Introduction to Hydrodynamics

Bruno Giacomazzo
University of Milano-Bicocca (Milan, Italy)

www.brunogiacomazzo.org

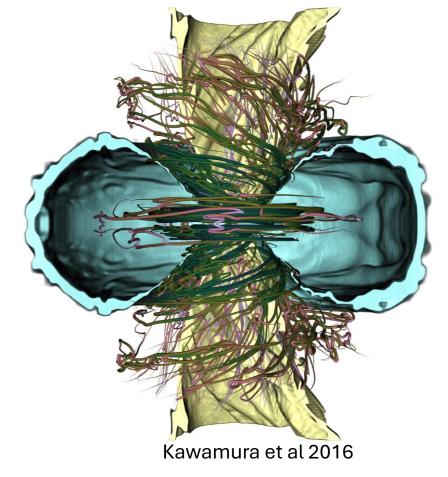






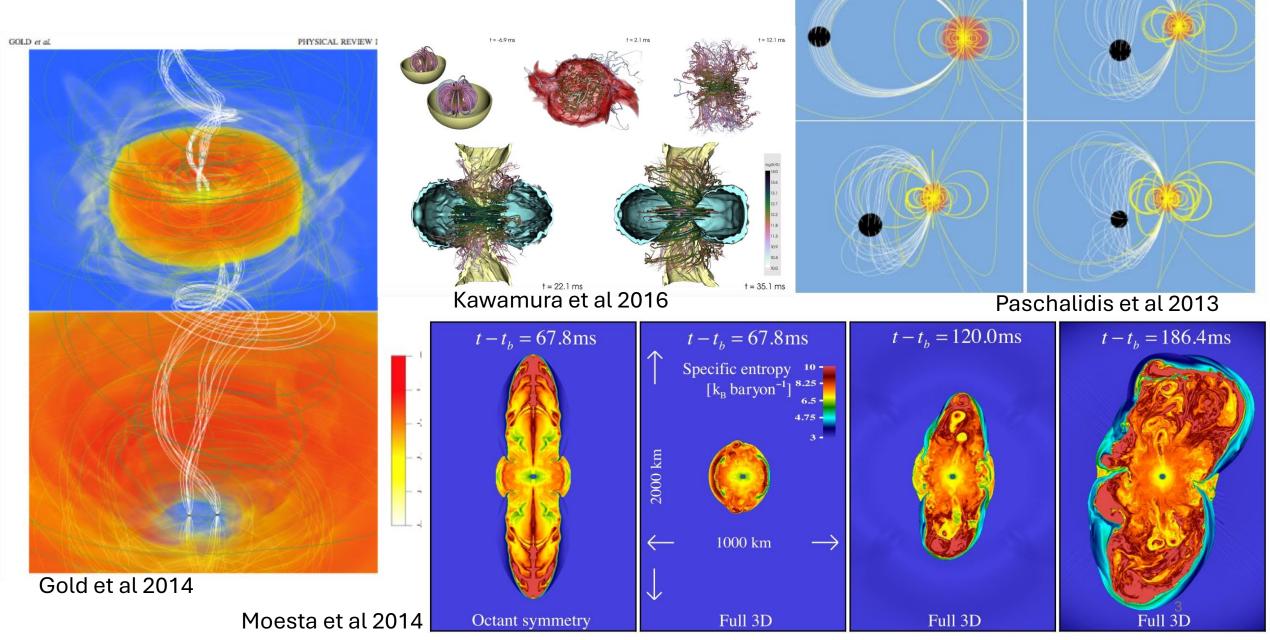
General Relativity and Astrophysics

- Binary Black Hole Mergers
- Binary Neutron Star Mergers
- Neutron Star Black Hole Mergers
- Supernovae
- Accretion Disks
- Cosmology



In all these scenarios general relativity plays a fundamental role.

