

A Neural-Network-defined Gaussian Mixture Model for particle identification in LHCb

Giacomo Graziani (1), Lucio Anderlini (1), Saverio Mariani (1, 2, 3), **Edoardo Franzoso** (4), Luciano Libero Pappalardo (4,5), Pasquale di Nezza (6)

(1) INFN Sezione di Firenze, Florence, Italy

(2) Università degli studi di Firenze, Florence, Italy,

(3) European Organization for Nuclear Research (CERN), Geneva, Switzerland,

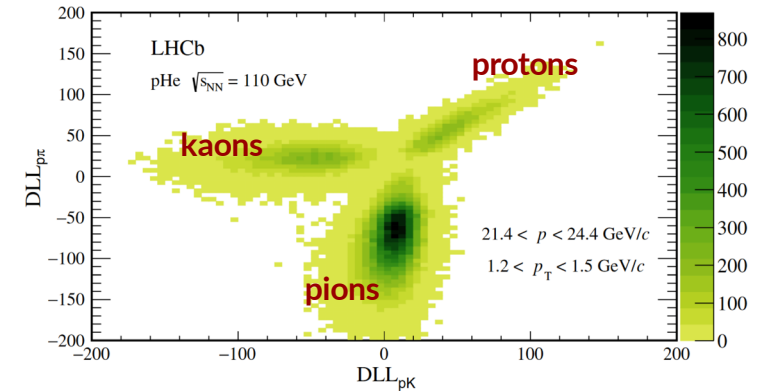
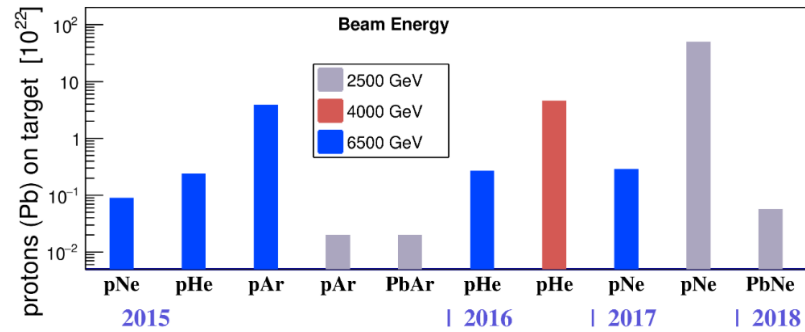
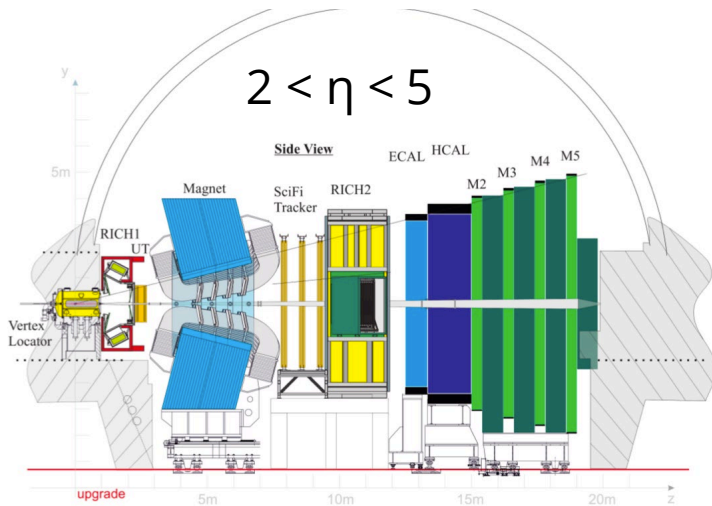
(4) INFN Sezione di Ferrara, Ferrara, Italy,

(5) Università degli studi di Ferrara, Ferrara, Italy,

(6) INFN Laboratori Nazionali di Frascati, Frascati, Italy

Motivation and idea

- **LHCb** relies on the Ring Imaging Cherenkov (**RICH**) detector system for the **charged hadron identification** (PID) in a wide momentum range (2 - 100 GeV/c)
- The PID was one of the dominant systematics into the measurement of cross-sections with fixed-target datasets in LHCb:



