

Dynamics of fast rotating neutron stars: Time evolution of linear perturbations in full general relativity

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Neutron Stars — laboratories for matter under extreme conditions

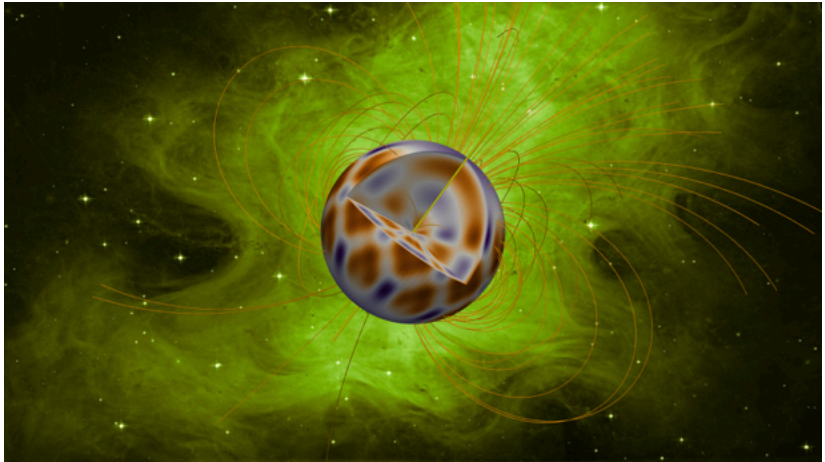


Illustration: Gaertig, Kokkotas (2019)

Equations of State - A Zoo

What's inside a neutron star?

- Neutron stars are the final stage of the lives of massive stars ($M \gtrsim 8 M_{\odot}$).
- About 1.4 – 2.0 solar masses are compressed into a ball of radius $r \approx 11 - 14$ km.
- Density reaches more than 10^{15} g/cm³, several times that of an atomic nucleus.
- Matter is described by an **equation of state** (EOS).

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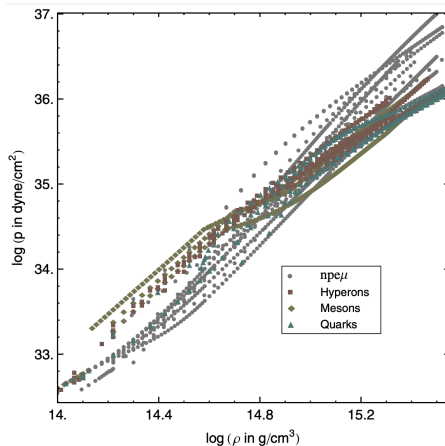
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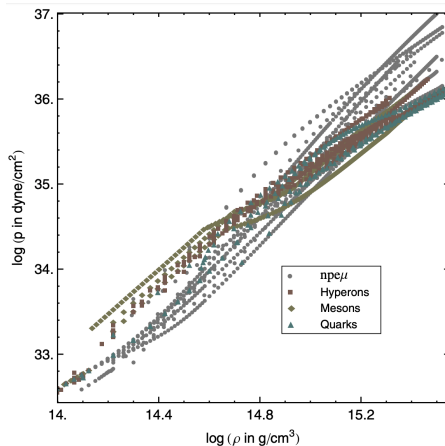


Read et al. (2009)

- EOS is a function $p = p(\rho)$.
- While the low density EOS is well constrained, it has large uncertainties at high densities (in the NS core, $\rho \gtrsim \rho_{\text{nuc}}$).
- Numerous EOS have been proposed.
- Various models (variational method, Hartree-Fock, RMF, ...), various particles ($npe\mu$, π , K , quarks, ...), phase transition, ...

