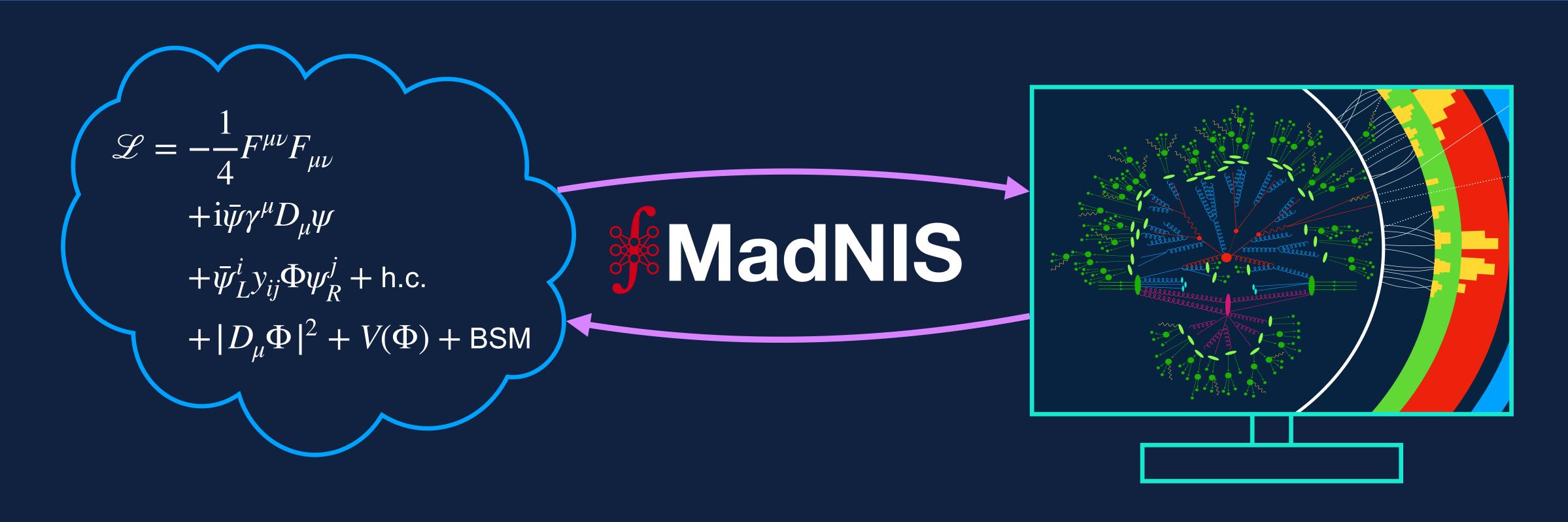
The MadNIS Reloaded

Boosting MadGraph with Neural Importance Sampling



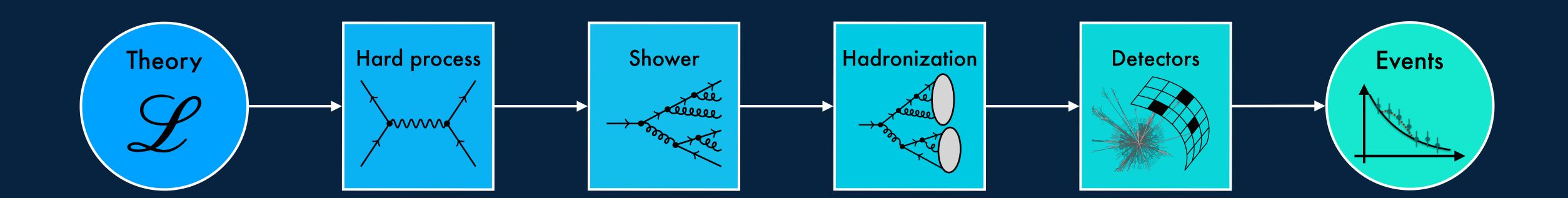


EuCAIFCon 2024 — Amsterdam

Ramon Winterhalder — UCLouvain

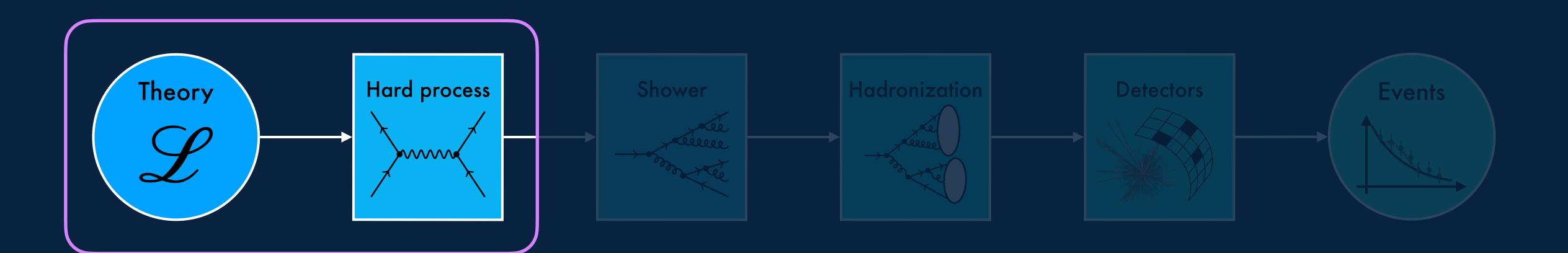
The LHC simulation chain





The LHC simulation chain





Differential cross section known from QFT:

 $d\sigma \sim pdf(x) \cdot |M(x)|^2 \cdot d\Phi$

Total cross section:

