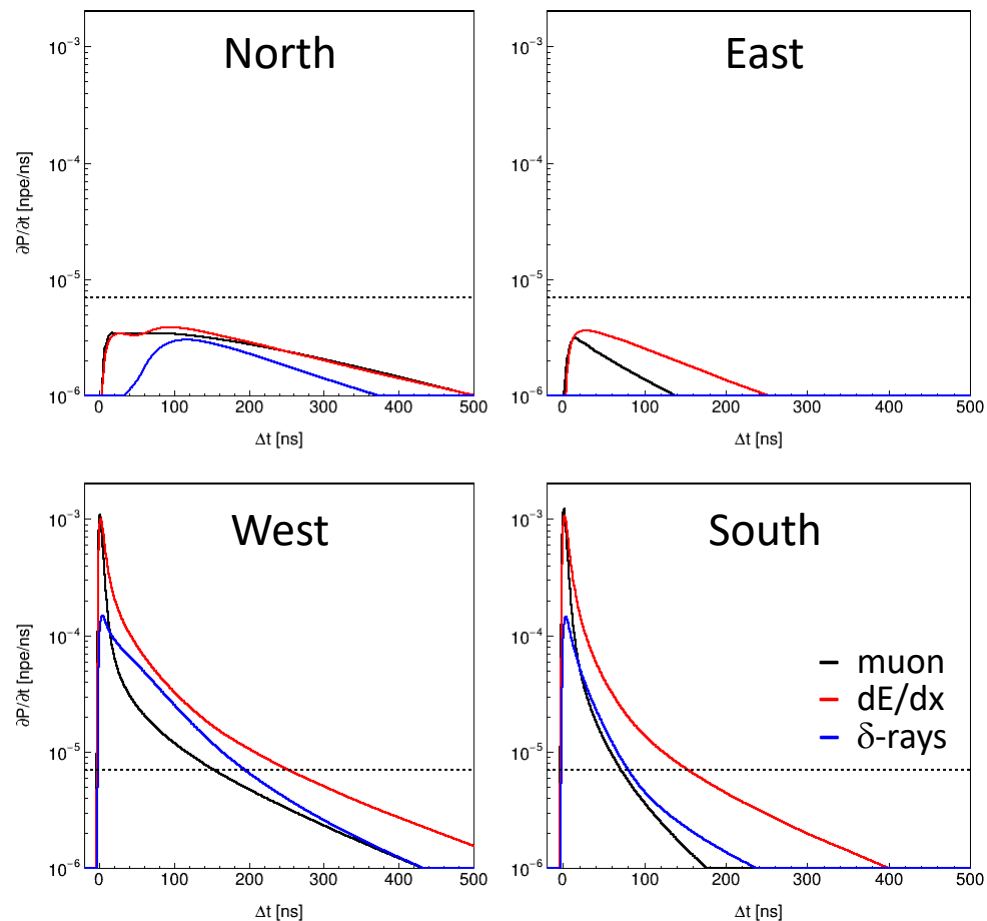
Which N best?

$$Q \equiv n - 0.25 \frac{\chi^2}{\text{NDF}} \Rightarrow$$



$\Rightarrow \checkmark N = 50$

PDF of Cherenkov light



PDF of Cherenkov light

- PDF can be calculated from first principles when [effective] scattering length is much larger than absorption length (see [documentation](#))

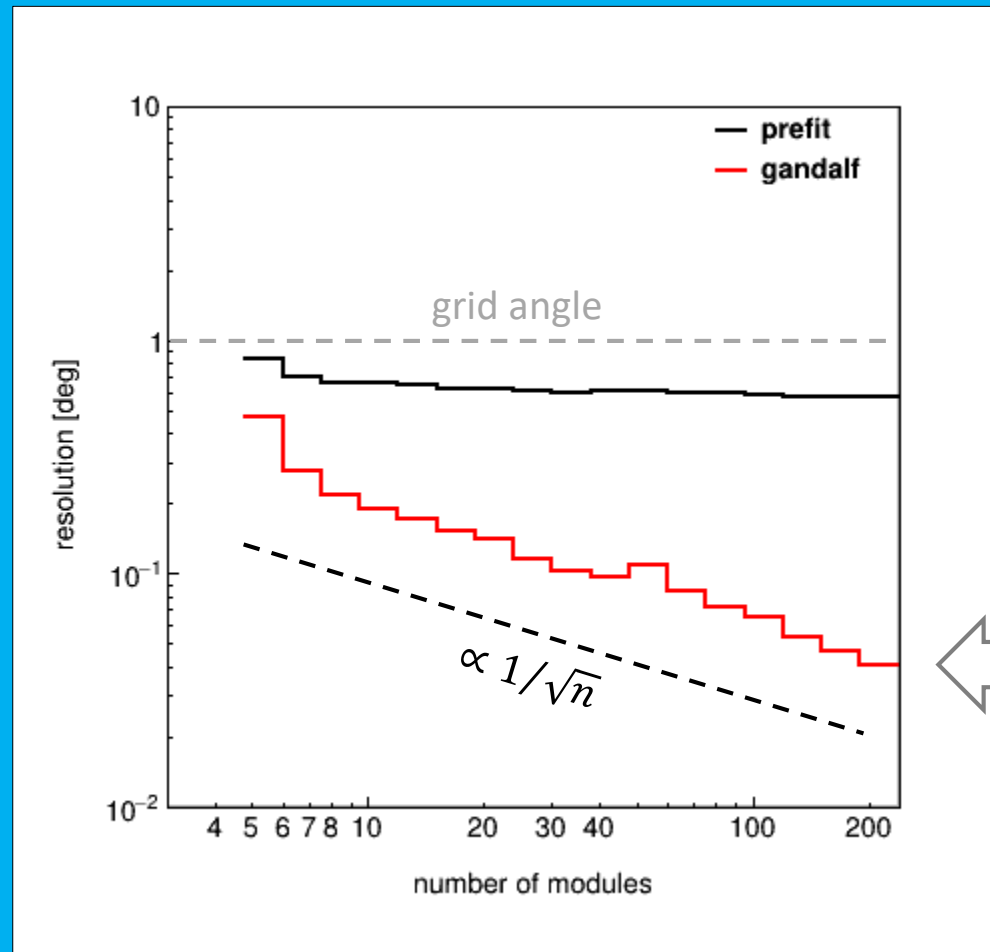
$$\frac{1}{R} \propto \quad \propto \frac{1}{R}$$

$$\frac{d\mathcal{P}}{dt} = \Phi_0(R, \lambda) A \left(\frac{\partial t}{\partial \lambda} \right)^{-1} \varepsilon(\cos \theta_\odot) QE(\lambda) e^{-d/\lambda_{abs}} e^{-d/\lambda_s}$$

$$\frac{d\mathcal{P}}{dt} = \iiint d\lambda dz d\phi_0 \frac{1}{2\pi} \frac{dN}{dx} \frac{1}{\lambda_s} \left(\frac{\partial t}{\partial u} \right)^{-1} \varepsilon(\cos \theta_\odot) QE(\lambda) e^{-d/\lambda_{att}} \frac{dP_s}{d\Omega_s} d\Omega$$

$$\frac{\partial N_s}{\partial u} \quad \frac{1}{1 - \cos \theta_s}$$

Performance



world's best!

$0.05^\circ \cong 1 \text{ mrad} \cong 3 \text{ arcmin}$

“intelligent lockdown”

Dear Dorothea and Robert,[¶]

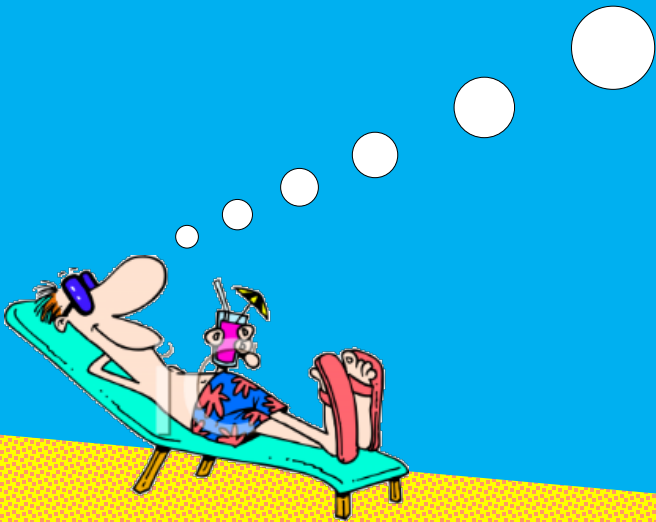
3 March 2020

I would like to suggest that the acoustic position calibration is approached from a data analysis perspective. If I correctly understood, there are various emitters on the seabed. The acoustic signals are regularly produced but the actual time of the emission is not directly recorded. These signals are synchronously detected in different optical modules located on different strings. Furthermore, the positions of the modules are constraint by the mechanics of the string. To make optimal use of the available information, the shapes of the different strings should simultaneously be reconstructed from the measured times-of-arrival of the acoustic signals. In this, the time of emission of the acoustic signal is a free parameter. To further constrain the system, signals from different emitters should be joint.