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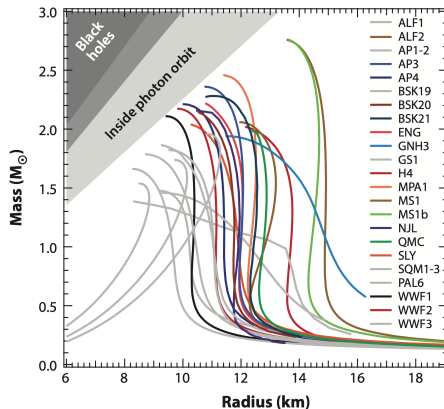
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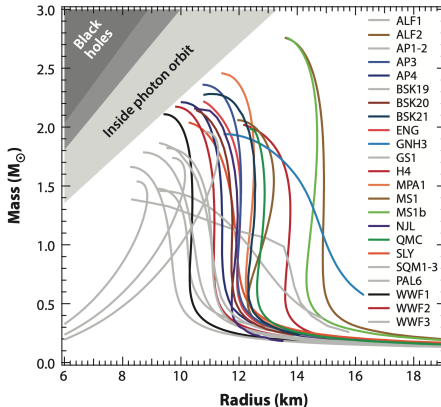
Equations of State - A Zoo



Özel, Freire (2016)

- EOS is typically visualised via the resulting M - R curve for NSs.
- Some EOS are already ruled out by observation:
 - $2 M_{\odot}$ NS,
 - Tidal deformability in binary mergers,
 - NICER observations, ...

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The Question

How can we probe the interior of an NS
and learn about the EOS?

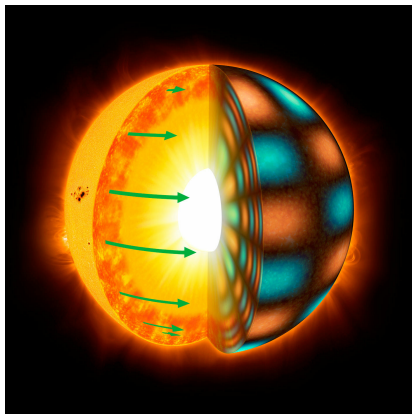
Here: Seismology

The Question

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Here: Seismology

Helioseismology



scitechdaily.com / MPS (2018)

- Seismology extremely successful in the sun
→ Helioseismology.
- Thousands of individual oscillation modes observed → detailed knowledge of the Sun's internal structure.

Asteroseismology

NS oscillations are extremely difficult to observe.

- via gravitational waves,
- perhaps in magnetar flares or by modulation of other e/m signals,
- via impact on dynamic system, e.g., binary inspirals.

For the moment

- calculate frequencies based on proposed models,
- unveil patterns and universal relations.

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Neutron Star Oscillations - Formulating the Problem

- Einstein equations

$$G_{\mu\nu} = 8\pi T_{\mu\nu}$$

and (implied) conservation of energy-momentum

$$\nabla_{\mu} T^{\mu\nu} = 0$$

- General metric for a rotating neutron star

$$ds^2 = -e^{2\nu} dt^2 + e^{2\psi} r^2 \sin^2 \theta (d\phi - \omega dt)^2 + e^{2\mu} (dr^2 + r^2 d\theta^2)$$

(as used by the `rns`-code (Friedman & Stergioulas (1995)))

- Neutron star matter modelled as perfect fluid

$$T^{\mu\nu} = (\rho + p)u^{\mu}u^{\nu} + pg^{\mu\nu}$$

These equations need to be solved – but it's quite complicated...

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Perturbation Equations

Simplification I

- Assume that the star is “almost” in equilibrium.
- Employ *first order perturbation theory*, i.e. write every quantity as “background + perturbation”:

$$X = \bar{X} + \delta X$$

- Then throw away all terms that are quadratic (or higher) in the perturbations.

→ Required numerical methods are *a lot* easier and computational costs are incomparably lower!

Perturbation Equations

Simplification II

- Most general form of the equations:

$$\frac{\partial Q}{\partial t} = A_r \frac{\partial Q}{\partial r} + A_\theta \frac{\partial Q}{\partial \theta} + A_\phi \frac{\partial Q}{\partial \phi} + A Q$$

- Q is a vector containing all evolved perturbation quantities and the A , A_r , A_θ and A_ϕ are coefficient matrices that depend on the background quantities only.

Perturbation Equations

Simplification II

- Assume axisymmetry:

$$Q(t, r, \theta, \phi) = \tilde{Q}(t, r, \theta)e^{im\phi}$$

- This removes the azimuthal derivatives from the equations:

$$\frac{\partial}{\partial \phi} \rightarrow im$$

- Number of dimensions reduced by 1.