$$\sigma = \int_{\Phi} d\sigma$$

Monte Carlo integration + sampling from differential cross section

Accelerate with

Deep Generative Models

Exact sampling ensured by known likelihood

1

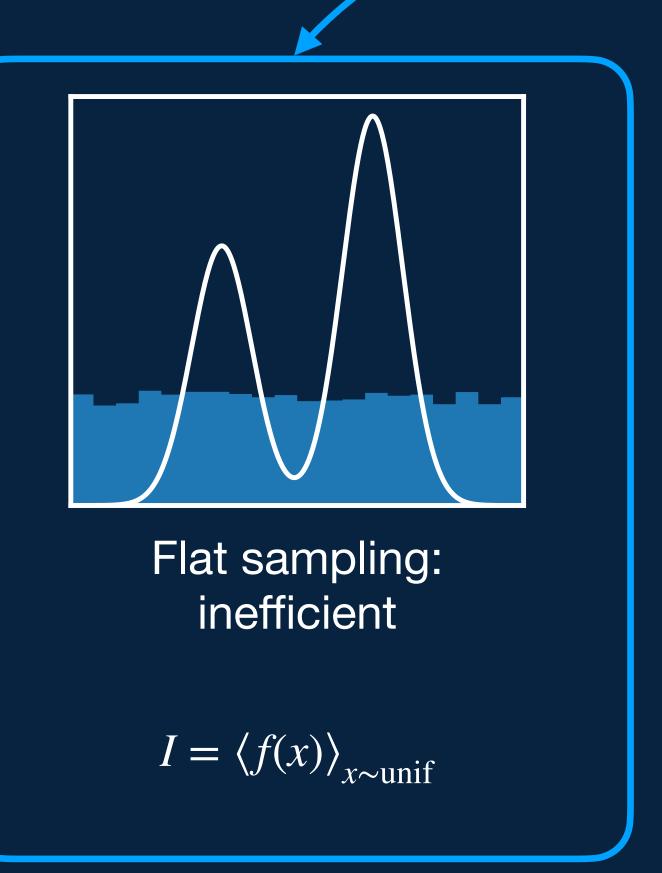
better model

faster sampling

Monte Carlo Integration

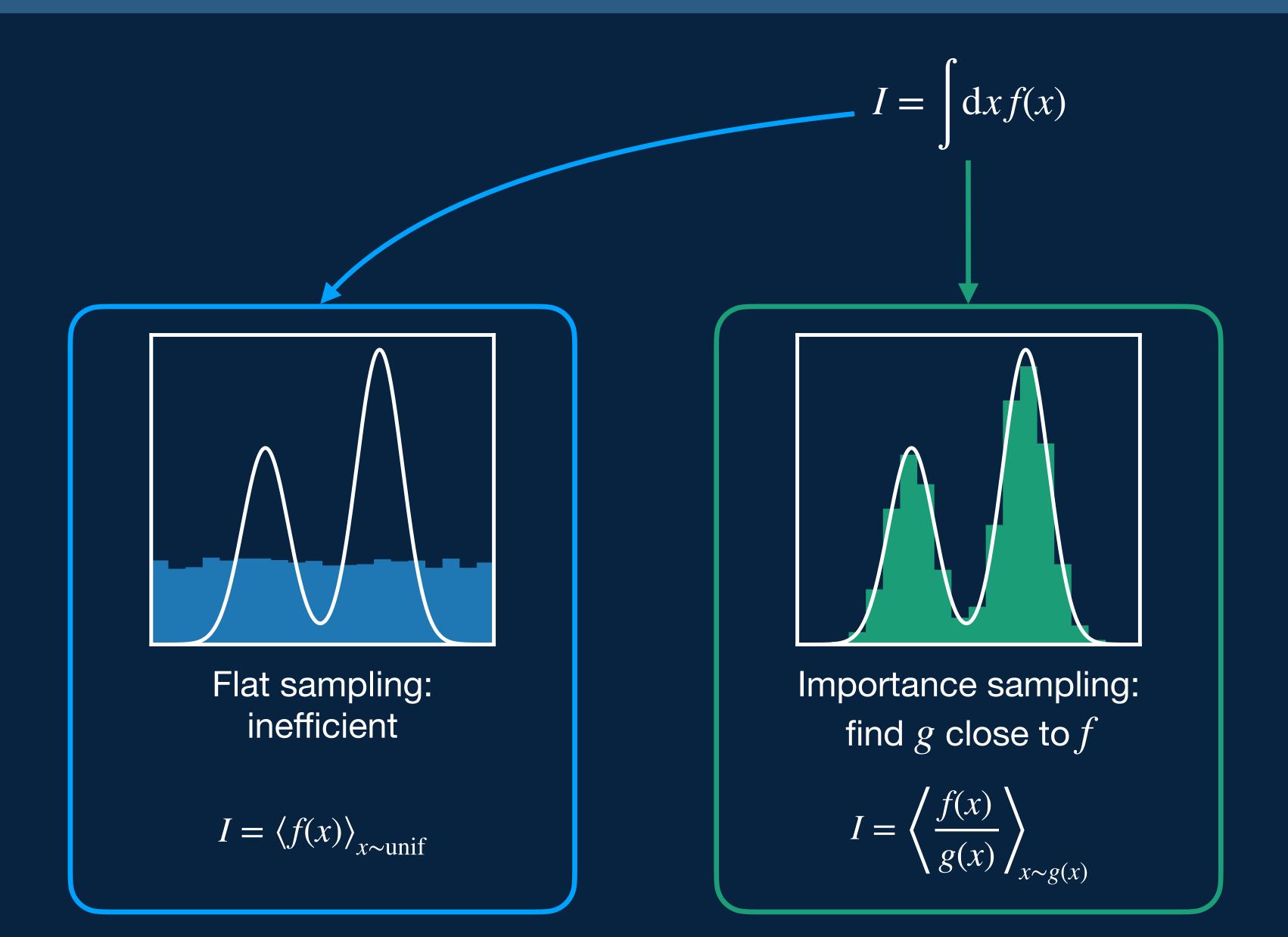


$$I = \int \mathrm{d}x f(x)$$



Monte Carlo Integration

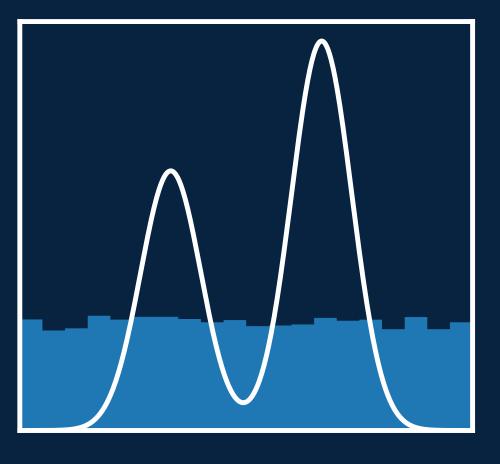




Monte Carlo Integration

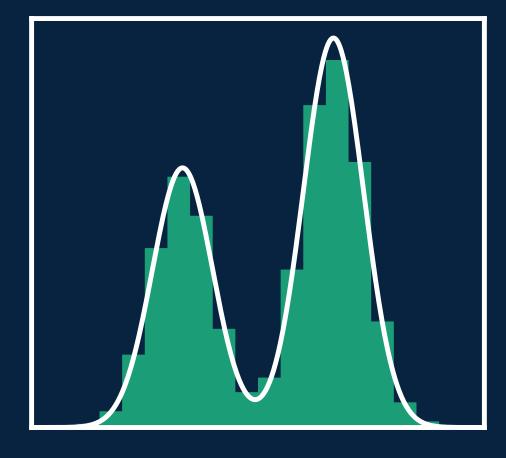






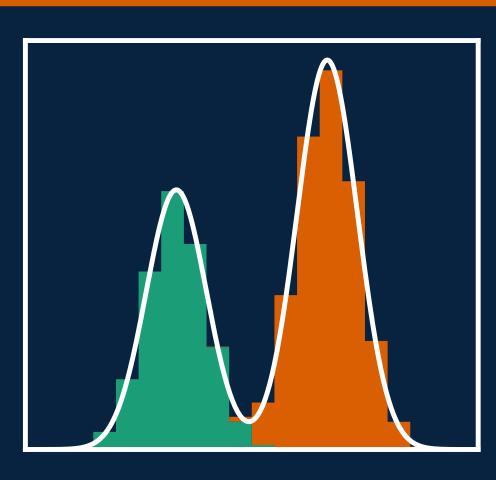
Flat sampling: inefficient

$$I = \langle f(x) \rangle_{x \sim \text{unif}}$$



Importance sampling: find g close to f

$$I = \left\langle \frac{f(x)}{g(x)} \right\rangle_{x \sim g(x)}$$



Multi-channel: one map for each channel

$$I = \sum_{i} \left\langle \alpha_{i}(x) \frac{f(x)}{g_{i}(x)} \right\rangle_{x \sim g_{i}(x)}$$

Event generation



Calculate (differential) cross sections

$$d\sigma = \frac{1}{\text{flux}} dx_a dx_b f(x_a) f(x_b) d\Phi_n \langle |M_{\lambda,c,...}(p_a, p_b | p_1, ..., p_n)|^2 \rangle$$

Sum over channels

MadGraph: build channels from Feynman diagrams



$$I = \sum_{i} \left\langle \alpha_{i}(x) \frac{f(x)}{g_{i}(x)} \right\rangle_{x \sim g_{i}}$$

Channel weights

MadGraph:
$$\alpha_i \sim |M_i|^2$$
 or
$$\alpha_i \sim \prod_k |p_k^2 - m_k^2 - \mathrm{i} m_k \Gamma_k|^{-2}$$

