Numerical methods in General Relativity (and possible other theories of gravity...)

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((O))VIRGD

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Contents:

 \rightarrow Don't forget the details: EoS and numerical simulations.

 \rightarrow Numerical vs physical resistivity: MIRK methods for the RRMHD equations.

 \rightarrow Adding more ingredients: MIRK methods for the neutrino transport equations (M1 scheme) in supernovae simulations.

 \rightarrow Numerical resolution of elliptic equations: at least for initial data.

 \rightarrow Your hyperbolic sector has (gravitational) waves: RK methods and stability.

 \rightarrow Black hole singularities in your numerical grid.

And everything is **coupled**...

GW signal divided in three distinct phases: inspiral, merger, postmerger oscillations $\frac{1}{0}$ $\frac{1}{0}$



Triplet of frequencies identified in GW spectrum.

0.2

0.1

-0.1

-0.2

h. [r/M_{sun}]

Future GW observations may extract $f_2 \& f_0$ GW **asteroseismology** with post-merger remnant to **constrain the EOS**. $f_{ ext{peak}} = f_2$ fundamental I=m=2 f-mode oscillation $f_- = f_2 - f_0$ quasilinear $f_+ = f_2 + f_0$ combination tones

f(kHz)

3

2

Constraining the EoS

Bauswein+ (2012): peak frequency of $(1.35-1.35)M_{\odot}$ BNS merger correlates with the radius of a $1.6M_{\odot}$ nonrotating NS in an EoS-independent manner.

Similar relations found for other binary masses and other radii (R_{1.35} or R_{1.8})



A potential measurement of f_{peak} from postmerger signal can be used to obtain an estimate on R_{1.6}, a quantity that can be used to directly constrain the EoS.

The smaller the scatter (<200 m) the smaller the error in radius measurement.

BNS mergers with hadron-quark phase transitions

Bauswein+ (2019) identified an observable imprint of a first-order hadron-quark PT at supranuclear densities on the GW emission of BNS mergers.

Dominant postmerger GW frequency f_{peak} may exhibit a significant deviation from an empirical relation between f_{peak} and tidal deformability if a first-order PT leads to the formation of a stable extended quark matter core in the postmerger remnant.



(Bauswein+ 2019)

EoS from Wroclaw group (Fischer+ 2018, Bastian+ 2018)

- \rightarrow Could this shift in the frequency be explained by a different reason?
- \rightarrow Could the anomalous dynamics be triggered by a non-convex EoS?

Non-convexity of isentropes in the p-rho plane: compressive rarefaction waves and expansive shocks. Classical fluid dynamics, the convexity is determined by the fundamental derivative:

$$\mathcal{G}_{(C)} \equiv -\frac{1}{2} V \frac{\frac{\partial^2 p}{\partial V^2}}{\frac{\partial p}{\partial V}} \qquad \mathcal{G}_{(C)} = 1 + \frac{\partial \log c_s}{\partial \log \rho} = \frac{1}{2} \left(1 + \Gamma_1 + \frac{\partial \log \Gamma_1}{\partial \log \rho} \right)$$
(all derivatives computed at constant entropy)

(all derivatives computed at constant entropy)

 Γ_1 adiabatic index. Characterizes stiffness of EoS at a given density, showing a local maximum above nuclear matter density.

Bethe (1942), Zel'dovich (1946) and Thompson (1971) (BZT) fluids exhibit negative values for the fundamental derivative.

Relativistic fluids [Ibáñez, Cordero-Carrión et al. (2013)]: extension to the relativistic case, introducing the relativistic fundamental derivative:

$$G_{(R)} = G_{(C)} - \frac{5}{2} c_{s_{(R)}}^2$$

EoS broadly used in

numerical simulations of CCSN and BNS mergers display regions where adiabatic index is not monotonic \rightarrow non-convex regions.

Good news: you can use standard numerical methods.