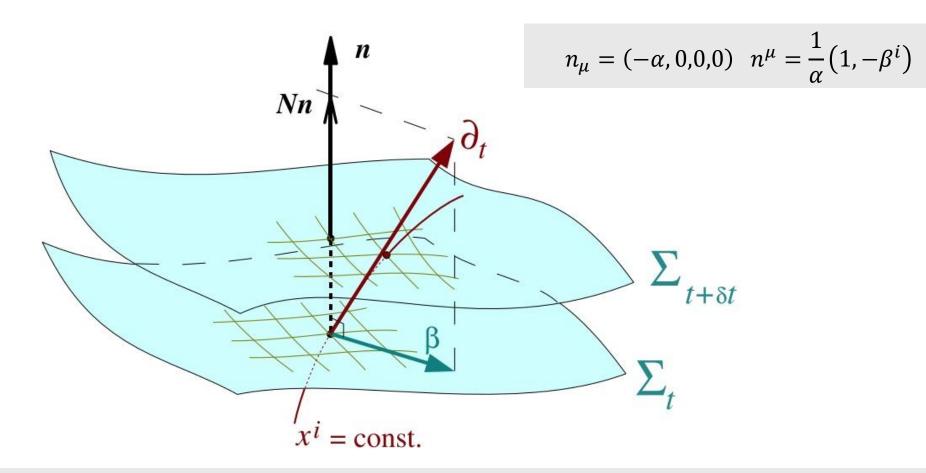
GR(M)HD APPLICATIONS



GRHD equations

The metric in the 3+1 form

$$G = c = 1$$



$$ds^2 = g_{\mu\nu}dx^{\mu}dx^{\nu} = -\alpha^2dt^2 + \gamma_{ij}(dx^i + \beta^i dt)(dx^j + \beta^j dt)$$

Equations

Einstein Equations

$$G_{\mu\nu} = R_{\mu\nu} - \frac{1}{2}g_{\mu\nu}R = 8\pi T_{\mu\nu}$$

Hydro Equations

$$egin{aligned}
abla_{\mu} T^{\mu
u} &= 0 \\

abla_{\mu} J^{\mu} &= 0 \\
J^{\mu} &=
ho u^{\mu} \\
T^{\mu
u} &=
ho h u^{\mu} u^{
u} + p g^{\mu
u}
\end{aligned}$$

 $h \equiv 1 + \epsilon + P/\rho$

Eulerian Observer

- It moves with 4-velocity n
- u^{μ} is the four-velocity of the fluid
- $u^{\mu} \equiv \frac{dx^{\mu}}{d\tau}$ and the velocity is $v^i = \frac{dx^i}{dt} = \frac{dx^i}{d\tau} \frac{d\tau}{dt} = \frac{u^i}{u^t}$
- In 3+1 GR, the Eulerian observer will measure the following velocity:

$$v^i \equiv rac{\gamma_\mu^i u^\mu}{W}$$
 $\gamma_\mu^i \equiv g_\mu^i + n^i n_\mu$

where W = αu^t is the Lorentz factor, i.e., $W = \frac{1}{\sqrt{1-v^i v_i}} = \frac{1}{\sqrt{1-v^2}}$

Eulerian Observer

• Therefore,
$$v^i=\frac{1}{W}\big(g^i_\mu+n^in_\mu\big)u^\mu=\frac{1}{W}\Big(u^i+\frac{\beta^i}{\alpha}\alpha u^t\Big)=\frac{u^i}{W}+\frac{\beta^i}{\alpha}$$

$$v^i = \frac{u^i}{W} + \frac{\beta^i}{\alpha}$$

$$v_i = \frac{u_i}{W}$$

Conservation of Rest Mass

$$\nabla_{\mu}J^{\mu} = 0 \rightarrow \nabla_{\mu}(\rho u^{\mu}) = 0 \rightarrow$$

$$\frac{1}{\sqrt{-g}} \partial_{\mu} (\sqrt{-g} \rho \mathbf{u}^{\mu}) = 0$$

$$\partial_t (\alpha \sqrt{\gamma} \rho u^t) + \partial_i (\alpha \sqrt{\gamma} \rho u^i) = 0$$

$$\partial_t(D) + \partial_i \left[\sqrt{\gamma} \left(\alpha v^i - \beta^i \right) W \rho \right] = 0$$