Channel mappings

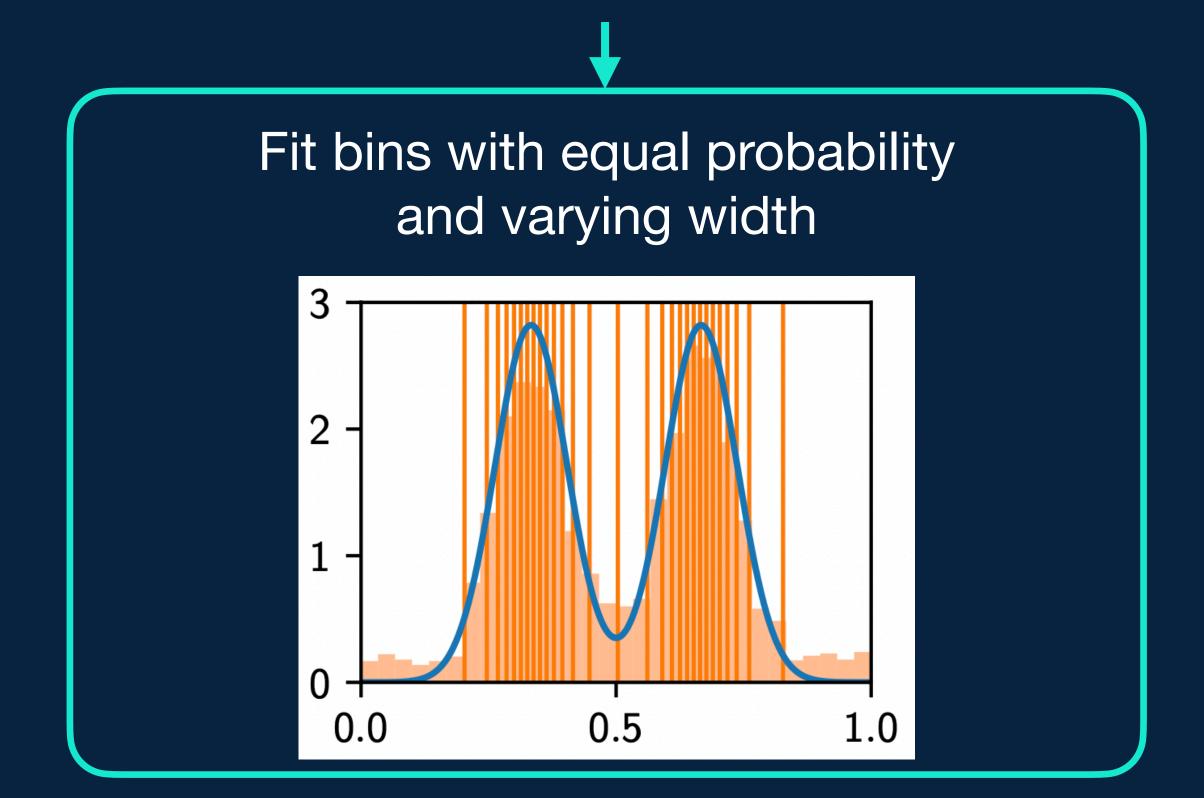
MadGraph: use amplitude structure, ...
refine with VEGAS
(factorized, histogram based
importance sampling)

Importance sampling — VEGAS



Factorize probability

$$p(x) = p(x_1) \cdots p(x_n)$$



Importance sampling — VEGAS



Factorize probability

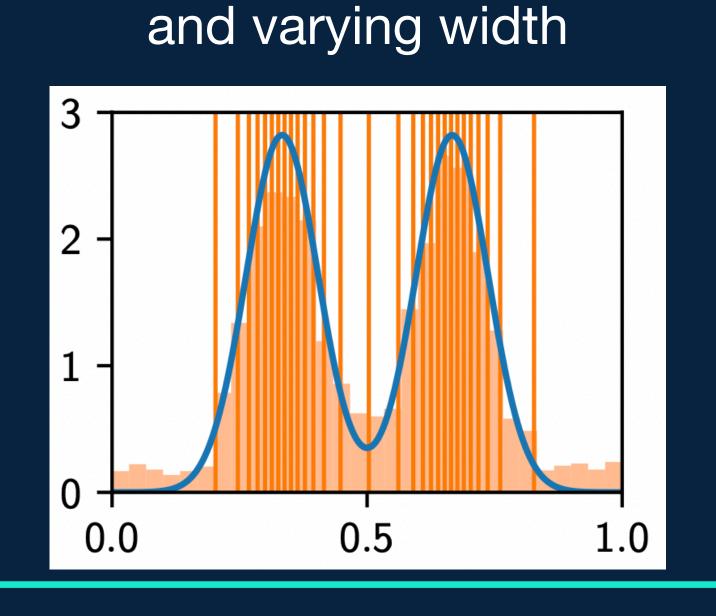
$$p(x) = p(x_1) \cdots p(x_n)$$

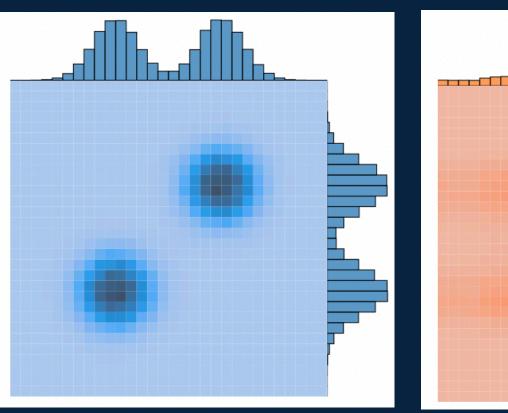
Fit bins with equal probability

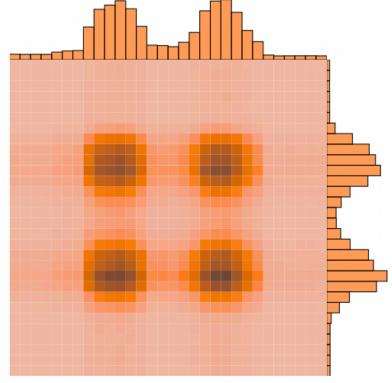


Computationally cheap

- High-dim and rich peaking functions
 - → slow convergence
- Peaks not aligned with grid axes
 - → phantom peaks







MadNIS

Neural Importance Sampling

MadNIS — Neural Importance Sampling



$$I = \sum_{i} \left\langle \alpha_{i}(x) \frac{f(x)}{g_{i}(x)} \right\rangle_{x \sim g_{i}(x)}$$