Numerical Implementation

Methods for solving the hyperbolic PDEs: Method of Lines

- Finite differences of 2nd order for spatial derivatives.
- Runge-Kutta 3rd order for time stepping.
- Use **Kreiss-Oliger dissipation** to stabilise time evolution.
Coefficients are of the order 10^{-5} to 10^{-7} .

$$\frac{\partial Q}{\partial t} = A_r \frac{\partial Q}{\partial r} + A_\theta \frac{\partial Q}{\partial \theta} + imA_\phi Q + A Q + \alpha \nabla^2 Q$$

- Derivatives of Kreiss-Oliger term are evaluated on grid coordinates rather than physical coordinates.

Perturbation equations

Time Evolution of Perturbation Equations

- **Perturbed** (linearised) Einstein Equations
& Conservation of Energy-Momentum

$$\begin{aligned}\delta G_{\mu\nu} &= 8\pi\delta T_{\mu\nu}, \\ \delta(\nabla_\nu T^{\mu\nu}) &= 0,\end{aligned}$$

with the typical metric perturbations

$$g_{\mu\nu} = g_{\mu\nu}^0 + h_{\mu\nu}.$$

- Metric perturbations require choice of gauge:
Choose the Hilbert Gauge:

$$\nabla^\mu h_{\mu\nu} = 0.$$

→ 10 coupled wave equations for the metric components.

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→ 10 coupled wave equations for the metric components.

$$\begin{aligned} \frac{(\alpha^*)^2 \left(\frac{\partial^2}{\partial t^2} PP \right)}{(\alpha^*)^2} &= \left(2 \operatorname{Im}(\psi_\mu - \psi_\mu + \cot(\theta)) + \frac{\operatorname{Im} \omega \sin(\theta) (\alpha^*)^2 \omega_\mu}{(\alpha^*)^2} \right) BB + \left((2n_1 - n) (\alpha^*)^2 - \frac{2(\nu_r \mu_r r^2 + r \nu_r - \nu_r \mu_r + 2\mu_r^2 + \nu_\mu \mu_r)}{r^2} + \frac{(\alpha^*)^2 (\sin^2(\theta) \omega_\mu^2)}{(\alpha^*)^2} \right) HH \\ &+ \left((\alpha^*)^2 n - \frac{2(r^2 \psi_r \nu_r - \mu_r^2 r^2 + r \nu_r + \psi_\mu \nu_r - \mu_r^2 + 2\nu_\mu \mu_r - 2\mu_r r + \cot(\theta) \nu_\mu - 1)}{r^2} - \frac{(\sin^2(\theta) (r^2 \omega_\mu^2 + \omega_\mu^2) (\alpha^*)^2)}{2(\alpha^*)^2} \right) KK - \frac{\operatorname{Im} \omega \operatorname{Im} M}{(\alpha^*)^2 r} \\ &+ \left((-2n_1 + n) (\alpha^*)^2 - \frac{-2\nu_r \mu_r r^2 + 2(\cot^2(\theta) + 2\cot(\theta) \nu_\mu - 4\cot(\theta) \nu_\mu - 2\mu_r r + 2\nu_\mu \mu_r - 4\nu_\mu \nu_r - 2\psi_r r - 2\nu_\mu \nu_r)}{r^2} - \frac{(\alpha^*)^2 (\sin^2(\theta) \omega_\mu^2)}{(\alpha^*)^2} \right) WW \\ &+ \left(2\sin(\theta) (\alpha^*)^2 (\alpha^*)^2 r \omega_1 n_1 + \frac{\sin(\theta) (\omega_r \mu_r r^2 + 2\nu_\mu \omega_\mu - \omega_\mu \mu_r + 2\cot(\theta) \omega_\mu + r \nu_r + \omega_\mu \mu_r)}{r} (\alpha^*)^2 \right) YY + 8(\alpha^*)^4 \pi Q_6 \\ &+ \left((-m^2 \kappa \rho \lambda \phi - n) (\alpha^*)^2 - \frac{2(\mu_r^2 r^2 + \psi_\mu^2 - 2\nu_r \nu_r + 2\nu_\mu \cot(\theta) + \mu_r^2 - 2\nu_\mu n_1 + 2\mu_r r - \nu_r^2 - 2\cot(\theta) \nu_\mu + \cot^2(\theta) + 1)}{r^2} + \frac{(\alpha^*)^2 (\sin^2(\theta) \omega_\mu^2)}{(\alpha^*)^2} \right) PP + (r \nu_r + \psi_r r + 2) \left(\frac{\partial}{\partial t} PP \right) + \frac{(\psi_\mu + 5\nu_\mu + \cot(\theta)) \left(\frac{\partial}{\partial t} PP \right)}{r} \\ &+ \left(4\nu_r \mu_r r - 2r \mu_r \mu_r - 2\nu_\mu \psi_r r + 2\nu_r \nu_r + 2\nu_\mu \psi_r r + \nu_r r r + \psi_r r r - 2\nu_\mu + 6\nu_r \right) QQ - \frac{2(-\nu_r + \mu_r) \left(\frac{\partial}{\partial t} QQ \right)}{r} + \frac{2(\mu_r r + 1) \left(\frac{\partial}{\partial t} QQ \right)}{r} + \frac{\partial^2}{\partial r^2} PP - \frac{21(\alpha^*)^2 \omega \left(\frac{\partial}{\partial t} PP \right) m}{(\alpha^*)^2} + \frac{\sin(\theta) (\alpha^*)^2 \omega_\mu \left(\frac{\partial}{\partial t} BB \right)}{(\alpha^*)^2} + \frac{\frac{\partial^2}{\partial t^2} PP}{r^2} \end{aligned}$$