$$\partial_t(D) + \partial_i \big[D \big(\alpha v^i - \beta^i \big) \big] = 0$$

$$D \equiv \sqrt{\gamma} \rho \alpha u^t = \sqrt{\gamma} \rho W$$

$$u^i = \left(v^i - \frac{\beta^i}{\alpha}\right) W$$

Conservation of Energy and Momentum

$$\nabla_{\mu}T^{\mu\nu}=0$$

$$g^{\nu\lambda} \left[\frac{1}{\sqrt{-g}} \partial_{\mu} \left(\sqrt{-g} T_{\lambda}^{\mu} \right) - \frac{1}{2} T^{\alpha\beta} \partial_{\lambda} g_{\alpha\beta} \right] = 0$$

$$\frac{1}{\sqrt{-g}} \partial_{\mu} \left(\sqrt{-g} T_{\lambda}^{\mu} \right) = \frac{1}{2} T^{\alpha \beta} \partial_{\lambda} g_{\alpha \beta}$$

$$\partial_t \left(\sqrt{\gamma} \alpha T_{\lambda}^0 \right) + \partial_i \left(\sqrt{\gamma} \alpha T_{\lambda}^i \right) = \frac{\sqrt{-g}}{2} T^{\alpha\beta} \partial_{\lambda} g_{\alpha\beta}$$

GRHD Equations

The system of equations is now written in a flux-conservative form (Valencia formulation, Banyuls et al 1997, Anton et al 2006):

$$\partial_t \mathbf{U} + \partial_i \mathbf{F}^i = \mathbf{S}$$

where $m{U}$ is the vector of conserved variables, $m{F}^i$ the fluxes, and $m{S}$ the source terms.

For example, let's take the conservation of rest mass:

$$\partial_t(D) + \partial_i [D(\alpha v^i - \beta^i)] = 0$$

$$\tilde{v}^i \equiv v^i - \beta^i / \alpha$$

then
$$U = D = \sqrt{\gamma}\rho W$$
, $F^i = D(\alpha v^i - \beta^i) = \alpha D\tilde{v}^i$, $S = 0$.

GRHD Equations

$$\boldsymbol{U} = (D, S_j, \tau)$$

$$D = \sqrt{\gamma} \rho W$$

$$S_j = \sqrt{\gamma} (\rho h W^2 v_j)$$

$$\tau = \sqrt{\gamma} (\rho h W^2 - P) - D$$

In the non-relativistic case, $D \to \rho$, $S_j \to \rho v_j$, $\tau \to \rho \epsilon$

GRHD Equations

$$F^{i} = \alpha \times \begin{bmatrix} D\tilde{v}^{i} \\ S_{j}\tilde{v}^{i} + \sqrt{\gamma}P\delta_{j}^{i} \\ \tau\tilde{v}^{i} + \sqrt{\gamma}Pv^{i} \end{bmatrix}$$

$$S = \alpha \sqrt{\gamma} \times \begin{bmatrix} 0 \\ T^{\mu\nu} \left(\frac{\partial g_{\nu j}}{\partial x^{\mu}} - \Gamma^{\lambda}_{\mu\nu} g_{\lambda j} \right) \\ \alpha \left(T^{\mu 0} \frac{\partial \ln \alpha}{\partial x^{\mu}} - T^{\mu\nu} \Gamma^{0}_{\mu\nu} \right) \end{bmatrix}$$

The importance of flux-conservative Form

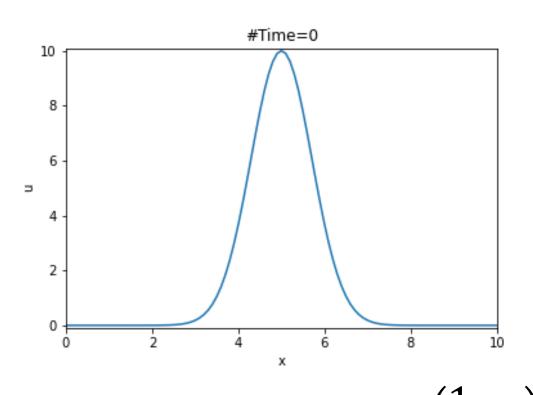
• Lax-Wendroff Theorem (1960): If a consistent numerical method written in a flux conservative form converges to a function u(x,t) for dx that goes to zero, then u(x,t) is a solution of the conservation law*.