Regards,

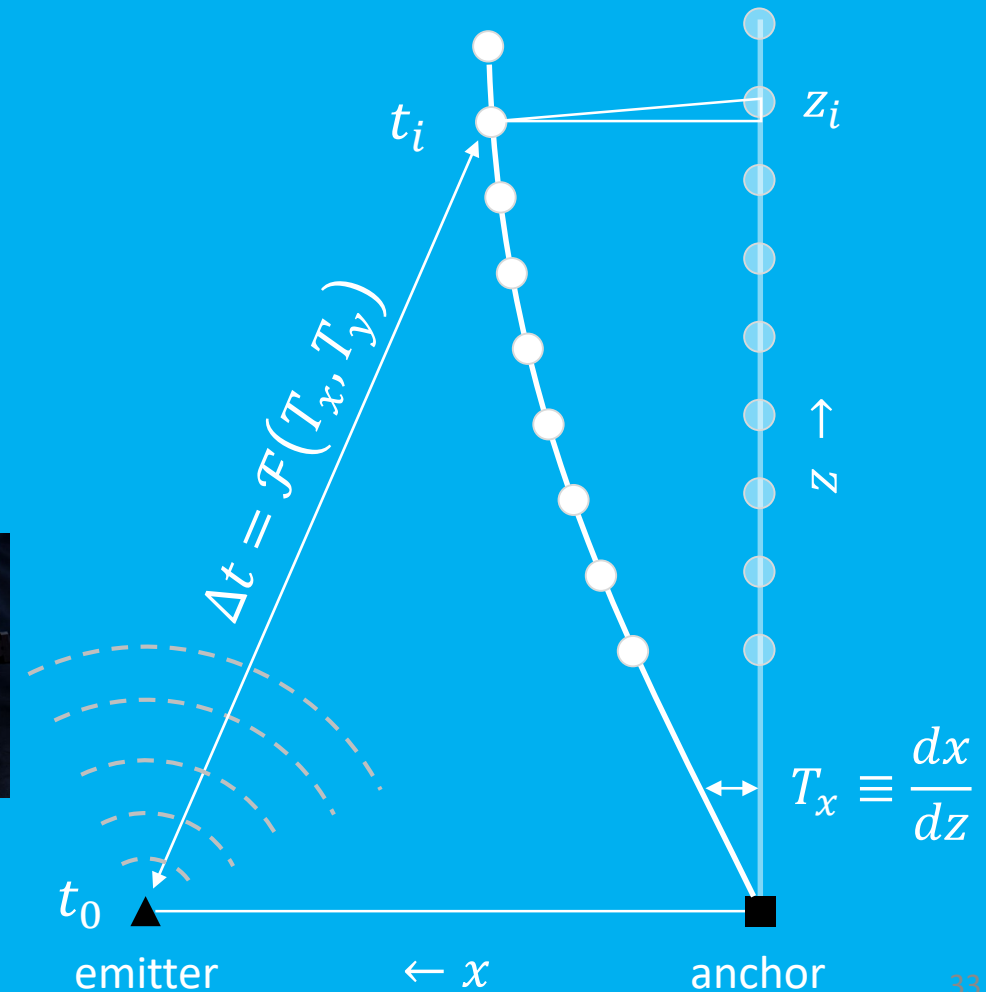
Maarten

[¶] Convenors of KM3NeT calibration working group.



Concept

- model
 - mechanical constraints
 - shape of string = drag + buoyancy
- parameters
 - string: 2 tilt angles (T_x, T_y)
 - ping: 1 time of emission (t_0)
- data
 - time of arrival t_i in optical module



Implementation

1. event builder

- correlate times of emission from given emitter (referred to as “event”)

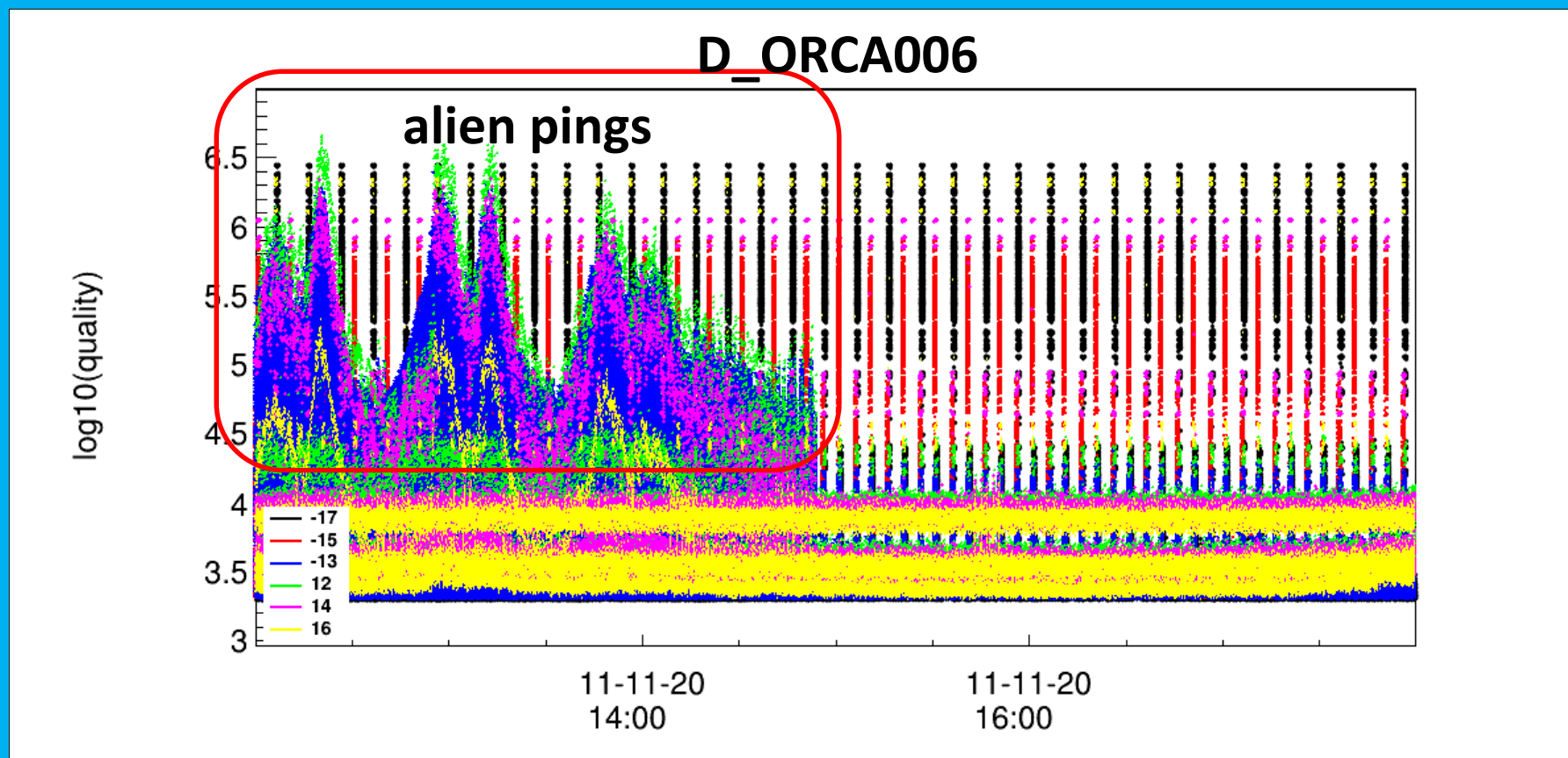
2. fit

- combine events within fixed time intervals (typically 10 mins.)
- simultaneously fit all model parameters to data