$$\begin{aligned} \frac{\partial}{\partial t} QI &= \left(12m\kappa n_2 - \frac{\operatorname{Im} \omega (p + \rho)}{2(\alpha^*)^2} \right) HH + \left(2112m\kappa n_2 - \frac{\operatorname{Im} \omega (p + \rho)}{2(\alpha^*)^2} \right) KK + \left(2112m\kappa n_2 - \frac{\operatorname{Im} \omega (p + \rho)}{2(\alpha^*)^2} \right) PP + \left(1(\omega + 2\omega) m \kappa + \frac{\operatorname{Im} \omega (p + \rho)}{2(\alpha^*)^2} \right) WW - \sin(\theta) m r r 2 \omega_1^2 (\alpha^*)^2 YY + \left(\kappa + \frac{-\frac{r}{2} - \frac{r}{2}}{(\alpha^*)^2} \right) \left(\frac{\partial}{\partial t} HH \right) + \left(2\kappa + \frac{-\frac{r}{2} - \frac{r}{2}}{(\alpha^*)^2} \right) \left(\frac{\partial}{\partial t} KK \right) \\ &+ \left(2\kappa + \frac{-\frac{r}{2} - \frac{r}{2}}{(\alpha^*)^2} \right) \left(\frac{\partial}{\partial t} PP \right) + \left(\kappa + \frac{-\frac{r}{2} - \frac{r}{2}}{(\alpha^*)^2} \right) \left(\frac{\partial}{\partial t} WW \right) - \frac{\operatorname{Im} QI}{\sin(\theta) r} + \left(-2\mu_r r + 3r \nu_r + \psi_r r + 2 - \frac{(\sin^2(\theta) (\alpha^*)^2 r^2 \omega_1^2)}{(\alpha^*)^2} \right) QI - \frac{\partial}{\partial r} QI + \left(-3\nu_r + 2\mu_r + \psi_\mu + \cot(\theta) - \frac{(\sin^2(\theta) (\alpha^*)^2 r \omega_1^2)}{(\alpha^*)^2} \right) QI - \frac{\partial}{\partial r} QI \end{aligned}$$