Use physics knowledge to construct channel and mappings





Normalizing flow to refine channel mappings

Fully connected network to refine channel weights





Update simultanously with variance as loss function



Basic functionality

Neural Channel Weights

Normalizing Flow

MadGraph matrix elements

MadEvent channel mappings



Improved multi-channeling

Stratified sampling/training

Symmetries between channels

Channel Dropping

Partial weight buffering

Improved training

VEGAS Initialization Buffered Training



Basic functionality

Neural Channel Weights

Normalizing Flow

MadGraph matrix elements MadEvent channel mappings



innel pings



Stratified sampling/training

Symmetries between channels

Channel Dropping

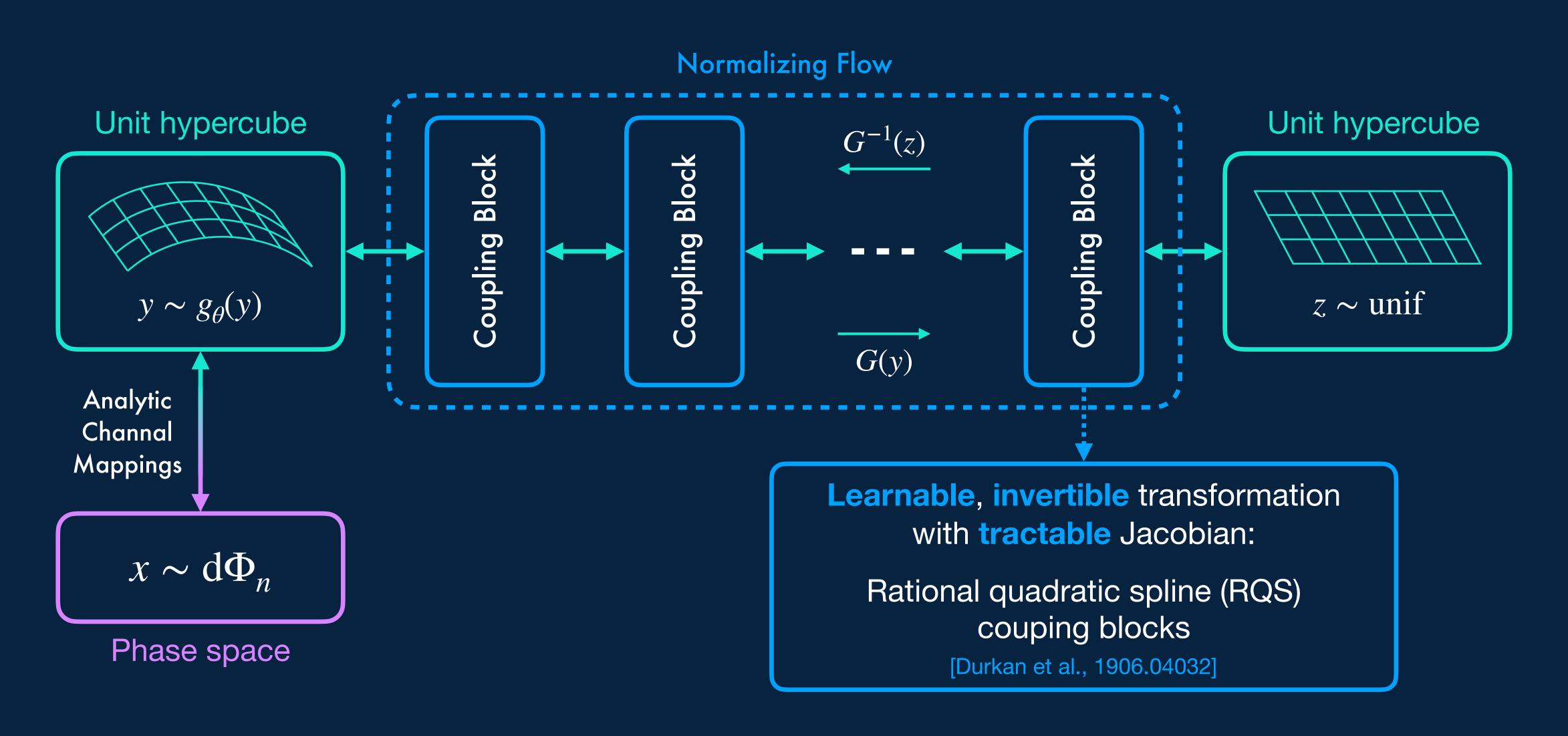
Partial weight buffering

Improved training

VEGAS Initialization Buffered Training

Neural importance sampling







Basic functionality

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MadEvent channel mappings





Improved training

VEGAS Initialization Buffered Training

Improved multi-channeling

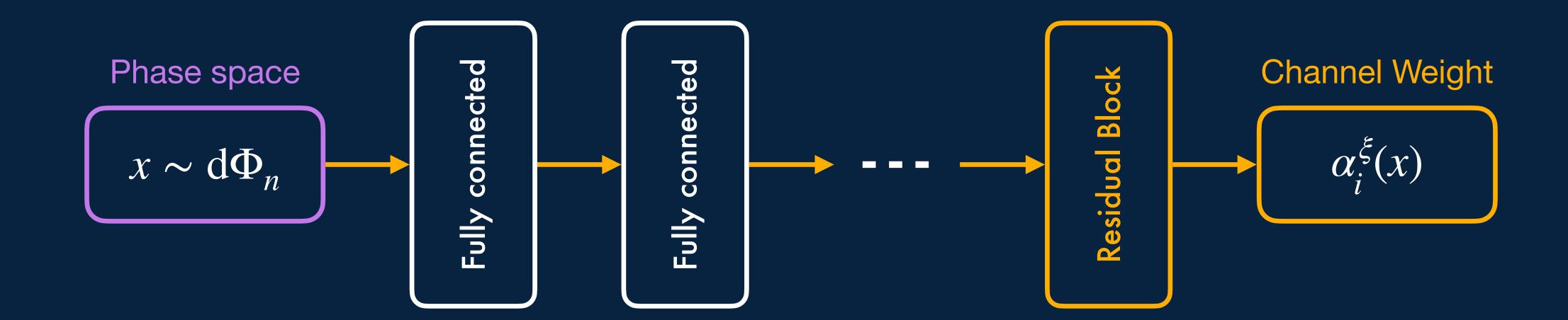
Stratified sampling/ training