Illustrative example: effect on BNS mergers with a phenomenological toy-model EoS





This is not really the end of the story [Ibáñez, Cordero-Carrión et al. (2015)]: the relativistic fundamental derivative has corrections due to the presence of intense magnetic fiels.

where

$$F := \frac{3}{2} W_s^{-4} \left(\frac{c_a^2 / a_s^2 - R}{1 - R} \right).$$

In the previous expressions, $R := \frac{B^2}{\mathcal{E}a^2}$, and $c_a^2 := \frac{b^2}{\mathcal{E}}$

Also, take care about the treatment of thermal effects in postmerger BNS merger with hybrid EoS vs tabulated EoS:



·· Magnetic fields are key in accretion disks, AGN, relativistic jets, compact objects.

·· A consistent treatment is necessary to avoid numerical resistivity.

·· Hyperbolic equations + constraints (divergence of magnetic and electric fields) \rightarrow augmented system of hyperbolic equations [Komissarov 2007] (velocity, density, electric and magnetic fields, two additional scalar equations).

•• Structure of the equations: $\partial_t E^j = S^j_E - \sigma W[E^j + (\nu \times B)^j - (\nu_l E^l)\nu^j] = \tilde{S}^j_E$,

$$\partial_t B^j = S^j_B,$$

$$\partial_t Y = S_Y,$$

·· Avoid numerical instabilities due to stiff source term in the evolution equation for the electric field for high conductivities.

·· PIRK methods to deal with wave-like equations (electric and magnetic fields) for low-order methods.

[I. C.-C. and P. Cerdá-Durán, arXiv:1211.5930 (2012)]

[I. C.-C. and P. Cerdá-Durán, SEMA SIMAI Springer Series Vol. 4 (2014)]

$$\left\{ \begin{array}{ll} u_t = \mathcal{L}_1(u,v), \\ v_t = \mathcal{L}_2(u) + \mathcal{L}_3(u,v), \end{array} \right. \quad \text{linearization} \quad \left\{ \begin{array}{ll} u_t = \bar{\alpha}_1 u + \bar{\alpha}_2 v, \\ v_t = \bar{\gamma}_1 u + \bar{\gamma}_2 v + \bar{\lambda} u, \\ v_t = \bar{\gamma}_1 u + \bar{\gamma}_2 v + \bar{\lambda} u, \end{array} \right. \\ \text{wave-like eq.:} \quad (\bar{\alpha}_1 - \bar{\gamma}_2)^2 + 4\bar{\alpha}_2(\bar{\gamma}_1 + \bar{\lambda}) < 0. \end{array} \right.$$

·· Ideal limit: infinite conductivity and $E^i = -(\boldsymbol{v} \times \boldsymbol{B})^i$.

·· Implicit / Semi-implicit methods include additional recoveries of primitive variables from conserved ones [Palenzuela et al. 2009] \rightarrow potential convergence problems, additional computational cost.

·· First-order MIRK method (stability criteria to select coefficients):

$$\begin{split} E^{j}|_{n+1} &= E^{j}|_{n} + \Delta t \, S^{j}_{E}|_{n} - \Delta t \, \overline{\sigma}|_{n} \, [c_{1}E^{j}|_{n} + (1-c_{1})E^{j}|_{n+1} + c_{2}(\nu \times B)^{j}|_{n} \\ &+ (1-c_{2})(\nu|_{n} \times B|_{n+1})^{j} - c_{3}\nu^{j}|_{n}\nu_{l}|_{n}E^{l}|_{n} - (1-c_{3})\nu^{j}|_{n}\nu_{l}|_{n}E^{l}|_{n+1}], \\ B^{j}|_{n+1} &= B^{j}|_{n} + \Delta t \, S^{j}_{B}|_{n}, \end{split}$$

$$Y|_{n+1} = Y|_n + \Delta t \, S_Y|_n.$$

 \rightarrow Pure explicit method with an effective time step:

$$E^{i}|_{n+1} = E^{i}|_{n} + \frac{\Delta t}{1 + \Delta t \,\overline{\sigma}|_{n}} \left[S^{i}_{E}|_{n} + \overline{\sigma}|_{n} E^{l}|_{n} \left(v^{i}|_{n} v_{l}|_{n} - \delta^{i}_{l} \right) - \overline{\sigma}|_{n} \left(v|_{n} \times B|_{n+1} \right)^{i} \right]$$

·· Analogous derivation for the two-stage second-order MIRK method.