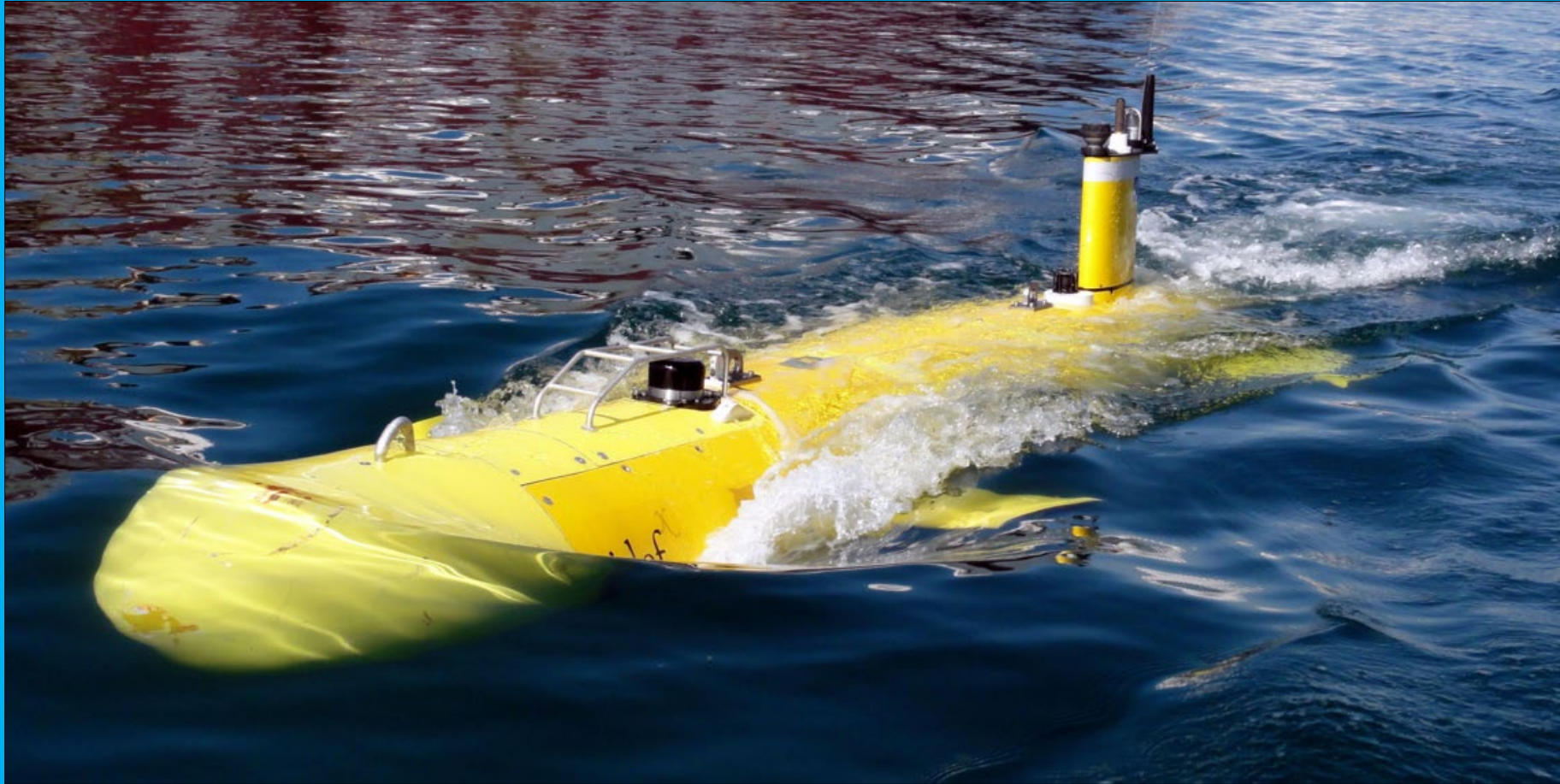
3. dynamical calibration of detector

- interpolate fitted model parameters and correct detector geometry on-the-fly (typically every minute)

Event builder



Culprit



Fit

- Levenberg-Marquardt algorithm (text book)
 - repeatedly solve curvature matrix equation

$$\underset{(n \times n)}{A} \underset{(n \times 1)}{\bar{x}} = \underset{(n \times 1)}{\bar{b}}$$

$$A_{ij} \equiv \sum_N \frac{\partial \chi^2}{\partial x_i} \frac{\partial \chi^2}{\partial x_j} \qquad b_i \equiv \sum_N \frac{\partial \chi^2}{\partial x_i}$$

Fit

- Number of parameters $n \sim 300$
- Number of data points $N \sim 100,000$

$$A_{ij} \equiv \sum_N \frac{\partial \chi^2}{\partial x_i} \frac{\partial \chi^2}{\partial x_j} \quad i \in \{1, 2, \dots, n\}$$

$\Sigma \Rightarrow \text{CPU}$

Fit

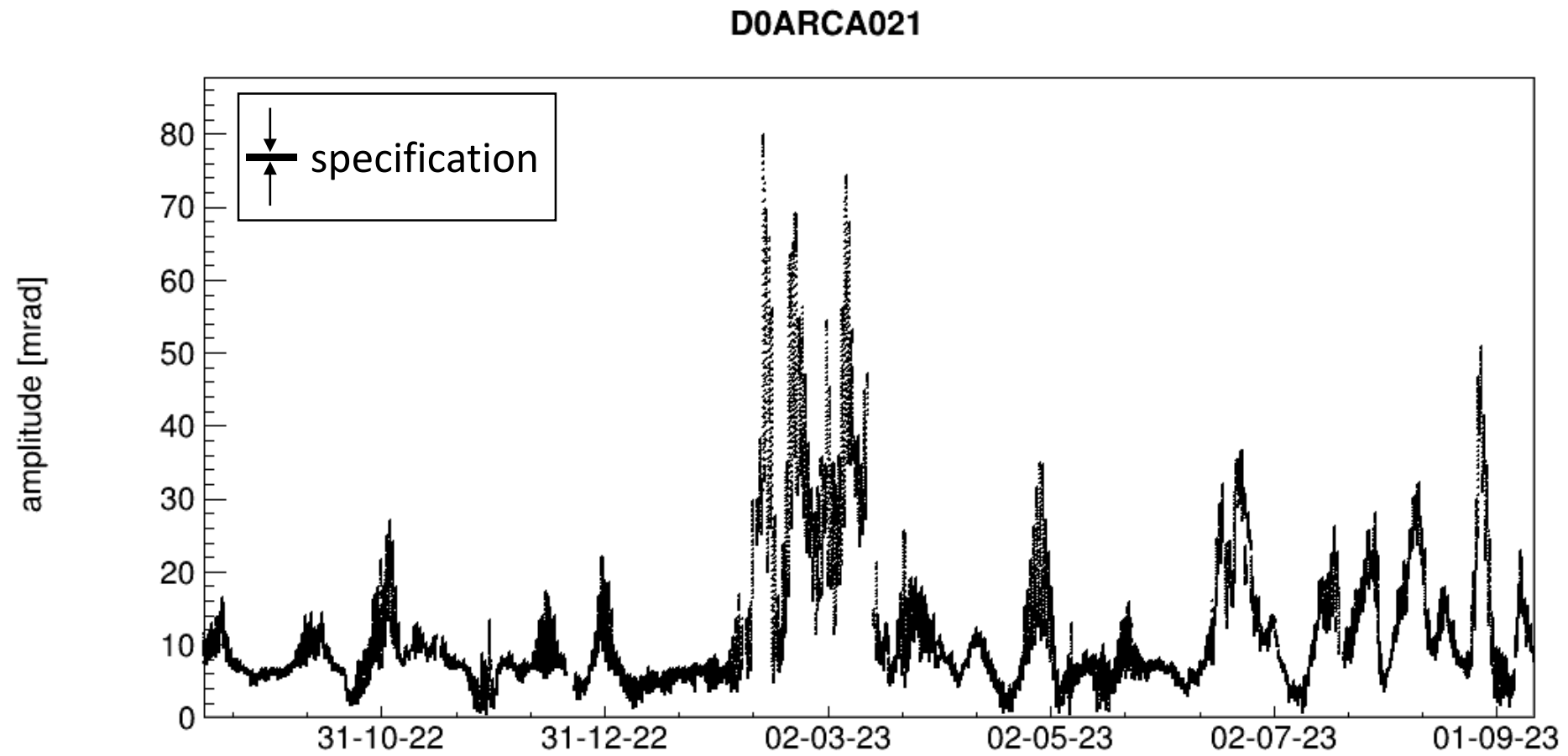
- Each data point affects only one ping and one string (= 3 parameters)

- $i \notin \{i_1, i_2, i_3\} \Rightarrow \frac{\partial \chi^2}{\partial x_i} = 0$

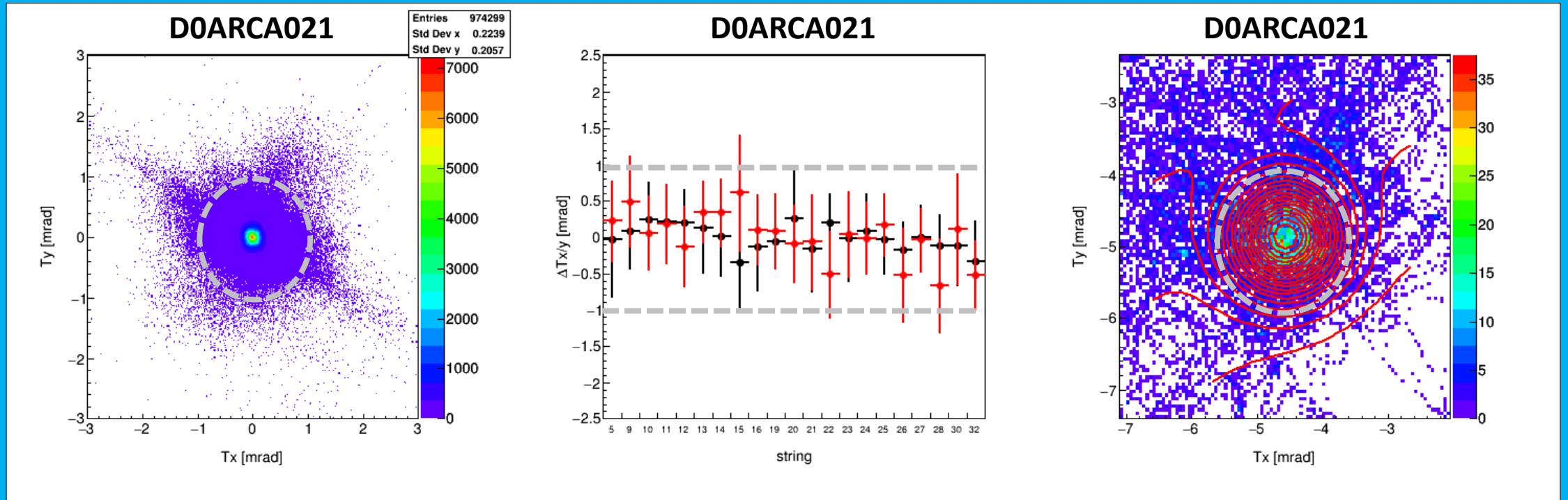
$$A_{ij} \equiv \sum_N \frac{\partial \chi^2}{\partial x_i} \frac{\partial \chi^2}{\partial x_j} \quad i \in \{i_1, i_2, i_3\}$$