Symmetries between channels

Channel Dropping Partial weight buffering

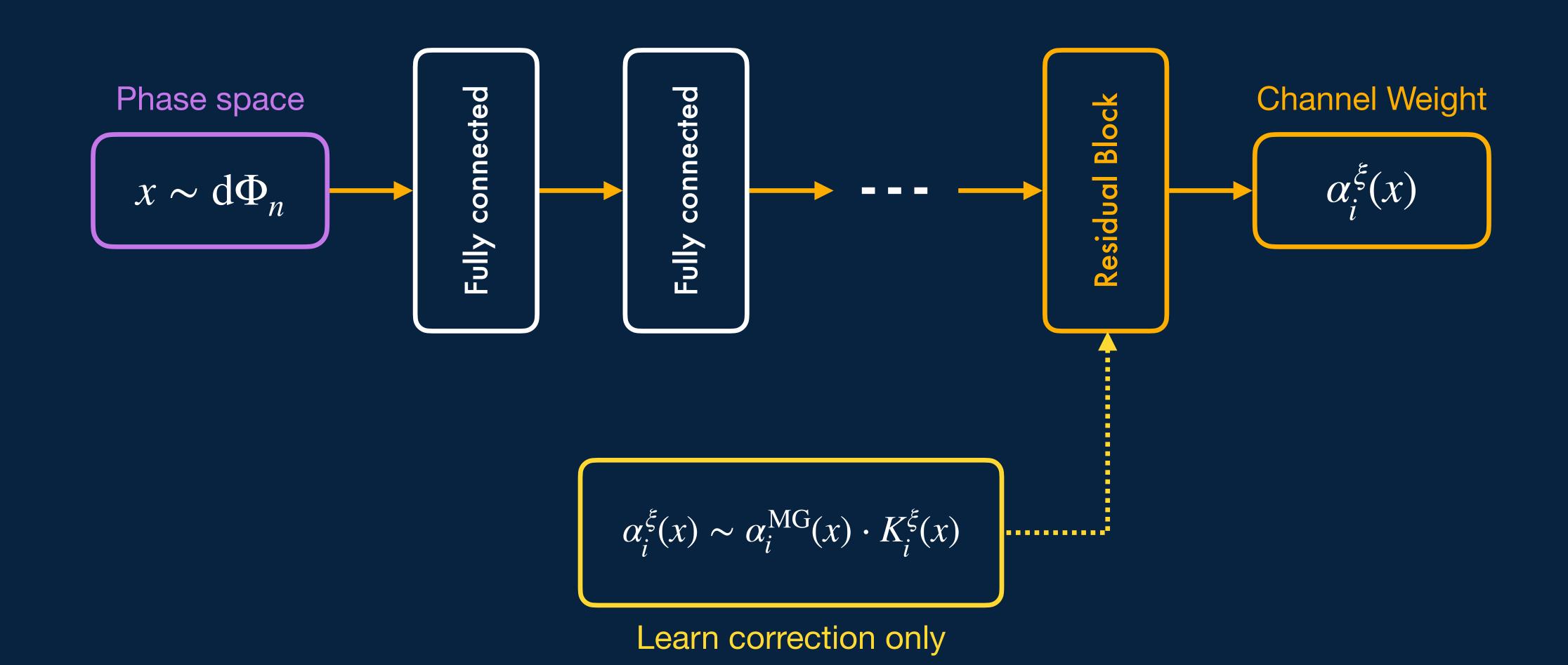
Neural Channel Weights





Neural Channel Weights







Basic functionality

Neural Channel Weights

Normalizing Flow

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Symmetries between channels

Channel Dropping

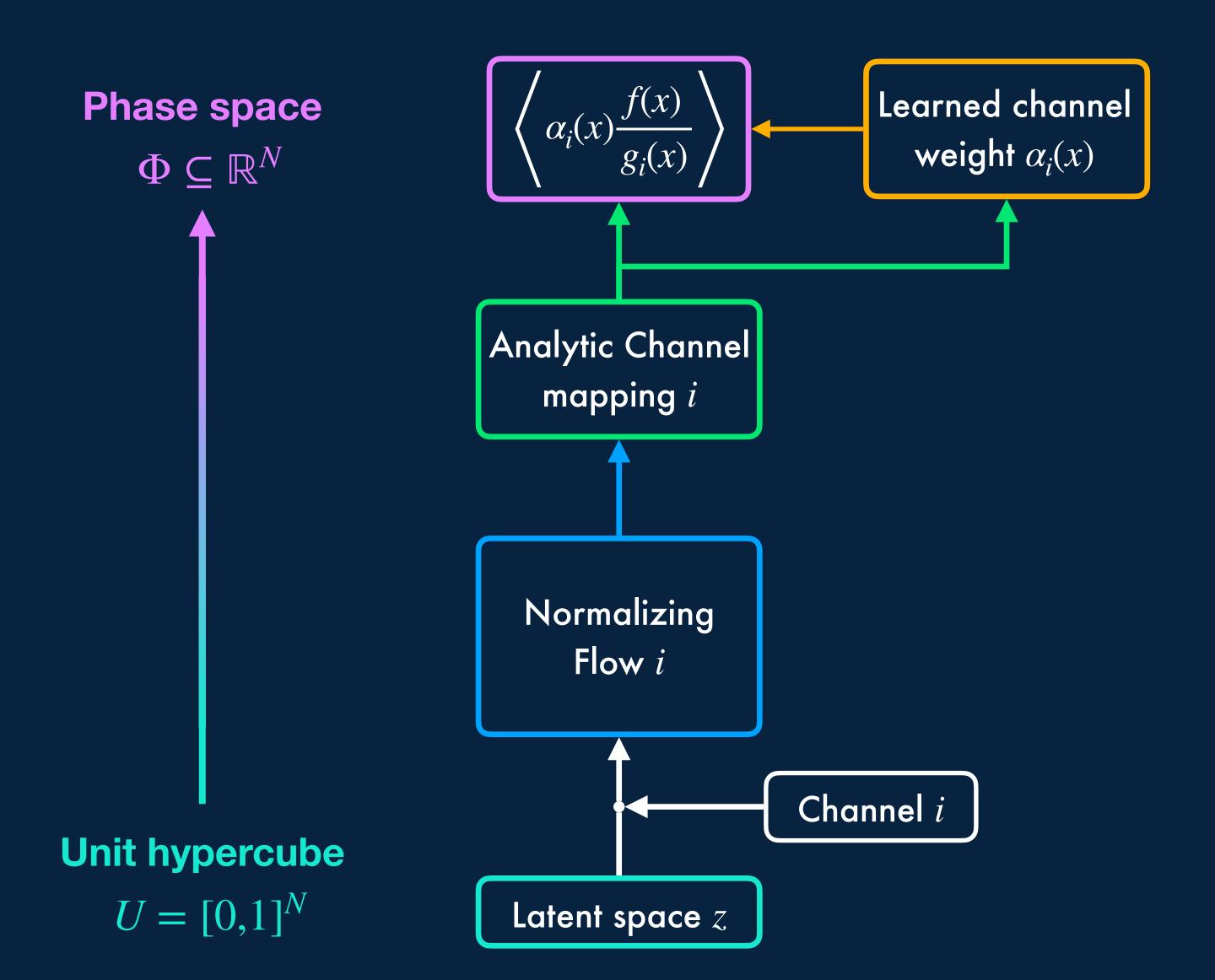
Partial weight buffering

Improved training

VEGAS Initialization Buffered Training

MadNIS — Neural Importance Sampling

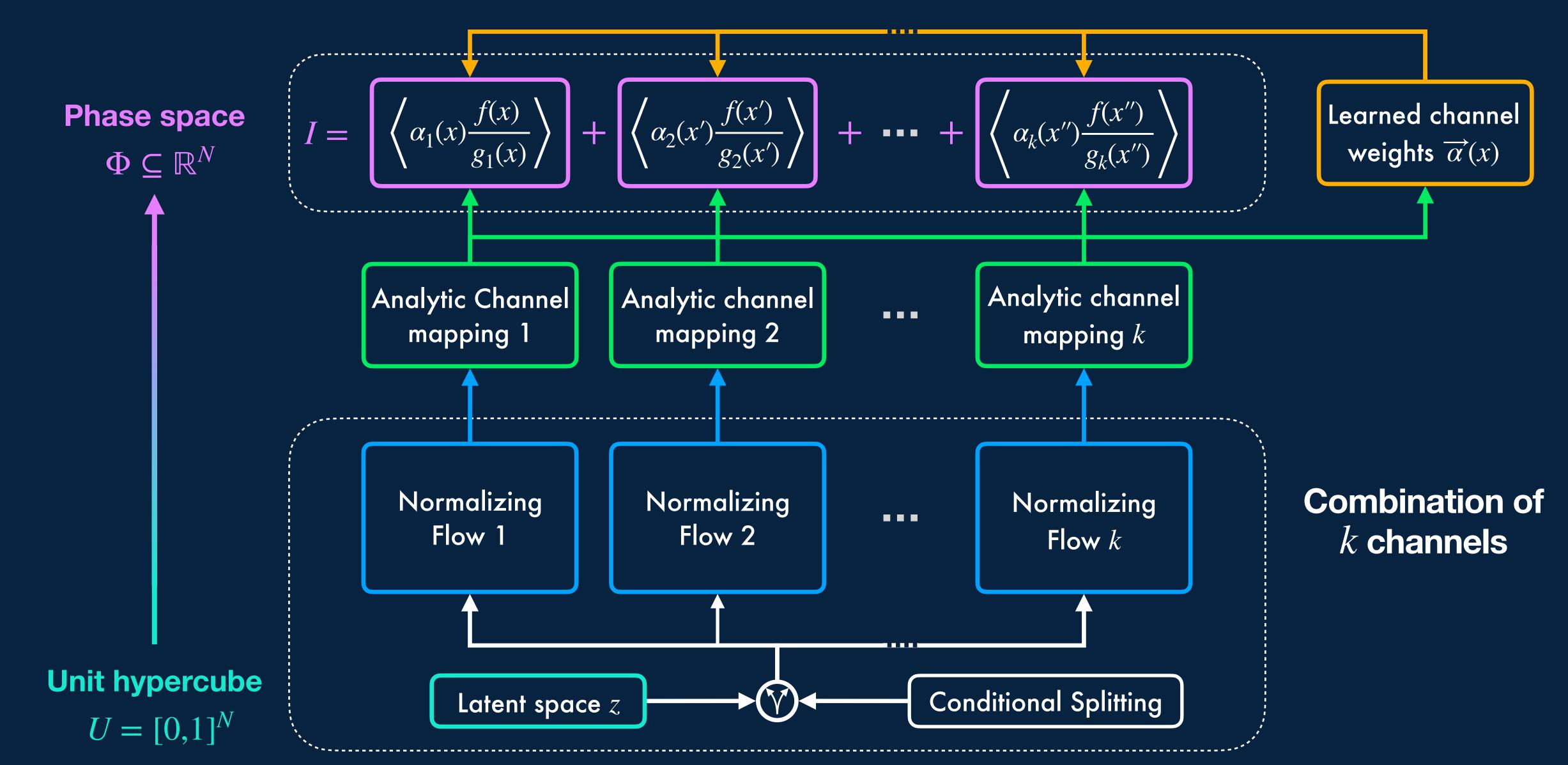




Single channel i

MadNIS — Neural Importance Sampling





Loss function



Minimize total variance

$$\sigma_{\mathrm{tot}}^2 = N \sum_{i} \frac{\sigma_i^2}{N_i}$$
 with

$$\sigma_i^2 = \operatorname{Var}\left(\alpha_i(x) \frac{f(x)}{g_i(x)}\right)_{x \sim g_i(x)}$$

Total variance depends on N_i \downarrow affects optimal $\alpha_i(x)$ \downarrow use stratified sampling

$$N_i = N \frac{\sigma_i}{\sum_k \sigma_k}$$

Loss function



Minimize total variance

$$\sigma_{\mathrm{tot}}^2 = N \sum_{i} \frac{\sigma_i^2}{N_i}$$
 with

$$\sigma_i^2 = \text{Var}\left(\alpha_i(x) \frac{f(x)}{g_i(x)}\right)_{x \sim g_i(x)}$$