·· Applications: Self-similar current sheet: 1D problem; CFL=0.8; initial data at t=1:

$$\boldsymbol{v} = (v^x, 0, 0), \, \boldsymbol{E} = (0, 0, 0), \, \boldsymbol{B} = (0, B^y(x, t = 1), 0), \, B_e^y(x, t) = \operatorname{erf}\left(\frac{x}{2}\sqrt{\frac{\sigma}{t}}\right) \qquad \sigma = 10^3$$



Stable simulations with zero and non-zero velocities ($v_x = 0.1$), first and second-order methods.

·· Applications: Circular Polarized Alfvén waves: 1D; full system (including matter); EoS for an ideal fluid, $\Gamma = 4/3$; $\rho(x, 0) = p(x, 0) = 1$; CFL=0.3 \rightarrow 0.7; $\sigma = 10^8$; KO term;

 $\boldsymbol{B}(x,0) = B_0 (1,\cos(kx),\sin(kx)),$

with $k = 2\pi$ and $B_0 = 1.1547$, and

 $\boldsymbol{E}(x,0) = -\boldsymbol{v}(x,0) \times \boldsymbol{B}(x,0),$

with $v(x, 0) = \frac{v_A}{B_0}(0, B^y(x, 0), B^z(x, 0))$ and $v_A = 0.423695$

Stable simulations, with first and second-order methods.

Exact solution refers to the one in the stiff limit (close enough for very high conductivities).





·· The explosion mechanism of CCSNe cannot be understood without a detailed account of the generation and transport of neutrinos.

·· Boltzmann equation (7D problem) \rightarrow momentum-space integration of the distribution function. Truncation: n=0 or diffusion; n=1, quite used – M1 scheme.

 $\cdot\cdot$ Optically thick regime \rightarrow very different timescales of different interactions and stiff source term for very high opacities.

•• Structure of the equations:
$$\partial_t E = S_E + C^{(0)}, \quad C^{(0)} = c \kappa_a (E_{eq} - E),$$

 $\partial_t F^i = S_F^i + C^{(1),i}, \quad C^{(1),i} = -c \kappa_{tra} F^i.$

·· IMEX-like method [Just et al. 2015]. Complexity of applying IMEX methods: opacities, equilibrium profile.

·· Similar derivation of MIRK methods, taking into account stability and limit at the stiff limit: effective time-step when written similar to explicit methods.

$$\rightarrow \text{First-order:} \quad E^{n+1} = E^n + \frac{\Delta t}{1 + \Delta t \kappa^n} \left[S_E^n + \kappa^n (E_{eq}^n - E^n) \right]$$

$$(F^i)^{n+1} = (F^i)^n + \frac{\Delta t}{1 + \Delta t \kappa'^n} \left[(S_F^i)^n - \kappa'^n (F^i)^n \right]$$

$$\rightarrow \text{Second-order:} \quad (\text{similar expressions for F}) \qquad E^{(1)} = E^n + \Delta t \left[S_E^n + a \kappa^n (E_{eq}^n - E^n) + (1 - a) \kappa^n (E_{eq}^n - E^n) + (1 - a) \kappa^n (E_{eq}^n - E^{(1)}) \right],$$

$$F^{n+1} = \frac{1}{2} [E^{(1)} + E^n] + \Delta t \left[\frac{1}{2} S_E^{(1)} + d' \kappa^{(1)} (E_{eq}^{(1)} - E^{(1)}) + \frac{1 - a}{2} \kappa^{(1)} (E_{eq}^{(1)} - E^n) + \frac{1 - a}{2} \kappa^{(1)} (E_{eq}^{(1)} - E^n) + \frac{(a - t)}{2} \kappa^{(1)} (E_{eq}^{(1)} - E^n) + \frac{(a - t)}{2} \kappa^{(1)} (E_{eq}^{(1)} - E^n)$$

 $+ \left(\frac{1}{2} - a\right) \kappa^{(2)} \left(E_{eq}^{(2)} - E^{(1)}\right),$

·· Applications: Simple test: test 1 from [J.A. Pons, J.M. Ibáñez, J.A. Miralles, MNRAS 317, 550-562 (2000)]:

Difussion limit (P = p E = E/3) in spherical symmetry (1D problem) and $\kappa_a = 0$:

$$\partial_t E + \partial_r F + \frac{F}{r} = -c \kappa_a \left(E_{eq} - E \right)$$

$$\partial_t F + \partial_r P + \frac{3P - E}{r} = -c \kappa_{tra} F$$
0

Analytical solution, c=1 (geometrical units):

$$E(t,r) = \left(\frac{\kappa_{\rm tra}}{t}\right)^{3/2} \exp\left(-\frac{3\kappa_{\rm tra}r^2}{4t}\right) \qquad F(t,r) = \frac{r}{2t}E(t,r)$$

··· Applications: Simple test: MIRK1: a=b=0. MIRK2: a=b=1/2, a'=(a-1)/2, b'=(b-1)/2. Similar results.

MIRK1 4.1606 1.4709 1.7560 1.9217 1.9835 MIRK2 4.1602 1.4704 1.7553 1.9202 1.9804

Numerical flux: Godunov method







CFL=1.

Exact solution used at boundary conditions and initial data at t=1.



·· Applications: Core-collapse simulation with all the important interactions that dominate the dynamics (see more details in arXiv reference).

·· Applications: Core-collapse simulation:

 \rightarrow Stable and accurate results using 1st and 2nd MIRK methods vs reference.

 \rightarrow Direct relation between the values of the coefficients and stability + correct values at the stiff limit (non-smooth variables).

 \rightarrow Slight modifications from pure explicit methods and similar computational cost, independently of the complexity of opacities and equilibrium profile.

General idea MIRK methods: Hyperbolic equations with stiff source terms that can be somehow linearized with respect to the conserved (evolved) variables:

$$\partial_t U + \partial_i F^i(U) = S(U), \qquad S(U) = S_E(U) + \frac{1}{\epsilon} [S_I(U) - U_0];$$
$$S_I(U) = \sum_{i=1}^n G_i(U) U^i.$$

Only the conserved variables are evaluated implicitly. More examples: GR force-free electrodynamics, rarefied gases problems, shallow water equations with friction...

Constrained evolution schemes: SOLVE the evolution and constraint equations on each spatial hypersurface: CFC, FCF...

CFC (Conformally Flat Condition) Isenberg 1979/2008, Wilson and Mathews 1989: conformally flat spatial 3-metric; gravitational radiation encoded in the neglected terms.

• Exact in spherical symmetry (CC 2011). Very accurate for axisymmetric rotating NSs.

• Set of elliptic equations for the metric variables (including the constraint equations): lapse, shift, conformal factor.

· Shares similar structure with XCTS, used in generation of initial data.

• Original formulation suffers from a non-local uniqueness pathology at extreme curvature or very high density regimes. This problem is solved with the introduction of auxiliary variables [Cordero-Carrión et al., 2009]. See talk in Einstein toolkit meeting 2019.

FCF (Fully Constrained Formulation) Bonazzola et al., 2004:

· Maximal slicing and Dirac generalized gauge.

· Similar elliptic system as in CFC with additional source terms + hyperbolic new sector encoding the GW radiation.

Elliptic equations are more stable but difficult to solve and parallelize:

· Initial data talk by P. Grandclément \rightarrow spectral methods with Lorene library, commonly used.

· Chevishev-Jacobi methods (CJM) (Adsuara et al. 2017): parallelization is possible.

Hyperbolic equations: PIRK methods developed for the hyperbolic FCF sector and afterwards applied to other (free evolution) formulations (BSSN).

Coupled with matter content...

Black hole singularities: infinite quantities cannot be treated numerically

 \rightarrow Remap somehow your space-time: punture method commonly used in free evolution schemes (BSSN) and BBH simulations.

 \rightarrow Excise a topological sphere from your numerical grid containing the black hole singularity:

· Pretorius 2005 simulations used GHG and excision.

• Excision can be combined with the CFC formulation [Cordero-Carrión et al., 2014].

This idea with a small modification has been recently used in core-collapse simulations [B. Sykes et al., 2023].

More ideas are about to come in the 1D case.

More research is needed in the 2D / 3D cases.