customisation \Rightarrow 1000 x faster

Results

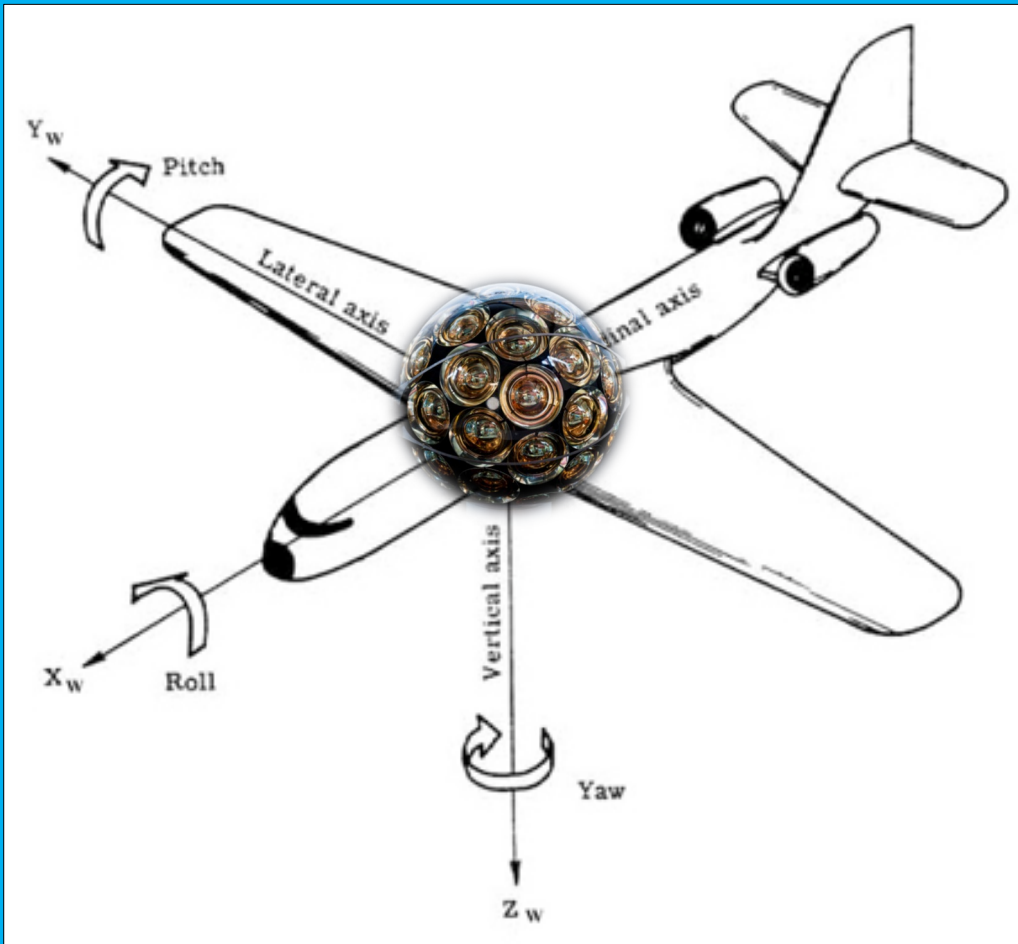


Resolution

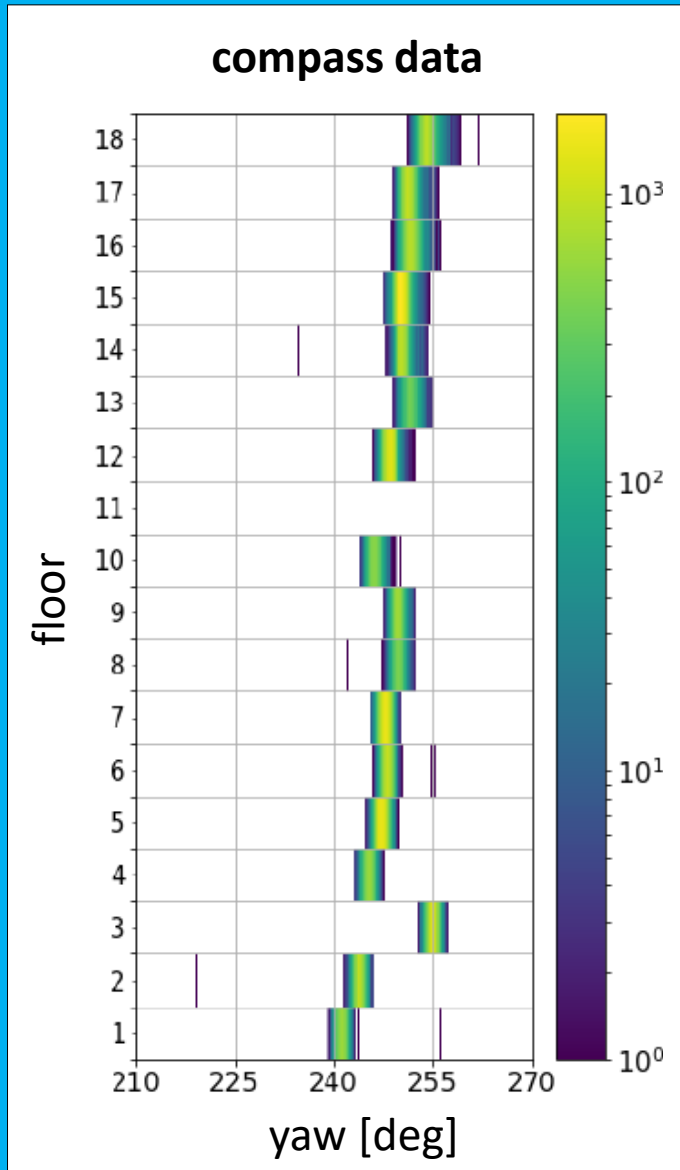


resolutions within 1 mrad

Orientation calibration



Here as he walked by
on the 16th of October 1843
Sir William Rowan Hamilton
in a flash of genius discovered
the fundamental formula for
quaternion multiplication
 $i^2 = j^2 = k^2 = i j k = -1$
& cut it on a stone of this bridge.



$$\text{twist} \equiv \frac{\Delta}{z}$$



idea

orientation of optical modules

- measured by 3D-compass
 - yaw, pitch and roll
- related through string mechanics
 - tilt
 - twist

$$\text{tilt} \equiv \varphi$$



Fit

- model

- $Q_i = Q_0 Q_1^{z_i}$

- Q_0 tilt of the string

- Q_1 twist of string

- z_i height floor i

- data

- yaw, pitch and roll → quaternion

Fit
polynomial of quaternions
to
quaternions

“Easier said than done.”