Total variance depends on N_i

affects optimal $\alpha_i(x)$

use stratified sampling

$$N_i = N \frac{\sigma_i}{\sum_k \sigma_k}$$





$$\mathcal{L} = \sigma_{\text{tot}}^2 = \left(\sum_i \sigma_i\right)^2$$



Basic functionality

Neural Channel Weights

Normalizing Flow

MadGraph matrix elements MadEvent channel mappings



Improved multi-channeling

Stratified sampling/training

Symmetries between channels

Channel Dropping

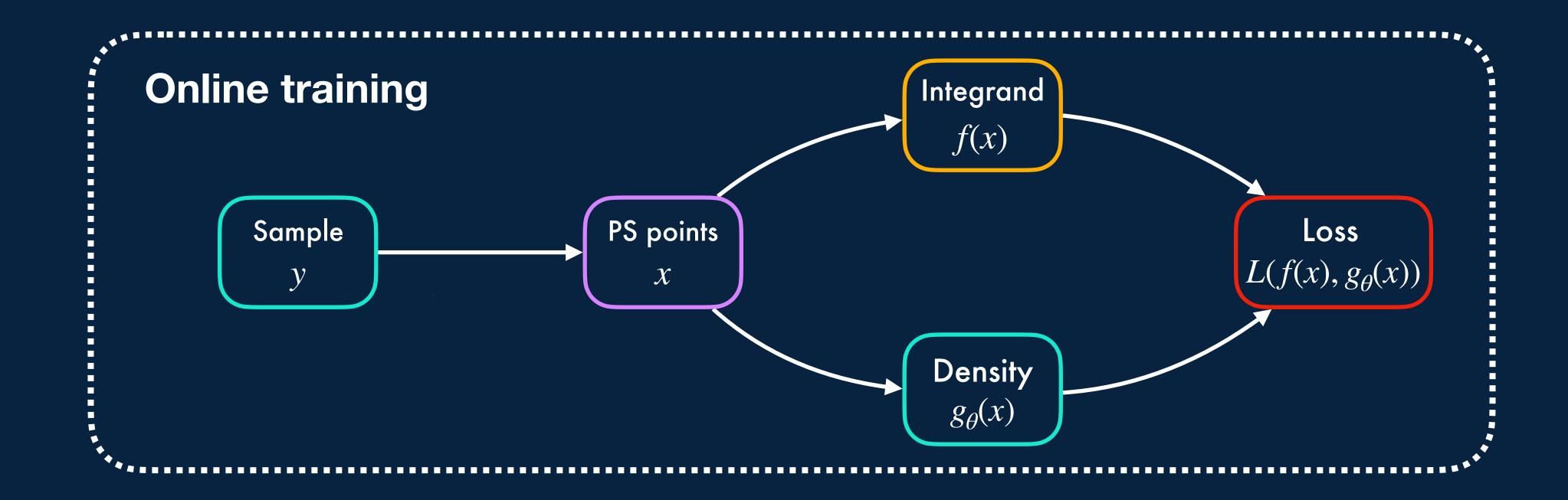
Partial weight buffering

Improved training

VEGAS Initialization Buffered Training

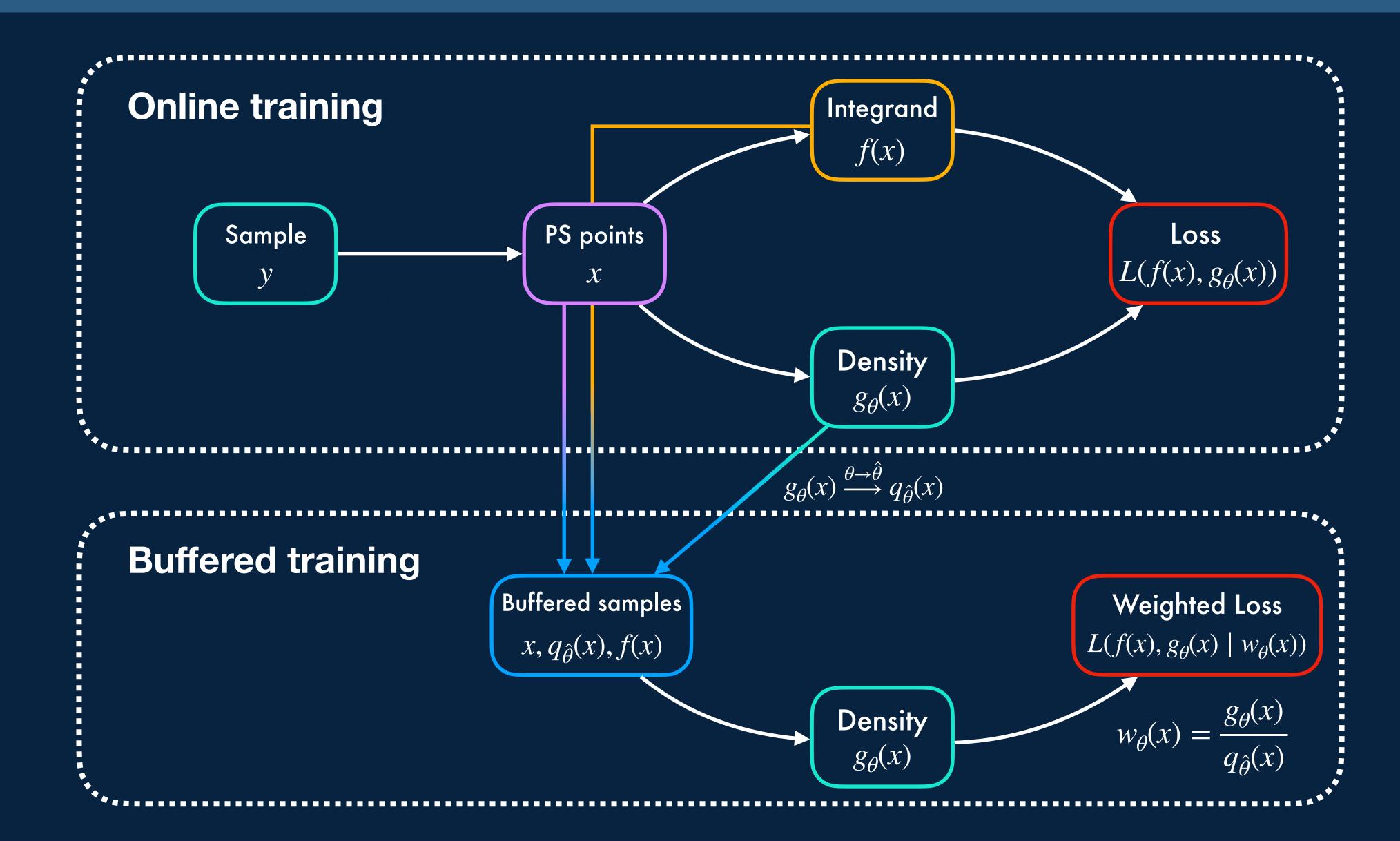
Buffered training





Buffered training





Buffered training



Training algorithm

generate new samples, train on them, save samples