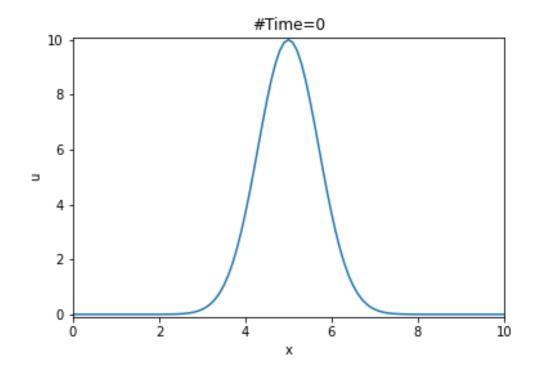
• Hou-LeFlock Theorem (1994): non-conservative schemes do not converge to the correct solution if a shock wave is present in the flow.

*note that the proper formulation of the Lax-Wendroff theorem is slightly different from what reported here (but for our purposes it is OK).

Burgers' Equation

FC NFC





$$\frac{\partial u}{\partial t} + \frac{\partial \left(\frac{1}{2}u^2\right)}{\partial x} = \frac{\partial u}{\partial t} + u\frac{\partial u}{\partial x} = 0$$

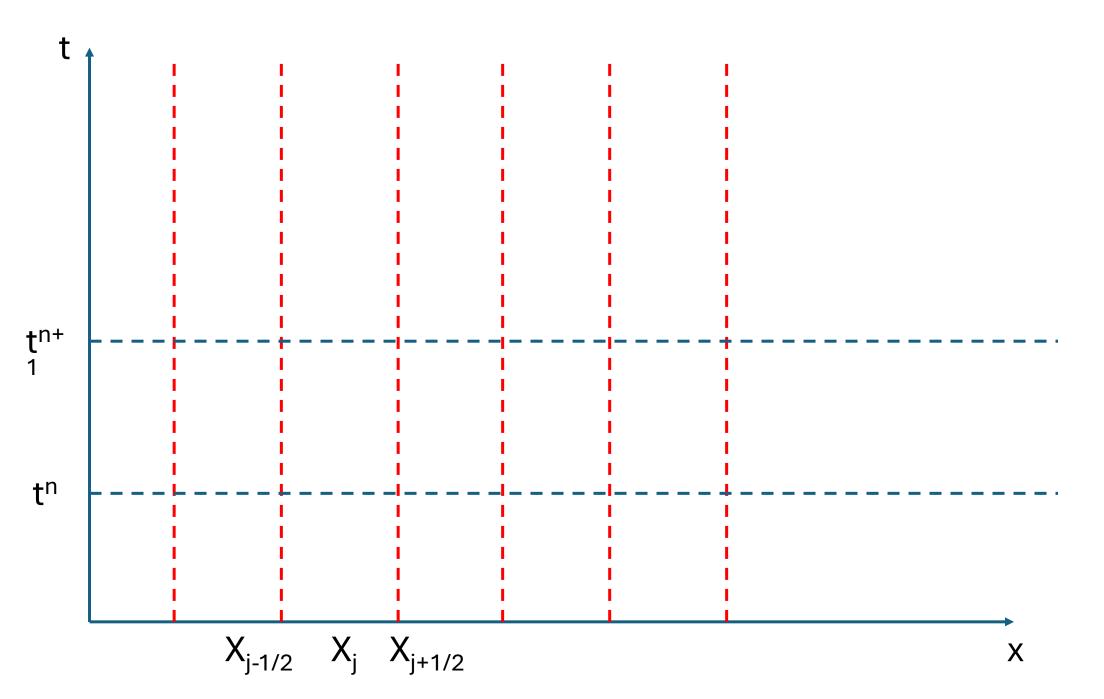
WHAT IS A FLUX-CONSERVATIVE FORM?