Fit

- Metric
 - geodesic distance between two quaternions

- Resolution for χ^2 evaluation

- $\sigma \equiv \frac{1}{2} \sqrt{\sigma_x^2 + \sigma_y^2 + \sigma_z^2}$

- Minimiser

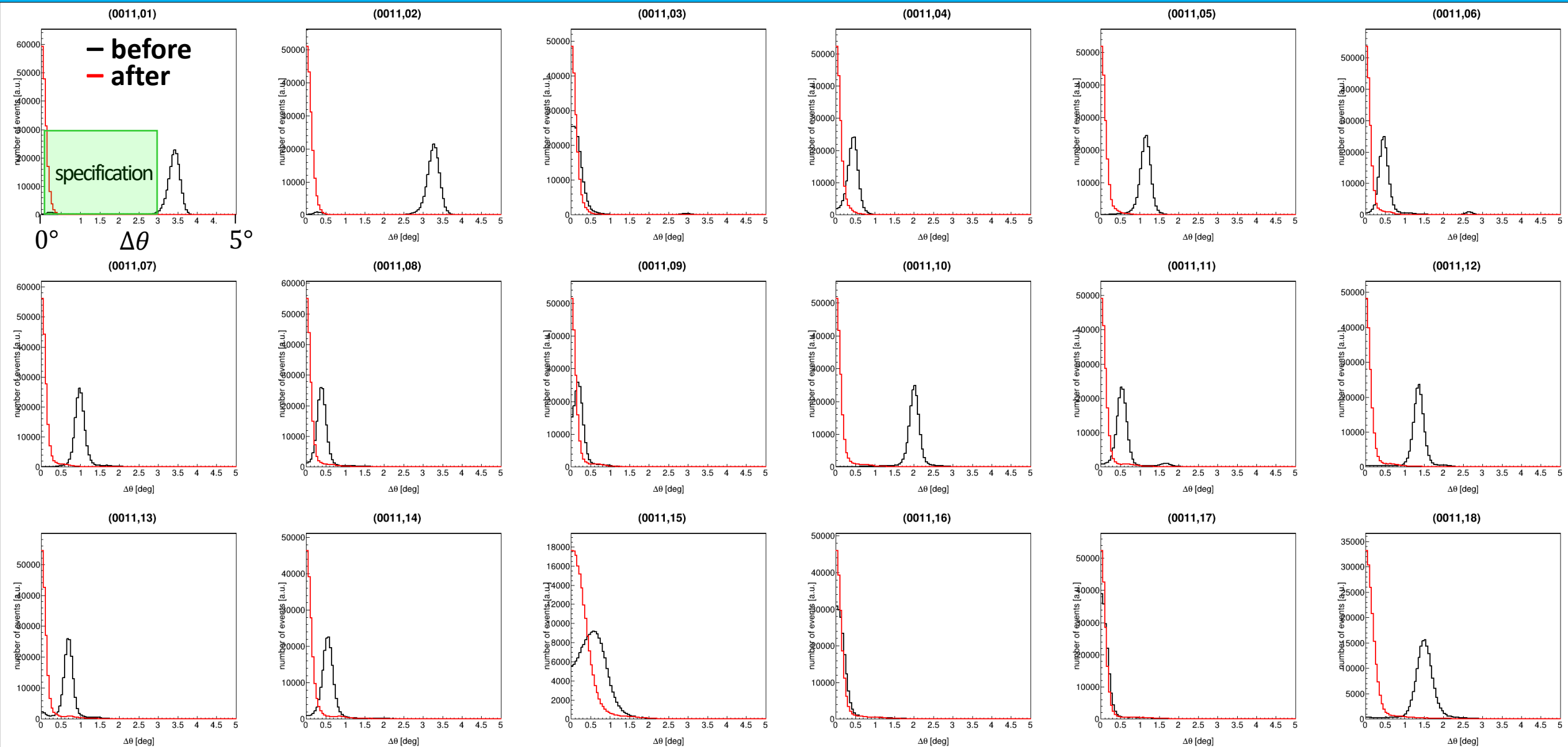
- JSimplex[¶] works out-of-the-box

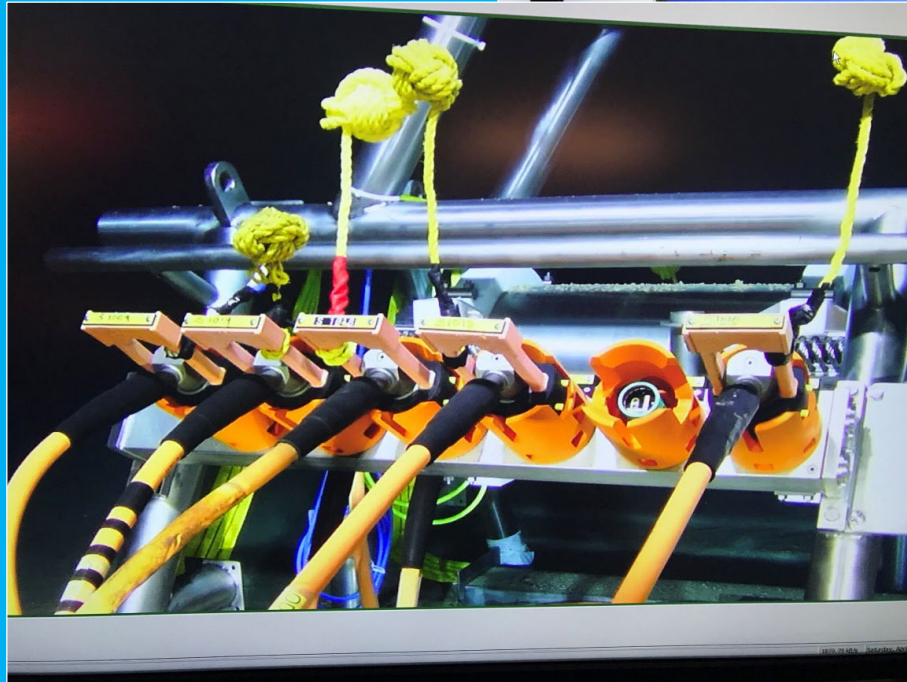
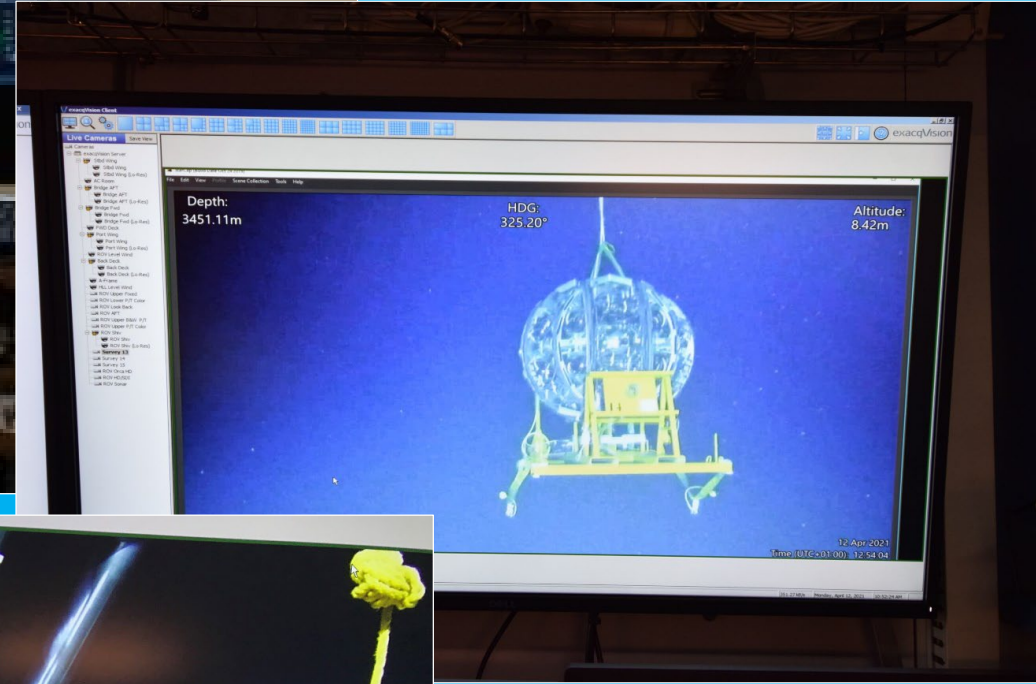
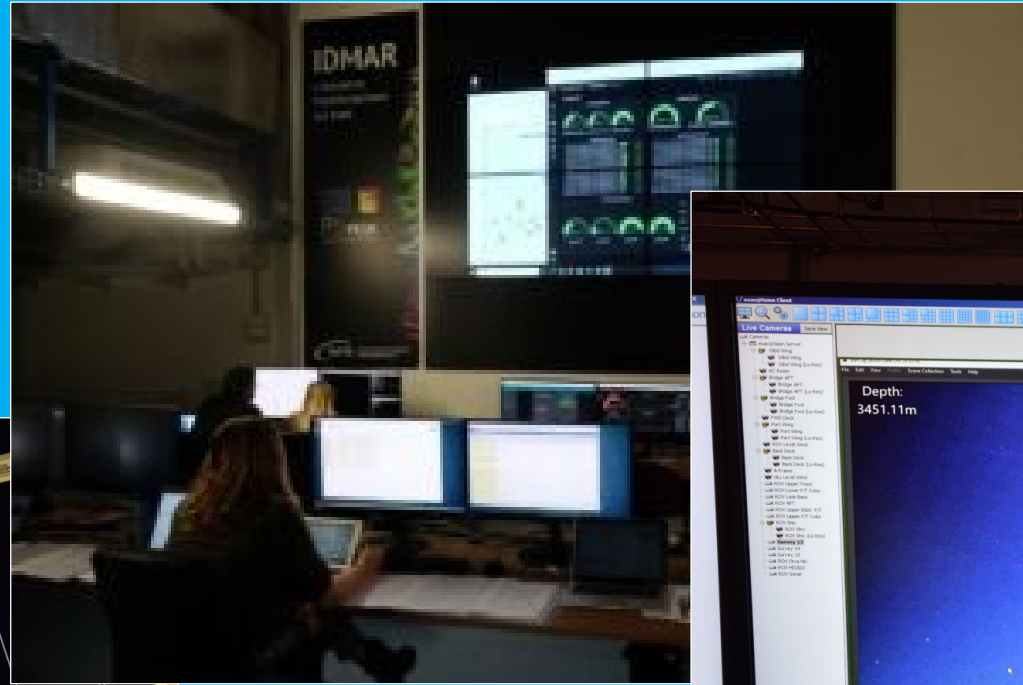
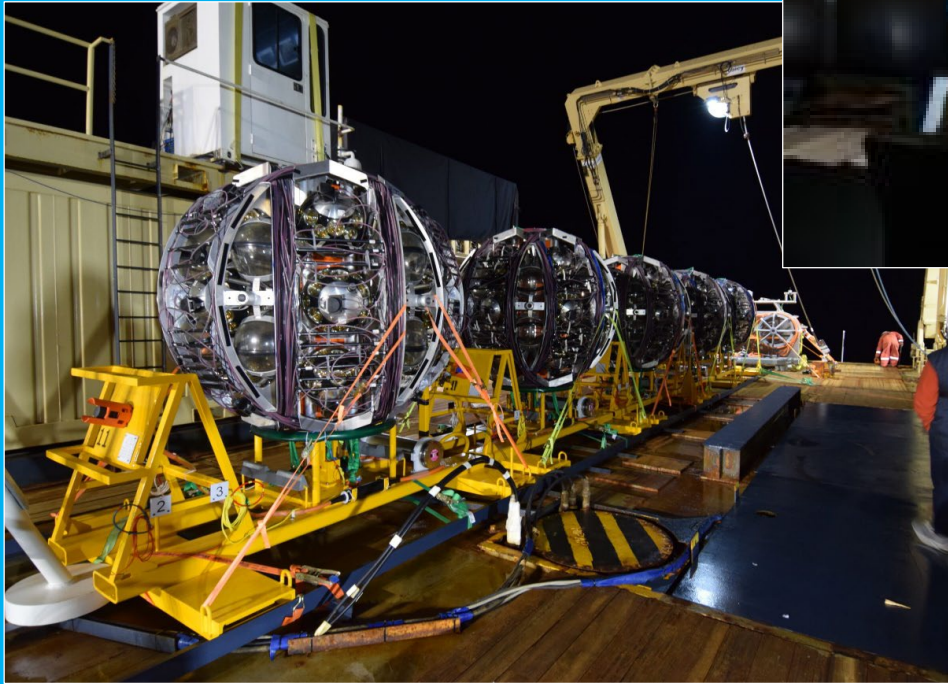
- step corresponds to multiplication $Q \pm \Delta Q \Rightarrow Q \Delta Q^{\pm 1}$
 - scaling corresponds to power $Q \times y \Rightarrow Q^y$