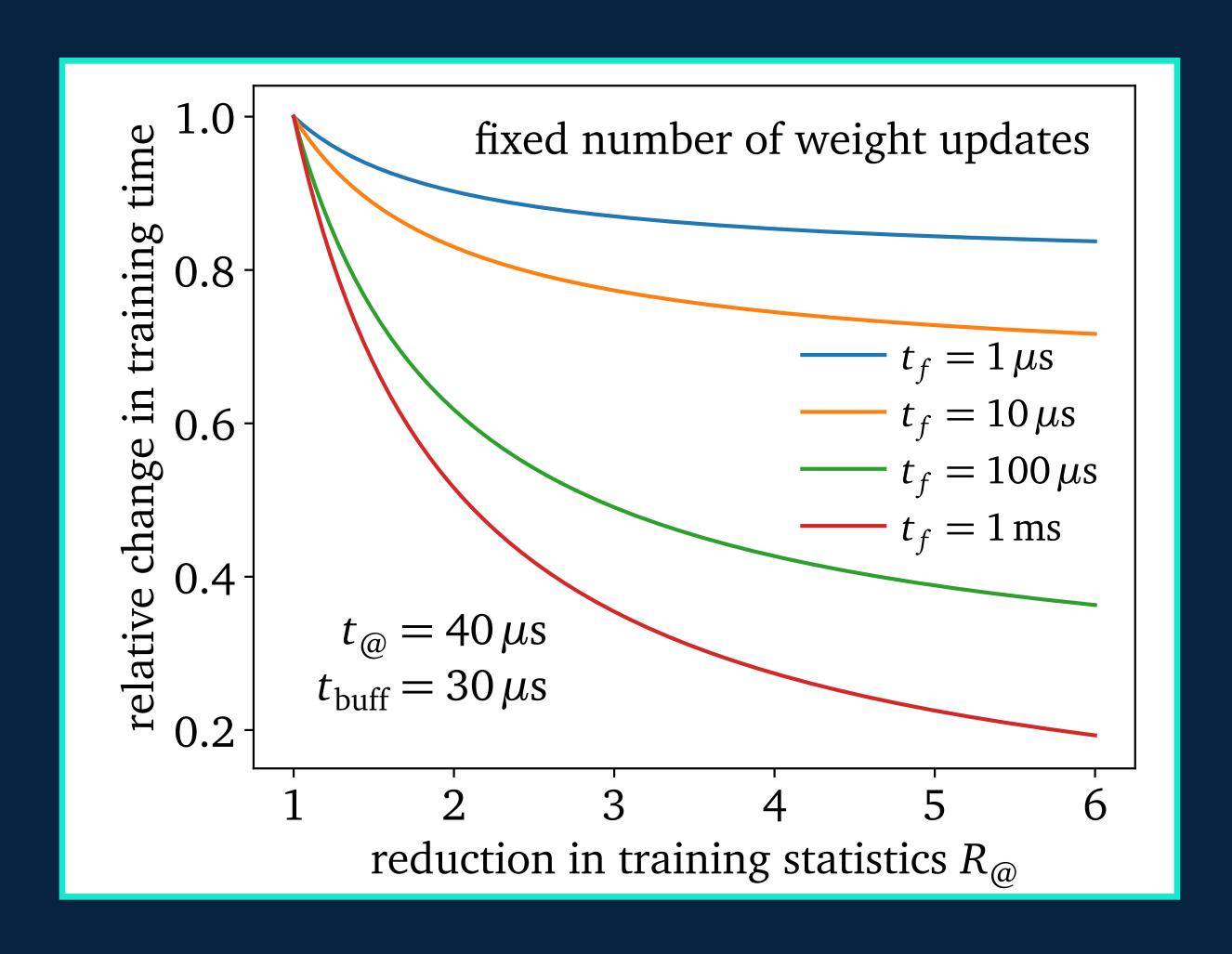
train on saved samples n times

repeat



Reduction in training statistics by

$$R_{@} = n + 1$$





Basic functionality

Neural Channel Weights

Normalizing Flow

MadGraph matrix elements

MadEvent channel mappings





Improved multi-channeling

Stratified sampling/ training

Symmetries between channels

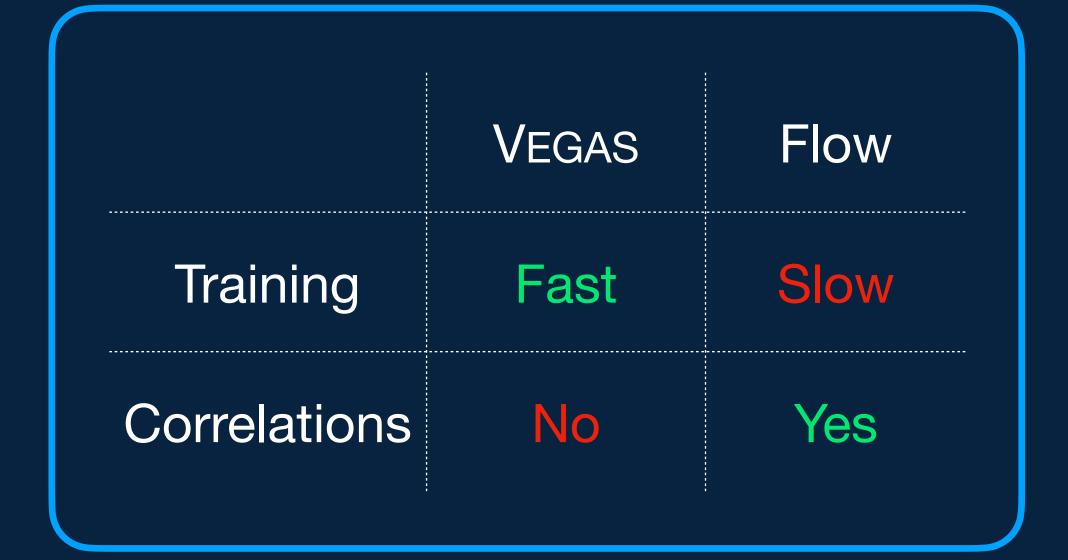
Channel Dropping Partial weight buffering

Improved training

VEGAS Initialization Buffered Training

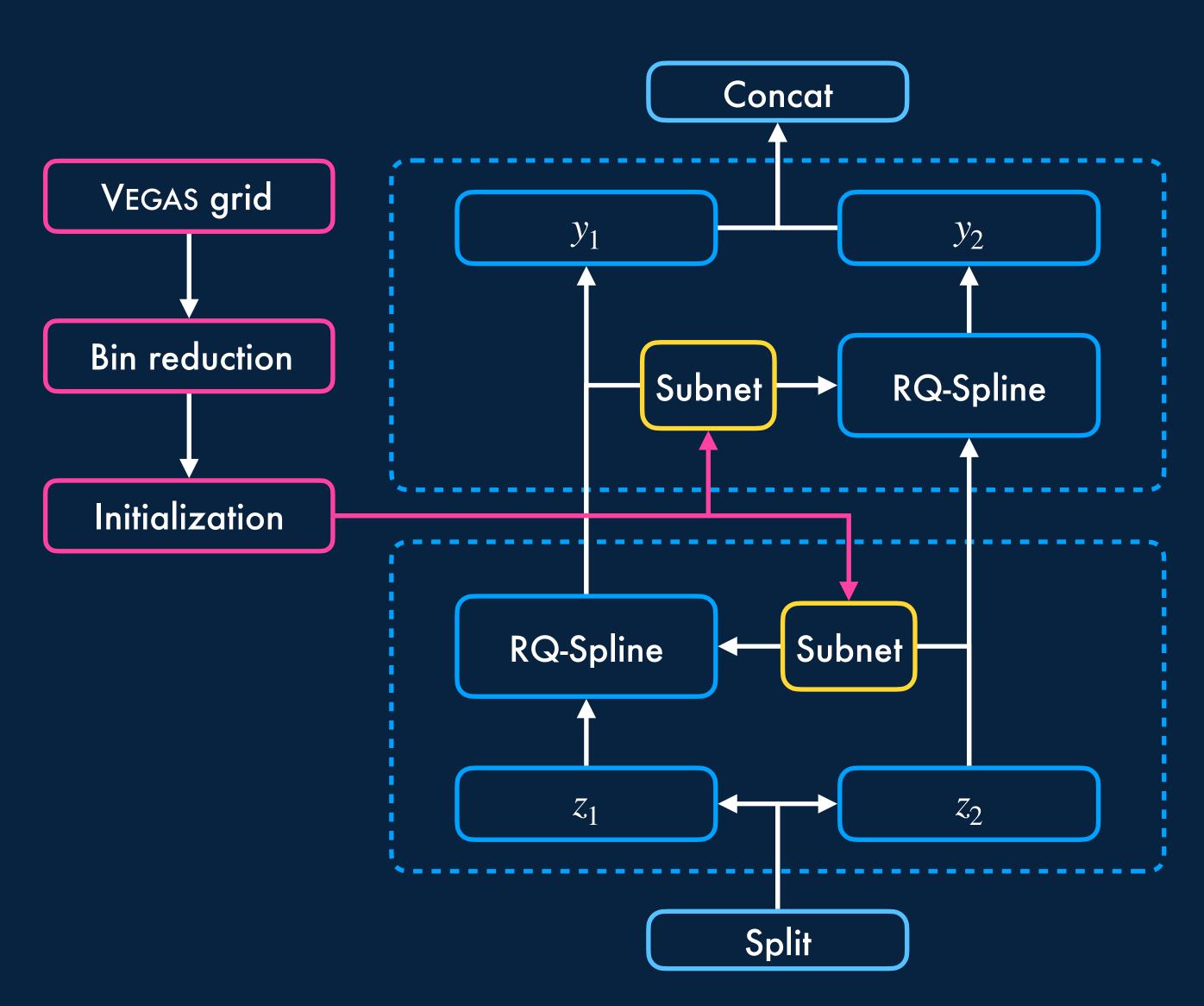
VEGAS initialization





Combine advantages:

Pre-trained VEGAS grid as starting point for flow training





Basic functionality

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MadGraph matrix elements MadEvent channel mappings