$$\begin{aligned} (\alpha^*)^2 \left(\frac{\partial}{\partial t} QI \right) &= 1 \sin(\theta) \operatorname{Im} \omega_1 r n_2 (\alpha^*)^2 AA + (-\nu_r \kappa 2(\alpha^*)^2 + (\sin^2(\theta) \kappa 2\nu_r (-\psi_r \omega_1 r + r \nu_r - \omega_1) (\alpha^*)^2) HH + (\nu_r \kappa 2(\alpha^*)^2 + (\sin^2(\theta) \kappa 2\nu_r (-\psi_r \omega_1 r + r \nu_r - \omega_1) (\alpha^*)^2) KK - \operatorname{Im}(\alpha^*)^2 QI \\ &+ (\nu_r \kappa 2(\alpha^*)^2 + (\sin^2(\theta) \kappa 2\nu_r (-\psi_r \omega_1 r + r \nu_r - \omega_1) (\alpha^*)^2) PP + (-\alpha^*)^2 \nu_r + (\sin^2(\theta) (-2\nu_\mu \omega_1 r - \psi_r \omega_1^2 r + \omega_r \mu_r - 2\omega_1 - \omega_1^2) (\alpha^*)^2) QI - \sin(\theta) (-2\nu_r \omega_1 r + r \nu_r - 2\omega_1) (\alpha^*)^2 QI \\ &- \operatorname{Im} \kappa 2LL + (-\nu_r - 2\mu_r - \frac{(\sin^2(\theta) \omega_1^2 r (\psi_r r + 1) (\alpha^*)^2)}{(\alpha^*)^2} (\alpha^*)^2) QI + (\nu_r \kappa 2(\alpha^*)^2 - (\sin^2(\theta) \kappa 2\nu_r (-\psi_r \omega_1 r + r \nu_r - \omega_1) (\alpha^*)^2) WW - \kappa 2 \sin(\theta) (2\nu_r \omega_1 + 2\psi_r \omega_1 r - r \nu_r + \omega_1) (\alpha^*)^2) YY \\ &+ \sin(\theta) \kappa 2\nu_r (\alpha^*)^2 \left(\frac{\partial}{\partial t} AA \right) + (-\kappa 2(\alpha^*)^2 \frac{p}{2} + \frac{p}{2}) \left(\frac{\partial}{\partial t} HH \right) + \left(\frac{p}{2} + \frac{p}{2} \right) \left(\frac{\partial}{\partial t} KK \right) - \kappa 2 \left(\frac{\partial}{\partial t} LL \right) + \left(\frac{p}{2} + \frac{p}{2} \right) \left(\frac{\partial}{\partial t} PP \right) - (\alpha^*)^2 \left(\frac{\partial}{\partial t} QI \right) + \kappa 2(\alpha^*)^2 \frac{p}{2} - \frac{p}{2} \left(\frac{\partial}{\partial t} WW \right) - \sin(\theta) \kappa 2\nu_r (\alpha^*)^2 (\alpha^*)^2 \left(\frac{\partial}{\partial t} YY \right) \end{aligned}$$

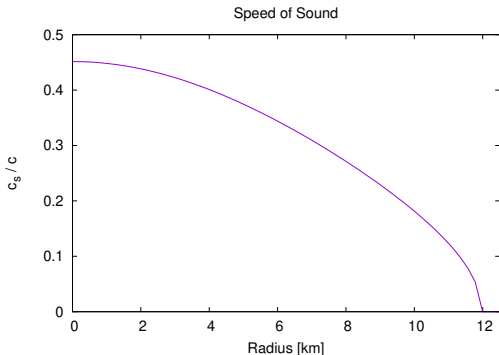
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Numerical Implementation

Choosing a Grid

- Characteristic speed of the neutron star fluid is the speed of sound c_s .

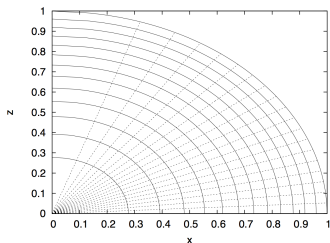
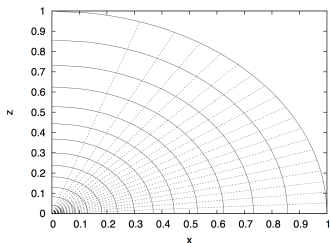


- A uniform grid enforces a small time step at the center of the star (due to the CFL criterion).