✓ Euler's theorem

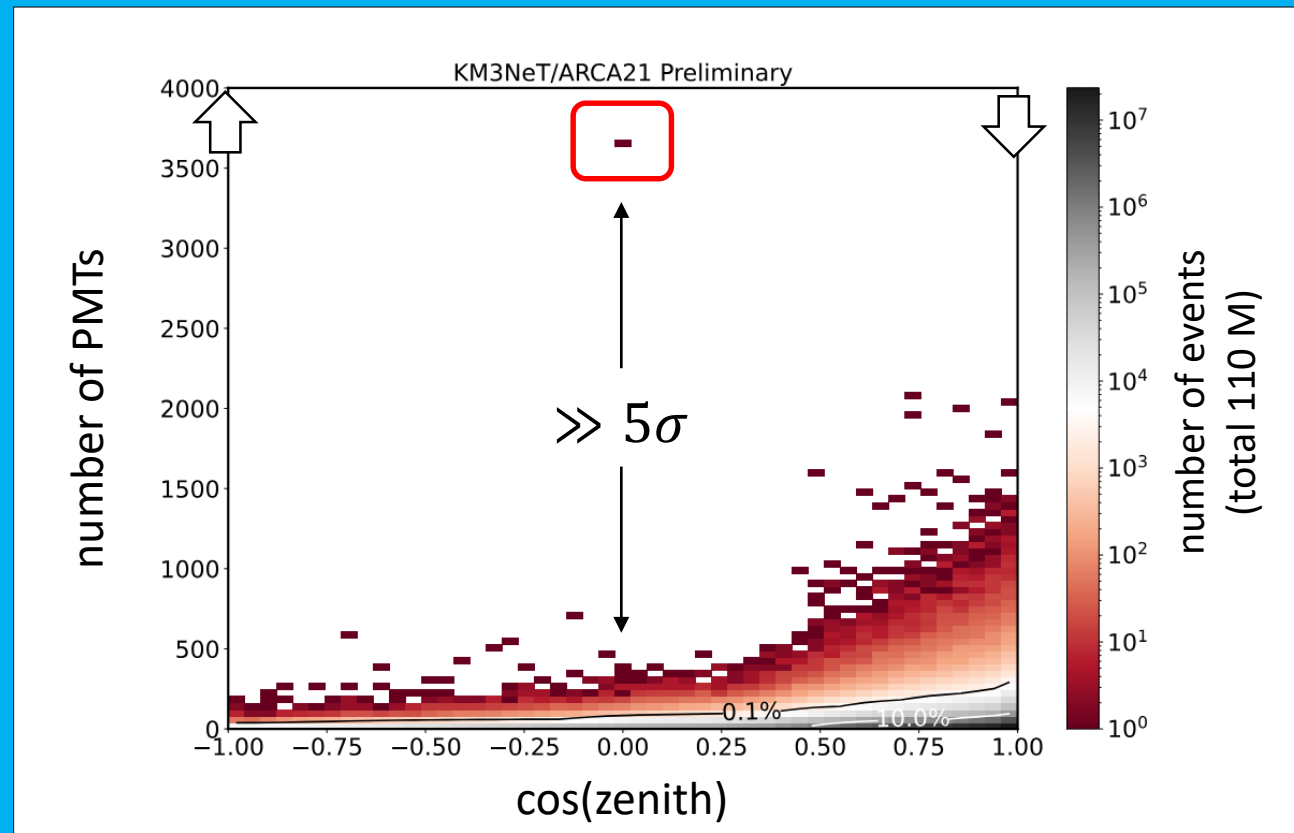
"Easier done than said."

[¶] JSimplex is a custom-made minimiser in C++.



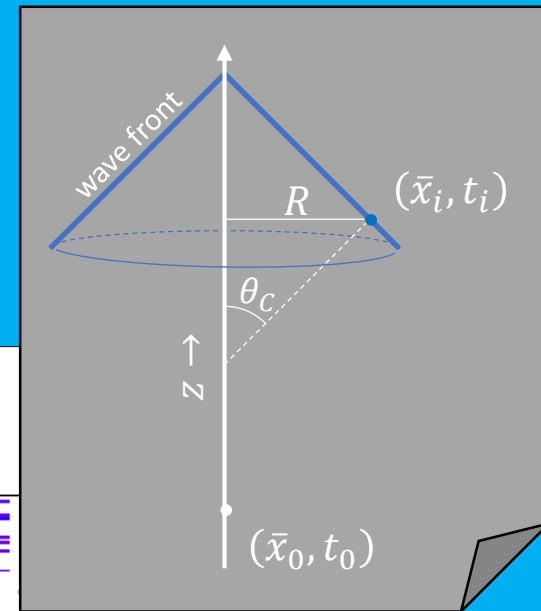
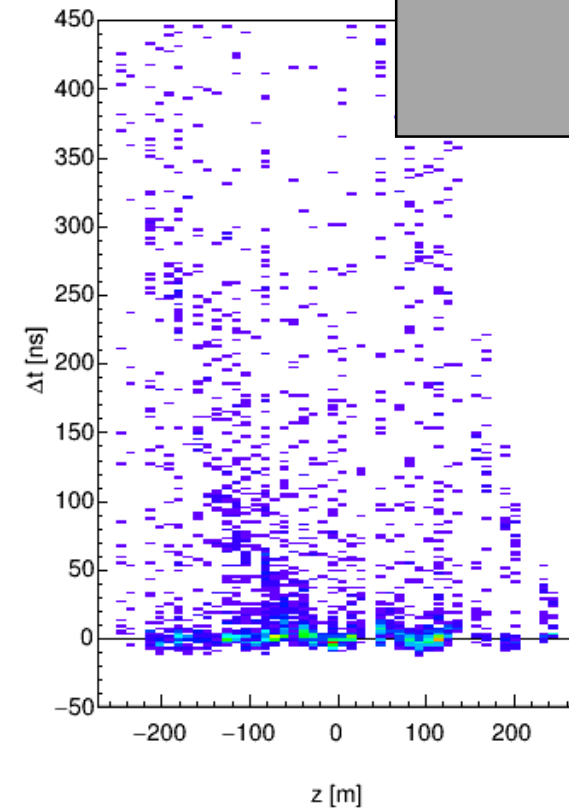
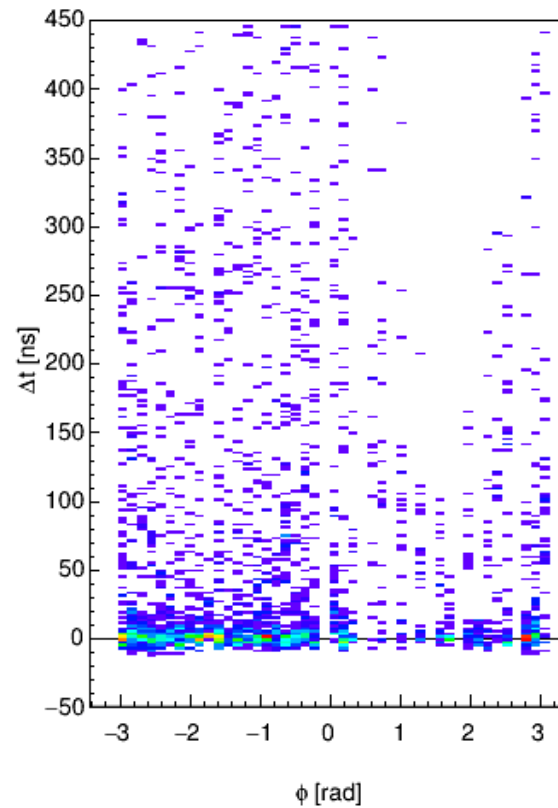
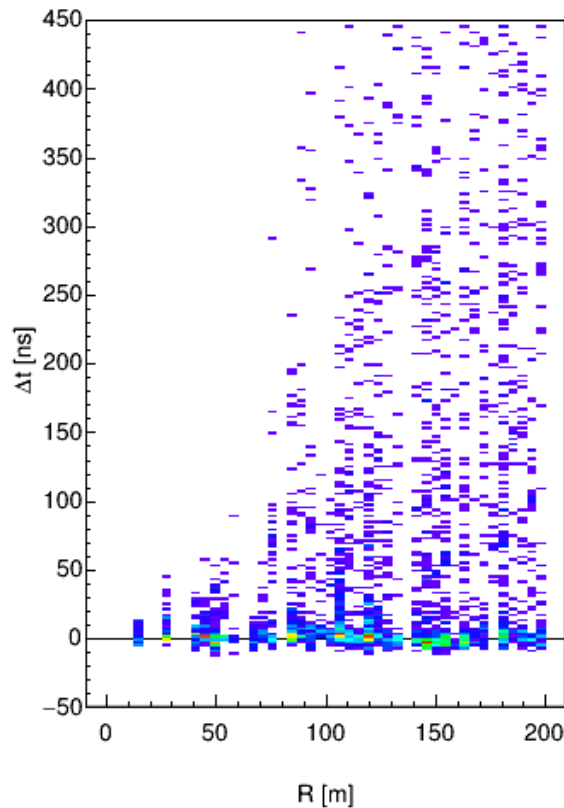


