

Flavour Tagging with Graph Neural Networks with the ATLAS experiment Waltteri Leinonen on behalf of the ATLAS Collaboration

Introduction to ATLAS Physics

The ATLAS detector is a general-purpose barrel detector located at the LHC It studies high-energy fundamental particles such as the **Top quark**, and the **Higgs boson**. While these particles cannot be *directly detected* ($\tau < 10^{-20} s$), their decay products and fractions are predicted by the Standard Model [6].

Source [6]	Mass	Lifetimes	Decay-mode	Branching Fraction
Top Quark	173.5 GeV	$\tau < 10^{-24} s$	$t \rightarrow W + b$	99.9%
Higgs Boson	125.09 GeV	$\tau < 10^{-22} s$	$h \rightarrow b \overline{b} / h \rightarrow c \overline{c}$	58% / 20%



b–tagging in ATLAS

Due to the strong interaction, color-charged partons radiate and hadronize into the collimated spray we call a "jet". **Heavy**-**flavour partons** such as the *b*-quark and *c*quark produce jets that can be distinguished from QCD "light-flavour jets" by their characteristic longer lifetimes, and decay–chains which can produce secondary (and tertiary) vertices in the jet. Identifying heavy-flavour

ary vertex ndary verte jets with high background rejection power is key to many measurements – and a proper calibration of the technique is of paramount

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Physics objects are reconstructed by combining information from detector subsystems (tracking, calorimeters, and muon 🧧	Prim
chambers). One important physics object that combines information from all subsystems is the jet – which represent a	Seco Tertia
collimated spray of charged and un–charged hadrons produced in the pp–collision. Jets in ATLAS are reconstructed with a $!$	$(d_0 on$
sequential anti-kt algorithm [3], where R=0.4 for "small–R jets" [4], and R=1.0 for "large–R jets" [5]. Internal to the jet, there	

are reconstructed **tracks** of charged particles – and at points where one or more tracks originate, one reconstructs **vertices**.



Flavour-tagging algorithms

Flavour-tagging has historically used a combination of "lowlevel" algorithms, which individually optimized to target a specific low-level observable (e.g. secondary-vertex reconstruction) and provide discrimination power from these physically interpretable observables alone. The outputs of these low-level taggers were then used as *input* into a "high-level" DNN known as DL1r [8]. This approach is labor intensive to train and to re-train for usage in the continually changing conditions at the LHC. A more **unified approach** is being pioneered, which uses only low-level input (jets, tracks) and auxiliary tasks (vertex reconstruction, track-origin) to create physically interpretable observables.



GN1 – a graph–attention *b*–tagger

Combined

Graph data-structures are well-suited to represent HEP data [9], which is generally unordered, feature-rich vectors that observe physical invariances. In flavour-tagging applications, each jet and track are presented by graph-level and node-level feature vectors, respectively. Graph neural networks (GNN) provide a framework for parsing such graph data-structures. Jet flavour prediction GNN

Boosted Object Tagging

Heavy particles are produced at the LHC with a continuum of momenta – should these particles decay into *hadrons* (e.g. *b*-quarks), these decay particles may be reconstructed as a jet. At higher momenta, the jets will begin to overlap (collimation) and the decay signature can no longer be distinguished as two separate objects.



The decay products of Higgs bosons with a $p_T \gtrsim 250 \text{ GeV}$ will be **collimated**, and it is in this high- p_T "boosted" regime that sensitivity to BSM effects is highest. To reconstruct boosted H(bb) and $H(c\bar{c})$, a large-R jet clustering is used. Like b-jet tagging, the main background is QCD multi-jet production. However, **boosted Top quarks** are a further background that could "fake" a boosted Higgs.

$GN_2X - a Transformer H(bb/cc)$ tagger

The GN	2 architect	ture is	similar	to GN 1	but 🔄	ATLAS Simulation Preliminary		H(bb
roplacoc	the CNN	lovor i	vith a 7	Francfor	$m \circ r = 0.07$	\sqrt{s} = 13 TeV, Anti- $k_{\rm t}$ R=1.0 UFO jets		H(cc̄)
replaces	ule GNN	layer v	vitii a	11a115101		$p_{\rm T}$ > 250 GeV, 50 < $m_{\rm I}$ < 200 GeV, $ \eta $ < 2		Тор
Т	1 • 1 1	C		1 1 т	<u>a</u>)	Multiie

The GN1 *b*-tagger is a GNN developed by ATLAS [1], which features the use of *self_attention* in its aggregation function.

 $h_i \rightarrow h'_i = \sigma[\sum_{j \in N_i} a_{ij} W h_j]$, where $a_{ij} = softmax_j (\boldsymbol{a} \cdot \theta[W h_i \oplus W h_i])$ are the **attention weights** given to each edge connecting to the i^{th} node, W and a are fully–connected layers, and σ and θ are non–linear activation functions.