Numerical Implementation

Choosing a Grid

- Employ grid (roughly) according to speed of sound:



(Left: grid used in `rns-code`. Right: grid used in (Cowling) time evolution.)

→ Time step Δt can be 10-20 times (or more) larger!

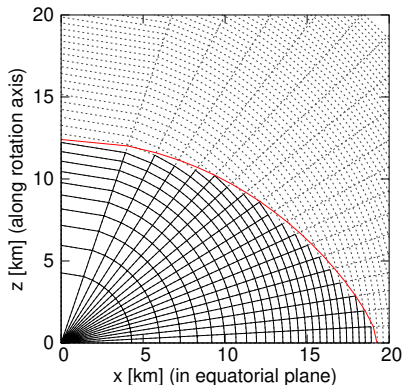
Side effects:

- Kreiss-Oliger coefficients can be smaller by 2 orders of magnitude.
- Deformed surface of neutron star is better resolved.

Numerical Implementation

Choosing a Grid

When spacetime is dynamic, the grid needs to extend up to a few hundred star radii.



Construct grid with similar properties:

- Grid lines squeezed close to surface of star.
- But with increased spacing toward the outer edge.

Numerical Implementation

Slicing the grid to use MPI

- Productive simulation runs on 3000x50 grid (radial \times polar resolution)
- Grid can easily be sliced along polar grid lines \rightarrow MPI.
- Only little communication between threads at slice boundaries necessary.
- All threads have very similar workload.

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Numerical Implementation

Slicing the grid to use MPI

- Walltime of single-threaded simulations: ~ 2 days.
- Local cluster in Tübingen BinAC has nodes with 28 CPUs.
- \rightarrow Walltime $\sim 1.5 - 2.5$ hours.

Numerical Implementation

Alternative: Multi-grid implementation

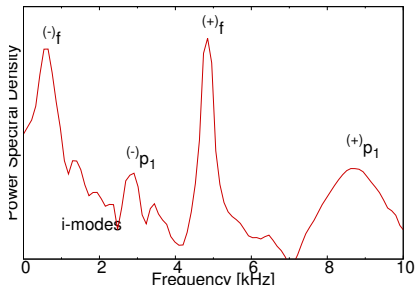
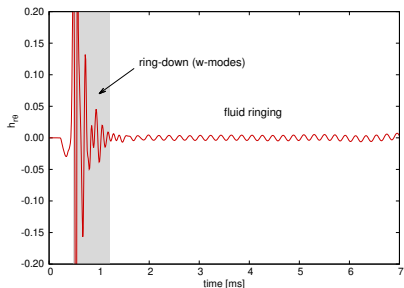
- Characteristic speeds of neutron star fluid and spacetime are quite different (c_s vs $c = 1$).
- Introduce individual grids for each “fluid”.
 - Neutron star fluid gets grid shown in the beginning.
 - Spacetime grid is almost uniform with slightly increasing spacing toward the outer edge.
- Need to interpolate between those grids at each (intermediate) time step.
- → Time step Δt can be chosen ~ 5 times larger.
→ Walltime for single-threaded run now ~ 5 -6 hours.

Numerical Implementation

Alternative: Multi-grid implementation

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Characteristic example of time signal



EoS SLy	$M = 2.02 M_{\odot}$
$\epsilon_c = 1.2e15 \text{ g/cm}^3$	$\Omega = 1.3 \text{ kHz}$
$r_e/r_p = 0.56$	$\Omega/\Omega_K = 0.98$

The fundamental mode of a NS

The *f*-mode (fundamental) mode of a NS

- Fundamental oscillation mode of a NS; present also in constant-density models.
- Typical frequency: 1 – 3 kHz.
- The quadrupolar ($l = |m| = 2$) *f*-mode is potentially a strong emitter of GWs.
- Could be excited during late binary inspiral and impact the phase of the waveform.

Spectrum of NSs is very rich and features various other modes: *p*-modes, *w*-modes, *s*-modes, *i*-modes, ...