$$\frac{\partial u}{\partial t} + \frac{\partial f(u)}{\partial x} = 0$$

Let's solve it on a numerical grid

$$x_j = j \times \Delta x, j = 0, \dots, J-1$$

 $t^n = n \times \Delta t, n = 0, \dots, N-1$



We now take the integral in t and x

$$\int_{x_{j-1/2}}^{x_{j+1/2}} \int_{t^n}^{t^{n+1}} \frac{\partial u}{\partial t} dx dt + \int_{t^n}^{t^{n+1}} \int_{x_{j-1/2}}^{x_{j+1/2}} \frac{\partial f(u)}{\partial x} dx dt = 0$$

$$\downarrow \qquad \qquad \downarrow$$

$$\int_{x_{j-1/2}}^{x_{j+1/2}} \left[u(x, t^{n+1}) - u(x, t^n) \right] dx + \int_{t^n}^{t^{n+1}} \left[f\left(u(x_{j+1/2}, t) \right) - f\left(u(x_{j-1/2}, t) \right) \right] dt = 0$$

We then divide by Δx

$$\frac{1}{\Delta x} \int_{x_{j-1/2}}^{x_{j+1/2}} u(x, t^{n+1}) dx = \frac{1}{\Delta x} \int_{x_{j-1/2}}^{x_{j+1/2}} u(x, t^n) dx
- \frac{1}{\Delta x} \left[\int_{t^n}^{t^{n+1}} f\left(u(x_{j+1/2}, t)\right) dt - \int_{t^n}^{t^{n+1}} f\left(u(x_{j-1/2}, t)\right) dt \right] = 0$$

$$\frac{1}{\Delta x} \int_{x_{j-1/2}}^{x_{j+1/2}} u(x, t^{n+1}) dx = \frac{1}{\Delta x} \int_{x_{j-1/2}}^{x_{j+1/2}} u(x, t^n) dx
- \frac{1}{\Delta x} \left[\int_{t^n}^{t^{n+1}} f\left(u(x_{j+1/2}, t)\right) dt - \int_{t^n}^{t^{n+1}} f\left(u(x_{j-1/2}, t)\right) dt \right] = 0$$

We now define

$$\tilde{u}_{j}^{n} \equiv \frac{1}{\Delta x} \int_{x_{j-1/2}}^{x_{j+1/2}} u(x, t^{n}) dx$$

$$\tilde{u}_{j}^{n+1} = \tilde{u}_{j}^{n} - \frac{1}{\Delta x} \left[\int_{t^{n}}^{t^{n+1}} f\left(u(x_{j+1/2}, t)\right) dt - \int_{t^{n}}^{t^{n+1}} f\left(u(x_{j-1/2}, t)\right) dt \right]$$

$$\tilde{u}_{j}^{n+1} = \tilde{u}_{j}^{n} - \frac{1}{\Delta x} \left[\int_{t^{n}}^{t^{n+1}} f\left(u(x_{j+1/2}, t)\right) dt - \int_{t^{n}}^{t^{n+1}} f\left(u(x_{j-1/2}, t)\right) dt \right]$$

Let's also define

$$f_{j+1/2}^n \equiv \frac{1}{\Delta t} \int_{t^n}^{t^{n+1}} f\left(u(x_{j+1/2}, t)\right) dt$$

And our equation reduces to:

$$\tilde{u}_{j}^{n+1} = \tilde{u}_{j}^{n} - \frac{\Delta t}{\Delta x} \left(f_{j+1/2}^{n} - f_{j-1/2}^{n} \right)$$

$$\tilde{u}_{j}^{n} \equiv \frac{1}{\Delta x} \int_{x_{j-1/2}}^{x_{j+1/2}} u(x, t^{n}) dx$$

$$f_{j+1/2}^{n} \equiv \frac{1}{\Delta t} \int_{t^{n}}^{t^{n+1}} f\left(u(x_{j+1/2}, t) \right) dt$$

a numerical method written in this way is said to be in flux conservative form.

Methods written in this form conserve \tilde{u} , indeed by summing over j

$$\Delta x \, \Sigma_{j=0}^{J-1} \, \tilde{u}_j^{n+1} = \Delta x \, \Sigma_{j=0}^{J-1} \, \tilde{u}_j^n - \Delta t \left(f_{J-1/2}^n - f_{-1/2}^n \right)$$

so \tilde{u} is conserved except for fluxes at the boundaries of the numerical domain.

How do we compute the flux?