KM3-230213A



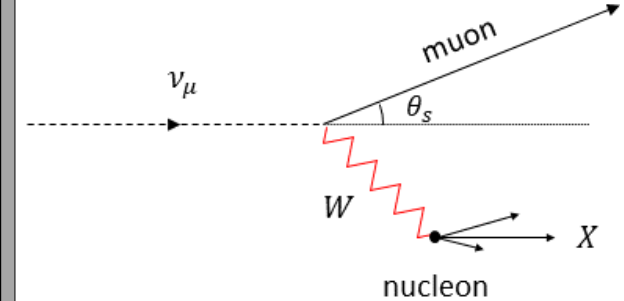
Event display

014728:46077/1188 Q = 1404 $E = 9.9\text{e}+07$ [GeV] $\cos(\theta) = -0.011$

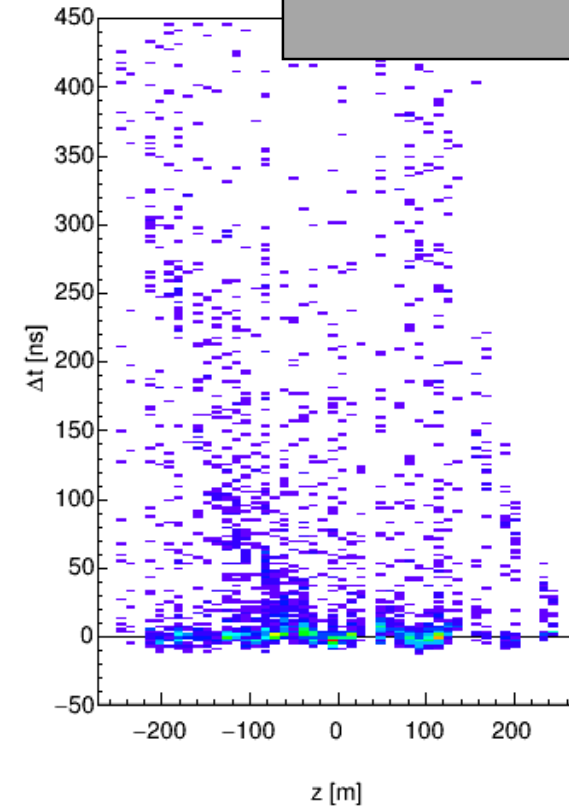
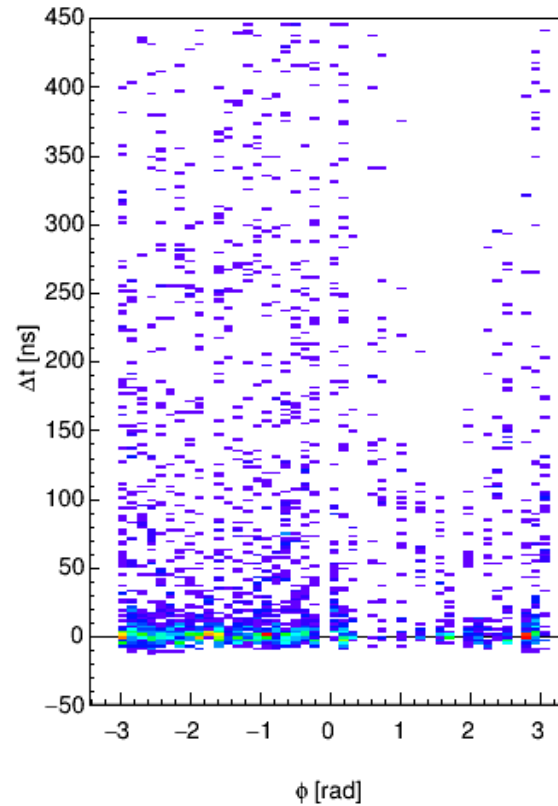
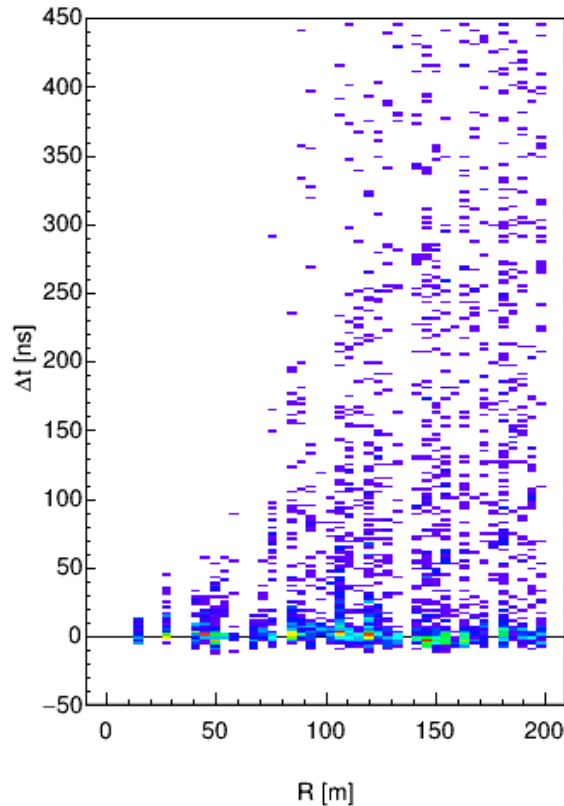