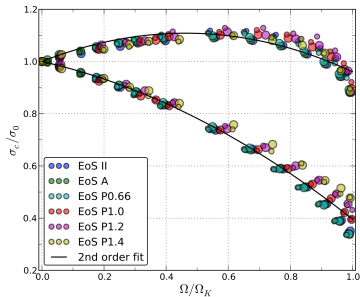
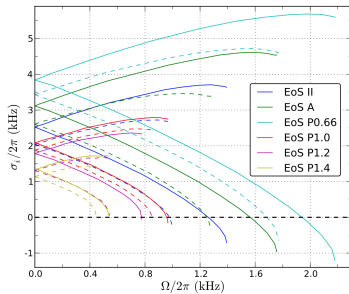
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f-mode frequency in the Cowling Approximation



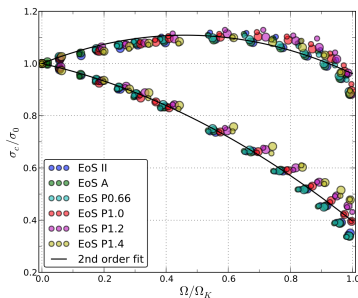
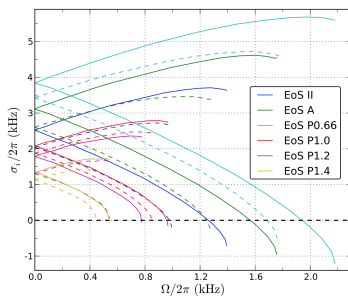
Gaertig, Kokkotas (2008, 2011, 2011) Doneva, Gaertig, Kokkotas, Krüger (2013)

Fitting
 formulae:

$$\frac{\sigma_c^s}{\sigma_0} = 1 - 0.235 \left(\frac{\Omega}{\Omega_K} \right) - 0.358 \left(\frac{\Omega}{\Omega_K} \right)^2$$

$$\frac{\sigma_c^u}{\sigma_0} = 1 + 0.402 \left(\frac{\Omega}{\Omega_K} \right) - 0.406 \left(\frac{\Omega}{\Omega_K} \right)^2$$

f-mode frequency in the Cowling Approximation



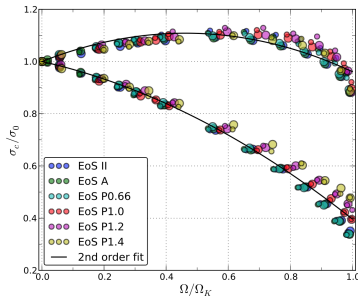
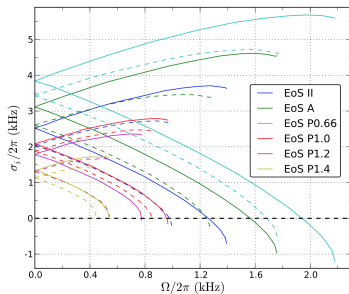
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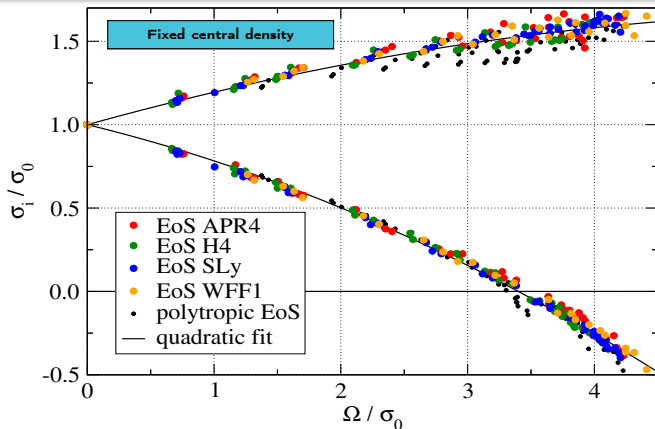
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20-40% error
 in frequencies

(due to neglecting dynamics of
 spacetime)