A very simple choice could be

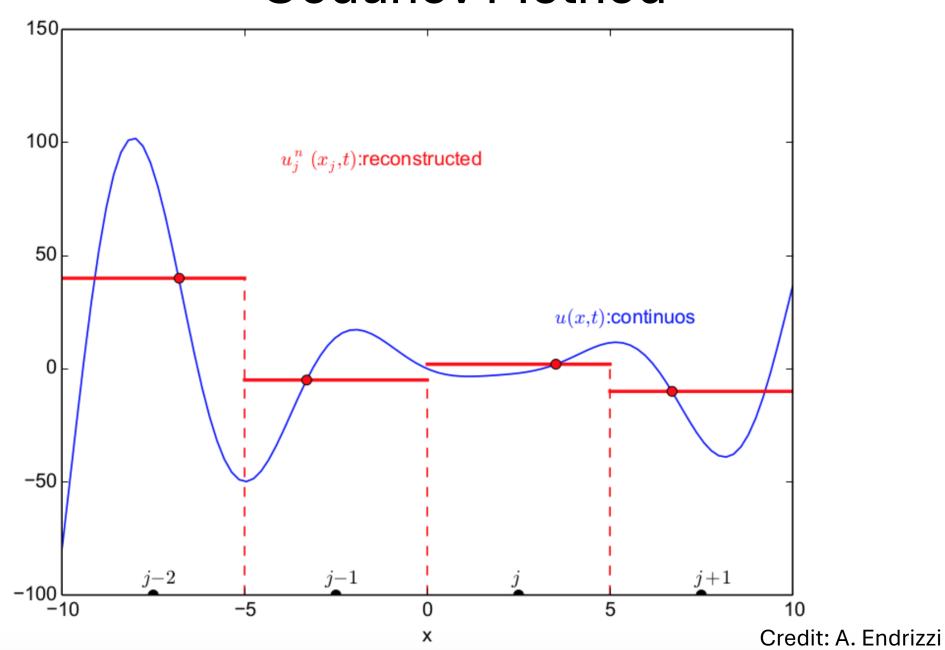
$$f_{j+1/2}^n = \frac{1}{2} \left[f(\tilde{u}_j^n) + f(\tilde{u}_{j+1}^n) \right]$$

$$\tilde{u}_{j}^{n+1} = \tilde{u}_{j}^{n} - \frac{\Delta t}{2\Delta x} \left[f(\tilde{u}_{j}^{n}) + f(\tilde{u}_{j+1}^{n}) - f(\tilde{u}_{j-1}^{n}) - f(\tilde{u}_{j}^{n}) \right]$$

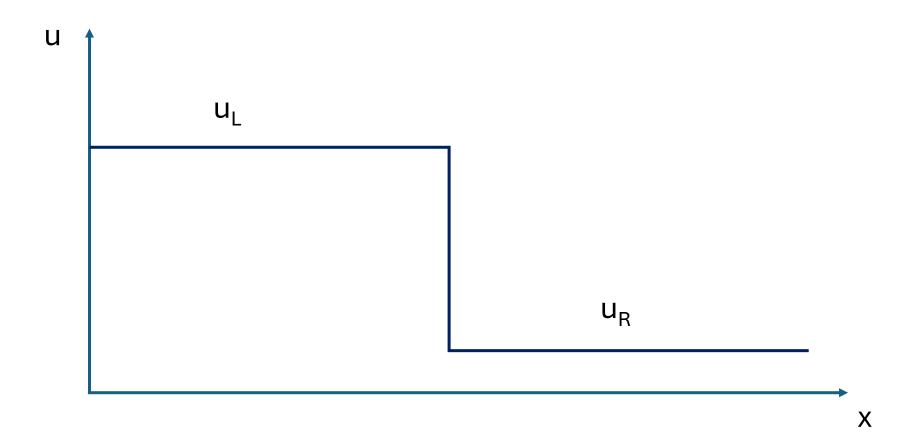
$$= \tilde{u}_{j}^{n} - \frac{\Delta t}{2\Delta x} \left[f(\tilde{u}_{j+1}^{n}) - f(\tilde{u}_{j-1}^{n}) \right]$$