$$E_\nu \geq E_\mu \geq E_{\text{measured}}$$

neutrino interaction

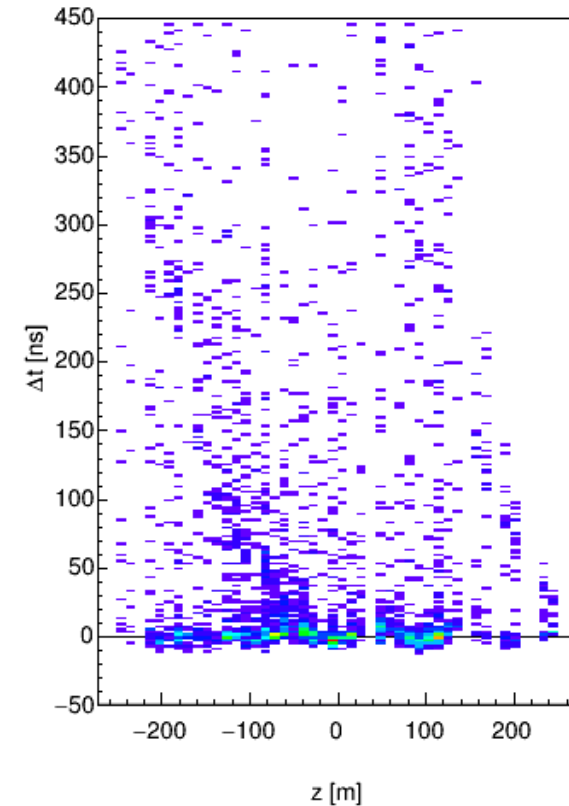
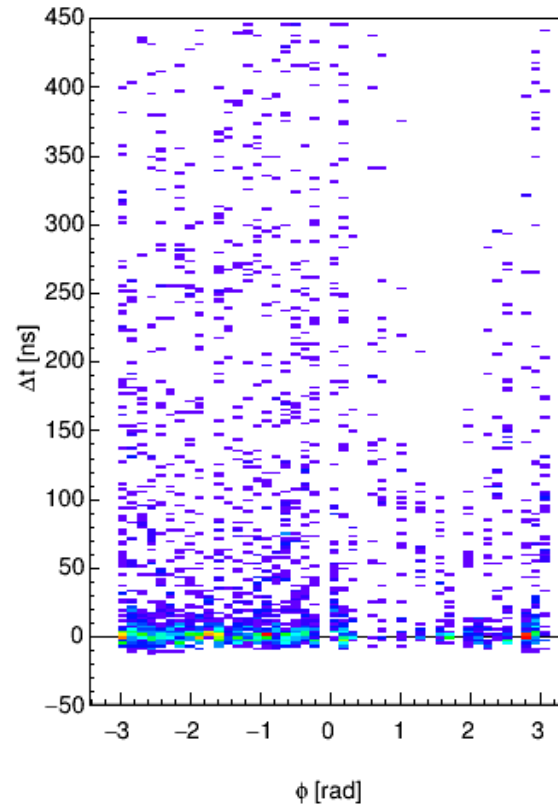
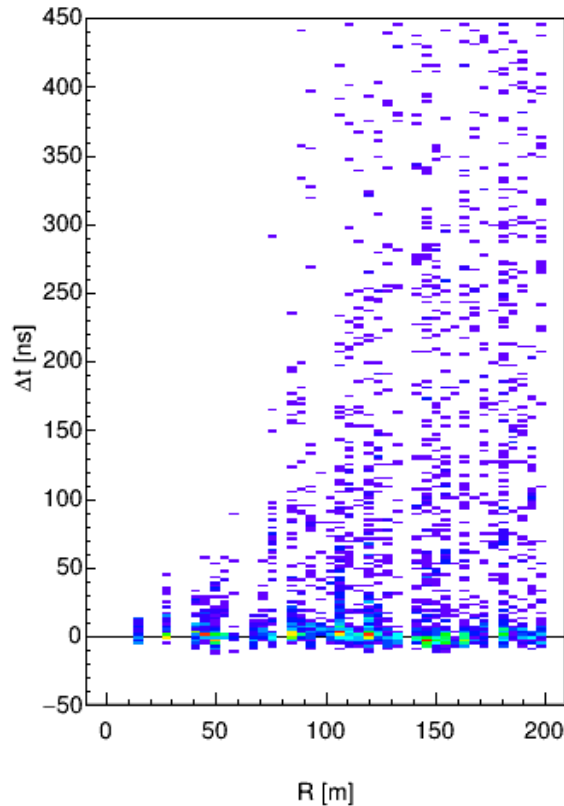


014728:46077/1188 Q = 1404 E = 9.9e+07 [GeV] cos(θ) = -0.011



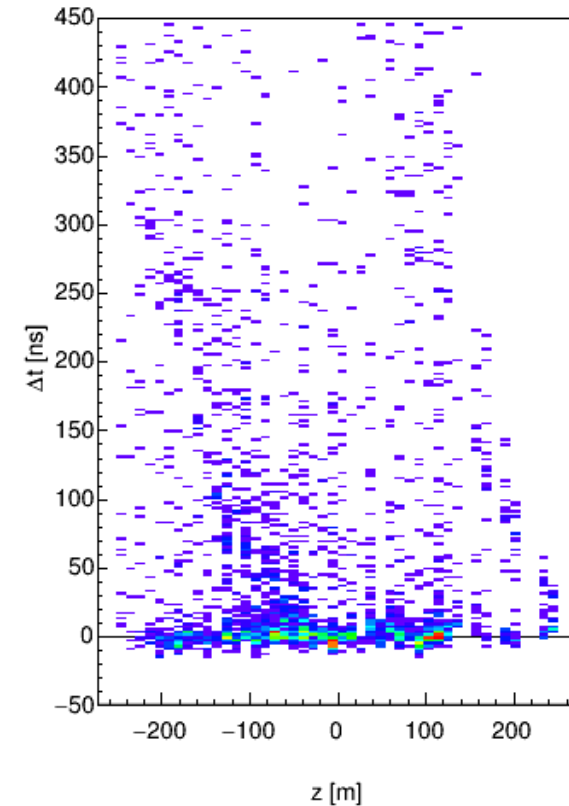
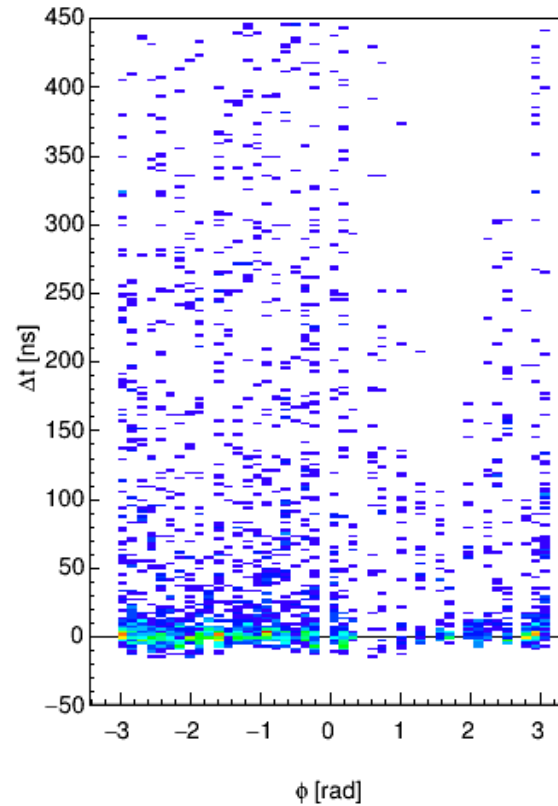
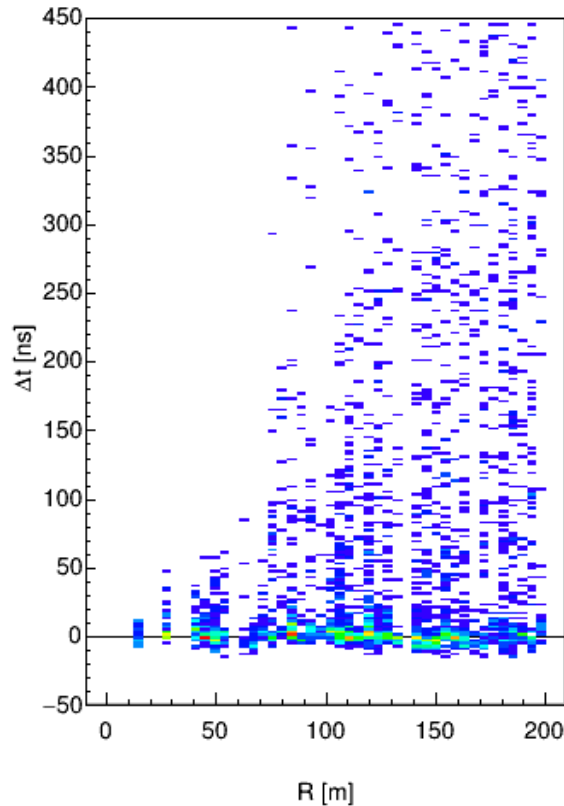
Event display - dynamic calibrations

014728:46077/188 Q = 1404 E = 9.9e+07 [GeV] $\cos(\theta) = -0.011$



Event display - static calibrations

014728:46077/188 Q = 1044 E = 8.9e+07 [GeV] $\cos(\theta) = -0.005$



Q/A

- Why is direction of this neutrino close to horizon?
- Do we know [astrophysical] origin of neutrino?
- Could it be a tau?
- Could it be a charged-current interaction of a tau neutrino?
- Is observation [in]compatible with IceCube results?

Summary & Outlook

- KM3NeT construction [now] proceeds as planned
 - time to completion about 5 years
 - **deployment of hardware for absolute pointing of KM3NeT/ARCA 2025/2026**
- KM3NeT operation ongoing
 - data are being recorded 24/7
 - **neutrino physics with KM3NeT/ORCA**
- KM3NeT science output depends on:
 - **calibration = data analysis**
 - **reconstruction = data analysis**