- 1 track initializer network
- 3 GNN blocks (as above)
- 1 final attention layer (weighted sum)
- **3 independent fully-connected NNs**
- > Global classification (jet-origin tagging) > Edge classification (vertex reconstruction)¹⁰ > Node classification (track-origin tagging)

Auxiliary Training Tasks

Track origin classification and vertex reconstruction are auxiliary training tasks that are folded into the overall task of tagging *b*-jets (and *c*-jets) by additional terms in the loss function. The total loss function is given as a weighted sum: $L_{total} = L_{jet} + \alpha L_{vertex} + \beta L_{track}$ where $\alpha = 1.5$ and $\beta = 0.5$ provide a weight on each task, signaling the relative difficulty of each auxiliary task.

 $\overset{c}{\overset{}_{0}}_{10} \overset{1}{\overset{}_{0}} = \textbf{ATLAS}$ Simulation Preliminary $\overset{c}{\overset{}_{0}}$ 0 10⁵ ATLAS Simulation Preliminary ---- DL1r

 $D_b = \log \frac{p_b}{(1 - f_c)p_l + f_c p_c}$ D_b tracks

Vertices

encoder which has four attention heads. Each $\frac{1}{5} = \ln \left(\frac{p_{Hbb}}{f_{Hcc}p_{Hcc} + f_{top}p_{top} + (1 - f_{Hcc} - f_{top})p_{QCD}} \right)$ stat. uncertainty encoder calculates the attention scores with a $\frac{8}{2}$ scaled dot-product attention

 $e_{ij} = \frac{(W_i h_i \cdot W_j h_j)}{\sqrt{s}} \rightarrow h'_{ij} = softmax(e_{ij}) \cdot W_k h_j \quad , \overset{\mathbb{W}}{\underset{\mathbb{Z}}{\mathbb{Z}}} \overset{0.04}{\overset{\mathbb{W}}{\mathbb{Z}}}$ closely resembling the original transformer 0.03 architecture [7]. This network has already superseded the GN1 architecture and has been applied not only to *b*-tagging, but to **boosted Higgs tagging** in the GN₂X.

Prior to **GN**₂**X**, the state-of-the-art boosted "Xbb" tagger was a DNN large-R jet tagger that relied on the sub-jet DL1r *b*-tagging information [10,11] within the large–R jet.

Mass sculpting

One of the major challenges that *GN*₂*X* (and the previous Xbb tagger) faces when taking analysis-level usage into consideration is the distribution-level mass sculpting effect on backgrounds such as QCD jets. If the mass of the large-R jet is used as an input, then one generally sees an *improved tagging efficiency* within the mass–range of your signal.

GN₂**X** is trained on **mass decorrelated** Higgs







Conditional track



sample, in which the Higgs boson decay width is artificially enlarged (nominally, the Higgs width $\Gamma_{Higgs} \sim 4 MeV$) to minimize correlations between jet mass and other features from being exploited by the network, and a kinematic resampling alters relative MC statistics in regions of phase-space to ensure similar kinematic distributions between all classes of jet $(H(b\overline{b}), H(c\overline{c}), \text{Top, QCD})$.



ATLAS Collaboration Graph Neural Network Jet Flavour Tagging with the ATLAS Detector (2022) URL: https://cds.cern.ch/record/2811135 2 ATLAS Collaboration Transformer Neural Networks for Identifying Boosted Higgs Bosons decaying into bb⁻and cc⁻in ATLAS (2023) URL: https://cds.cern.ch/record/2866601 3 Matteo Cacciari *et al.* The anti-kt jet clustering algorithm. JHEP04(2008)063 URL: http://dx.doi.org/10.1088/1126-6708/2008/04/063 [4] Aaboud, M., Aad, G., Abbott, B. *et al.* Jet reconstruction and performance using particle flow with the ATLAS Detector. *Eur. Phys. J. C* 77, 466 (2017) [5] Aad, G., Abbott, B., Abbott, D.C. et al. Optimisation of large-radius jet reconstruction for the ATLAS detector in 13 TeV proton–proton collisions. Eur. Phys. J. C 81, 334 (2021) 6 M. Tanabashi et al. (Particle Data Group), Phys. Rev. D 98, 030001 (2018) URL: https://journals.aps.org/prd/pdf/10.1103/PhysRevD.98.030001 [7] Vaswani, A et al. Attention Is All You Need arXiv:1706.03762 (2017) 8 Aad, G., Abbott, B., Abbott, D.C. et al. ATLAS flavour-tagging algorithms for the LHC Run 2 pp collision dataset. Eur. Phys. J. C 83, 681 (2023) [9] Jonathan Shlomi et al. Graph neural networks in particle physics (2021) Mach. Learn.: Sci. Technol. 2 021001 [10] ATLAS Collaboration., Aad, G., Abbott, B. et al. Identification of boosted Higgs bosons decaying into b-quark pairs with the ATLAS detector at 13 TeV. Eur. Phys. J. C 79, 836 (2019) 11 ATLAS Collaboration Efficiency corrections for a tagger for boosted $H \rightarrow bb^-$ decays in *pp* collisions at $\sqrt{s} = 13$ TeV with the ATLAS detector (2021) URL: https://cds.cern.ch/record/2777811/files/ATL-PHYS-PUB-2021-035.pdf