- This motivated the development of a **novel approach to the modelling of particle identification classifiers** using machine-learning techniques
 - **Explicitly model the marginal probability density function** (pdf) of the PID classifiers → must **depend on the experimental features** θ
 - Extract the marginal pdf using a **Gaussian Mixture Model**, whose parameters are predicted by Multi Layer Perceptrons trained on calibration data
 - **Model each hadron type** h (π , K and p) PID response independently using the appropriate control modes

Model and Validation

- In the **bidimensional PID space** the pdf x is defined as:
$$\underline{x}_h \sim \sum_{j=1}^{N_{g,h}} \alpha_{j,h}(\underline{\theta}) \frac{\exp(-\frac{1}{2}(\underline{x}_h - \underline{\mu}_{j,h}(\underline{\theta}))^T \Sigma_{j,h}^{-1}(\underline{\theta}) (\underline{x}_h - \underline{\mu}_{j,h}(\underline{\theta})))}{2\pi \sqrt{\det(\Sigma_{j,h}(\underline{\theta}))}}$$

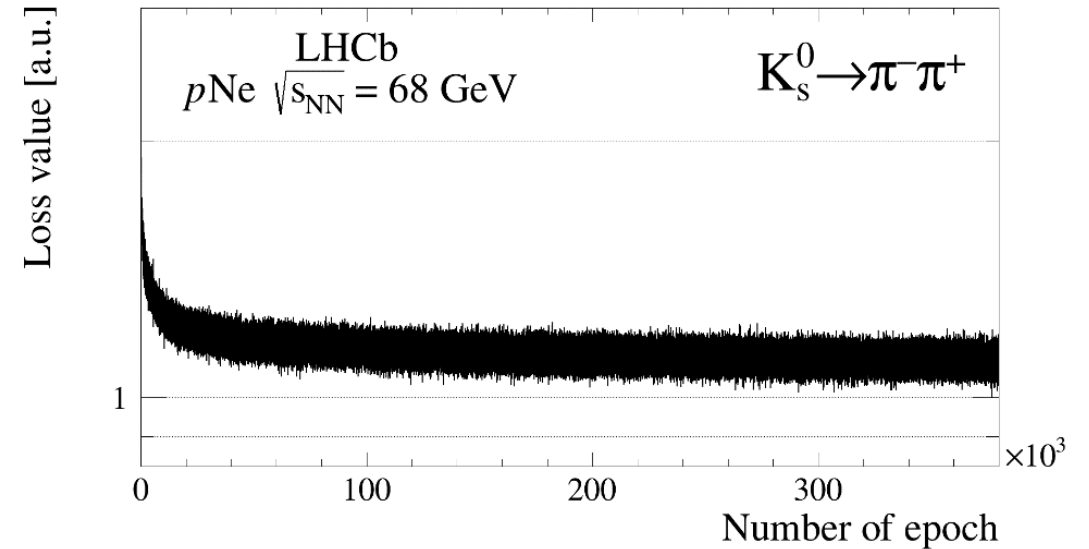
Training on proton-Neon sample

- The learning process of the networks relies on the **minimization** of the loss function, defined as the **negative log-likelihood**

$$\mathcal{L} = - \sum_{i=1}^{n_h} w_i \log \left[\sum_{j=1}^{N_{g,h}} \alpha_{j,h}(\underline{\theta}_i) \mathcal{G}(x_i, \mu_{j,h}(\underline{\theta}_i), \sigma_{j,h}(\underline{\theta}_i)) \right]$$

- Training performed with **mini-batches gradient descent** with a user-defined number of Gaussians and NN structure

Input parameter	$K_S^0 \rightarrow \pi^- \pi^+$	$\bar{\Lambda} \rightarrow \bar{p} \pi^+$	$\phi \rightarrow K^- K^+$
Number of Gaussians	64	20	64
Number of NN nodes	128	128	128
Starting learning rate	10^{-3}	10^{-4}	$5 \cdot 10^{-6}$
Batch size	10000 events	10000 events	20000 events



Model and Validation

Validation on fixed-target datasets

- Marginal-pdf prediction validated for the same training dataset and then **applied to two independent lower-statistics samples** of proton-Helium and proton-Argon collisions
 - **significant modifications of the kinematic distributions** of the produced particles
 - **different events multiplicity** and the detector occupancy
 - **identical detector and data-taking conditions** can be assumed
- **Data description quality improved by the model** compared to simulation
- The method is generic, not relying on a specific set of experimental feature variable