Fitting formulae – σ/σ_0 vs. Ω/σ_0



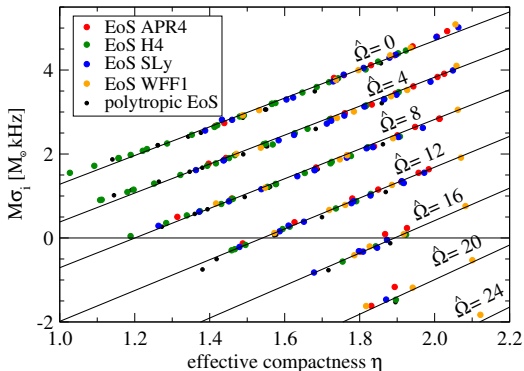
Zeeman-like splitting of *f*-mode, here shown for $l = |m| = 2$.

$$\frac{\sigma^u}{\sigma_0} = 1 - 0.193 \left(\frac{\Omega}{\sigma_0} \right) - 0.0294 \left(\frac{\Omega}{\sigma_0} \right)^2$$

$$\frac{\sigma^s}{\sigma_0} = 1 + 0.220 \left(\frac{\Omega}{\sigma_0} \right) - 0.0170 \left(\frac{\Omega}{\sigma_0} \right)^2$$

f-mode “changes sign”, i.e., becomes CFS-unstable when $\Omega \gtrsim 3.4\sigma_0$.

Fitting formulae – $M\sigma$ vs. $\hat{\Omega}$ vs η



$$M\sigma_i^u = \left(-2.14 - 0.201\hat{\Omega} - 7.68 \cdot 10^{-3}\hat{\Omega}^2 \right) + \left(3.42 + 1.75 \cdot 10^{-3}\hat{\Omega}^2 \right) \eta$$

$$\hat{\Omega} = M\Omega$$

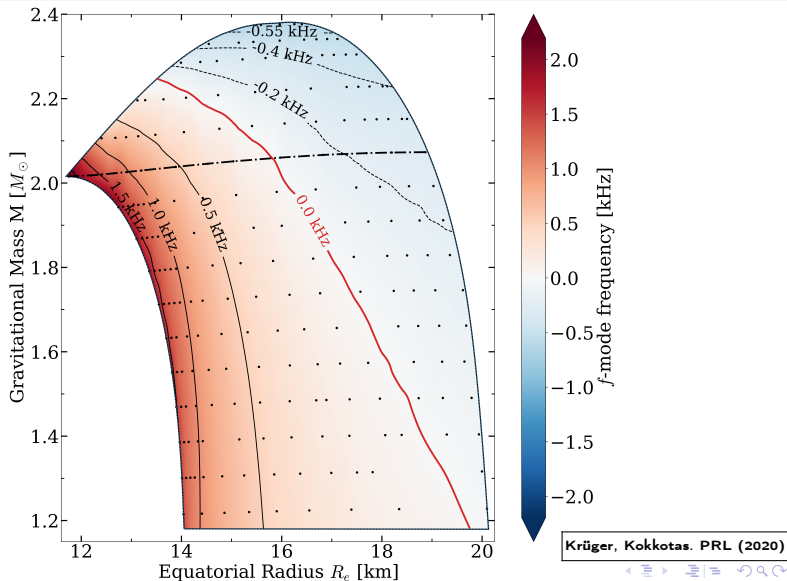
$$M\sigma_i^s = \left(-2.14 + 0.220\hat{\Omega} - 14.6 \cdot 10^{-3}\hat{\Omega}^2 \right) + \left(3.42 + 6.86 \cdot 10^{-3}\hat{\Omega}^2 \right) \eta$$

$$\eta = \sqrt{M^3/I}$$

Non-rotating case: Lau, Leung, Lin (2010)

Cowling case: Doneva, Kokkotas (2015)

Overview of Entire (Cold) EoS H4



Summary

- Written a time evolution code from scratch to evolve perturbations of *fast* rotating neutron stars in time.
- Evolution equation are supposed to be contributed to the ETK at some point.
- With MPI parallelisation or multi-grid approach, walltime is conveniently small (few hours).
- Determined *f*-mode frequency and onset of CFS-instability of rapidly rotating NSs in full GR without approximation.
- Provided asteroseismological relation for *f*-mode frequency.
- Relevant for various astrophysical scenarios: continuous sources, inspiral + post-merger phase in binary mergers, ...
- Universal relation can be used in cheap EOS inference codes and numerous other applications, ...

*Thank you for your
attention!*

Questions?

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