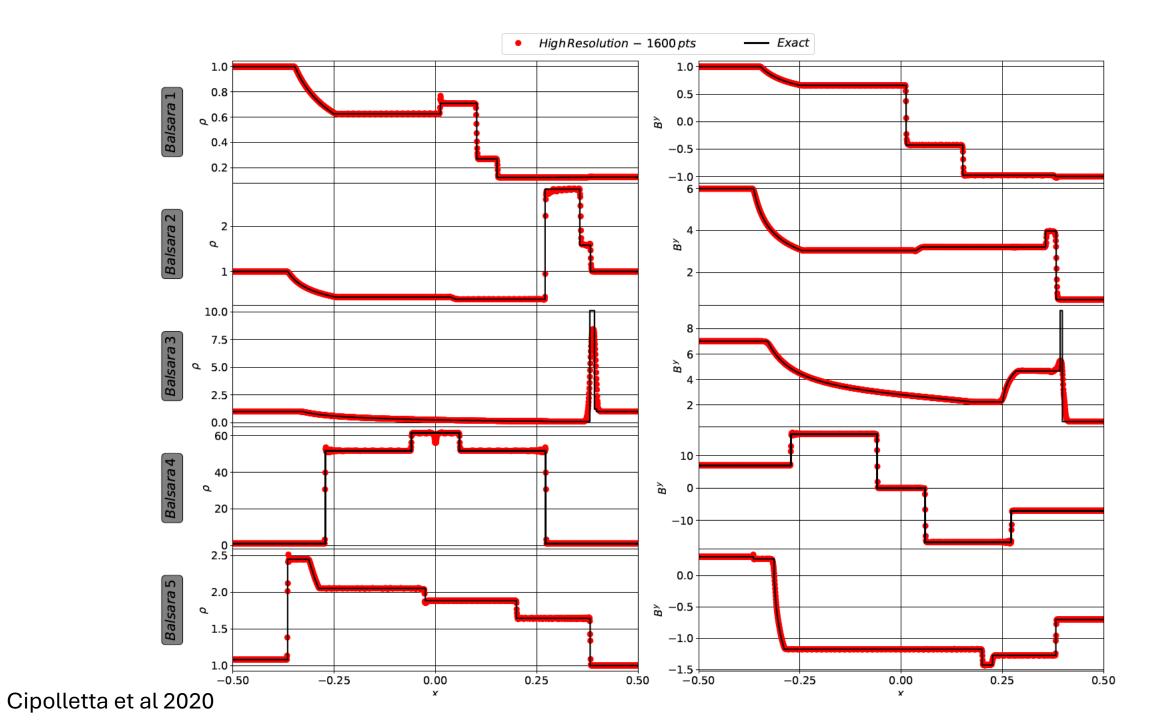
This method is known as FTCS and it is known to be unfortunately unstable...

Godunov Method



RIEMANN PROBLEM





RIEMANN PROBLEM

• By solving the Riemann problem one can compute

$$f_{j+1/2}^n \equiv \frac{1}{\Delta t} \int_{t^n}^{t^{n+1}} f\left(u(x_{j+1/2}, t)\right) dt$$

- My open-source exact RMHD Riemann solver can be downloaded here: https://github.com/bgiacoma/Exact_Riemann_Solver
- More computationally convenient to use approximate Riemann solvers, e.g., HLLE

HIGH RESOLUTION SHOCK-CAPTURING METHODS

• To increase the order, instead of assuming a step function one could use a piecewise linear function:

$$\tilde{u}(x, t^n) = \tilde{u}_j^n + \sigma_j^n (x - x_j) \quad \text{for } x_{j-1/2} < x < x_{j+1/2}$$

$$\sigma_j^n = \min \left(\frac{\tilde{u}_j^n - \tilde{u}_{j-1}^n}{\Delta x}, \frac{\tilde{u}_{j+1}^n - \tilde{u}_j^n}{\Delta x}\right)$$

$$\operatorname{minmod}(a, b) \equiv \begin{cases} a & \text{if } |a| < |b| \text{ and } ab > 0 \\ b & \text{if } |b| < |a| \text{ and } ab > 0 \\ 0 & \text{if } ab < 0 \end{cases}$$

or higher orders functions (e.g., PPM).

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