Improved multi-channeling

Stratified sampling/training

Symmetries between channels

Channel Dropping

Partial weight buffering

Improved training

VEGAS Initialization Buffered Training

Improved multi-channeling



Use symmetries

Groups of channels only differ by permutations of final state momenta

use common flow and combine in loss function

Stratified training

Channels have different contributions to the total variance

more samples for channels with higher variance during training

Channel dropping

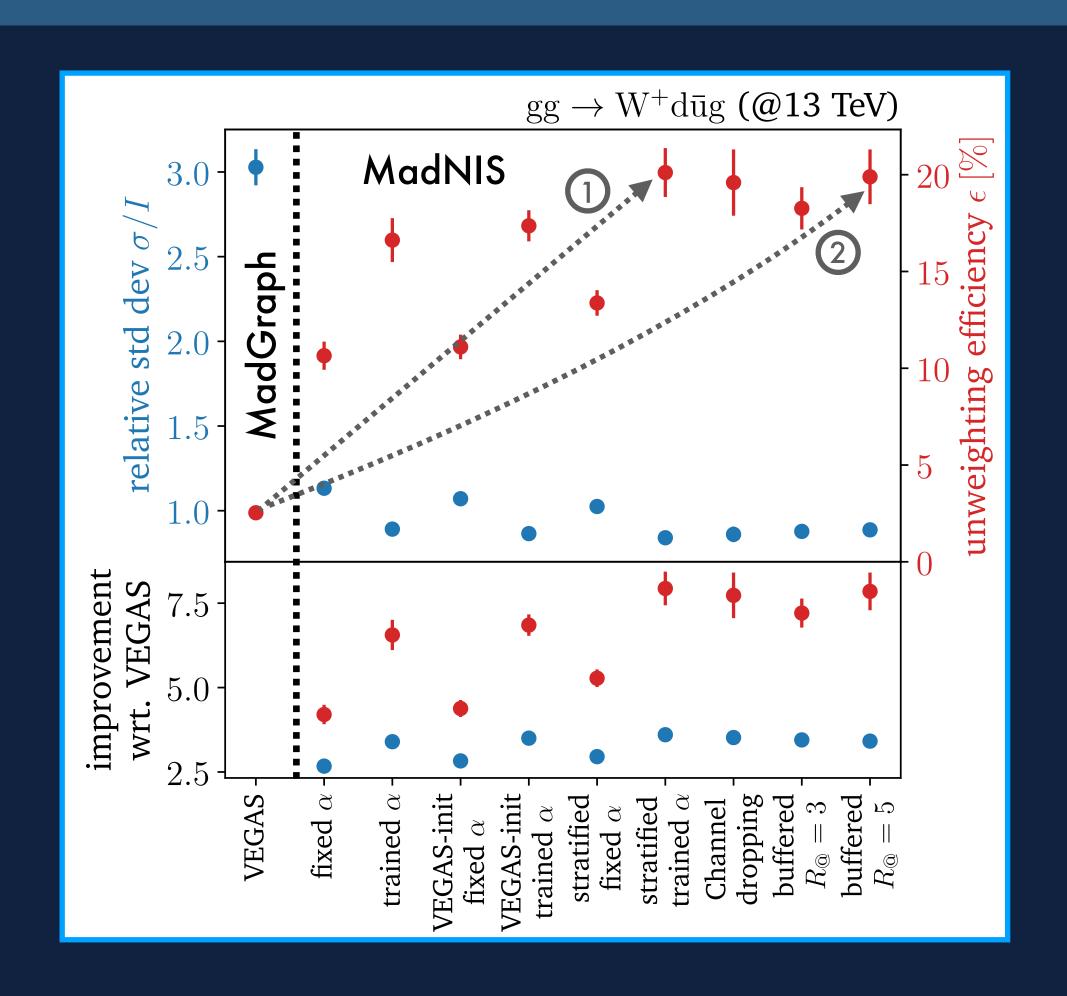
MadNIS often reduces contribution of some channels to total integral

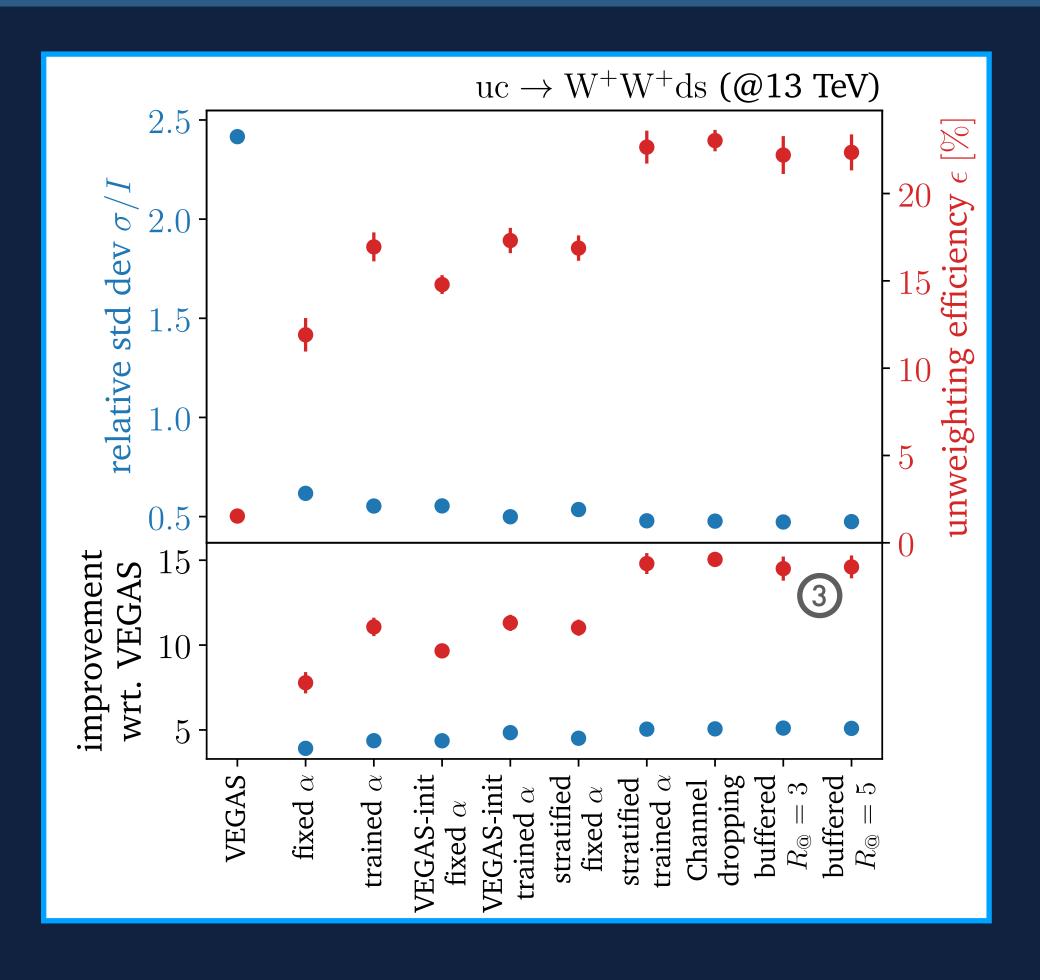
remove these channels from the training completely

Reduced complexity Improved stability

LHC processes



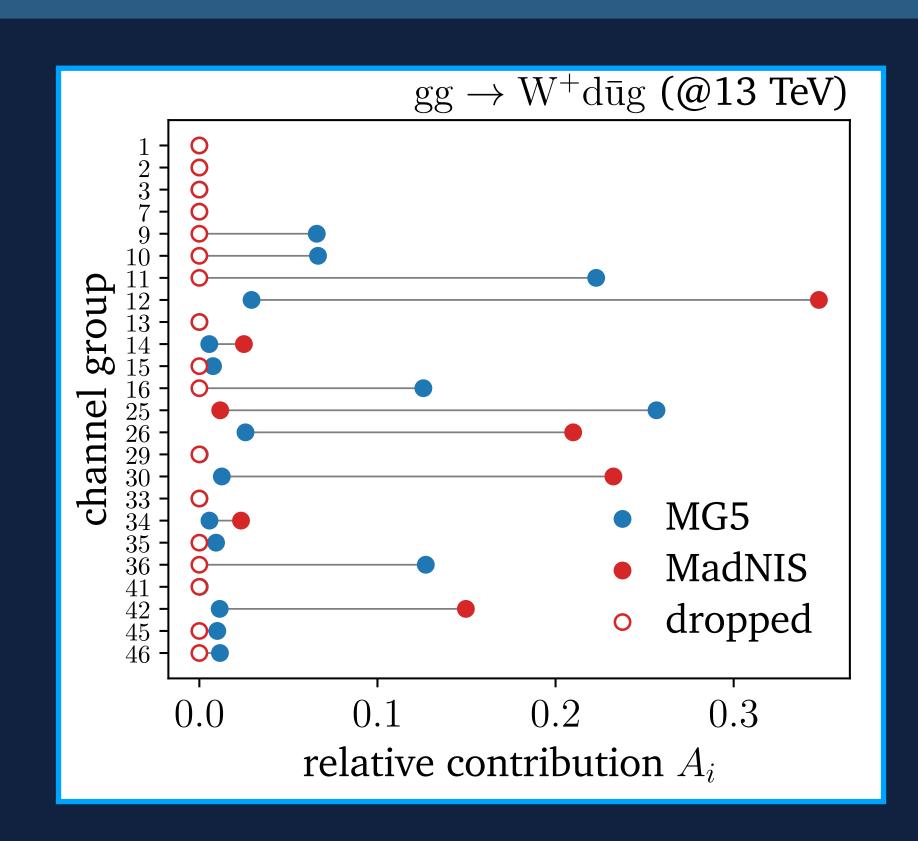


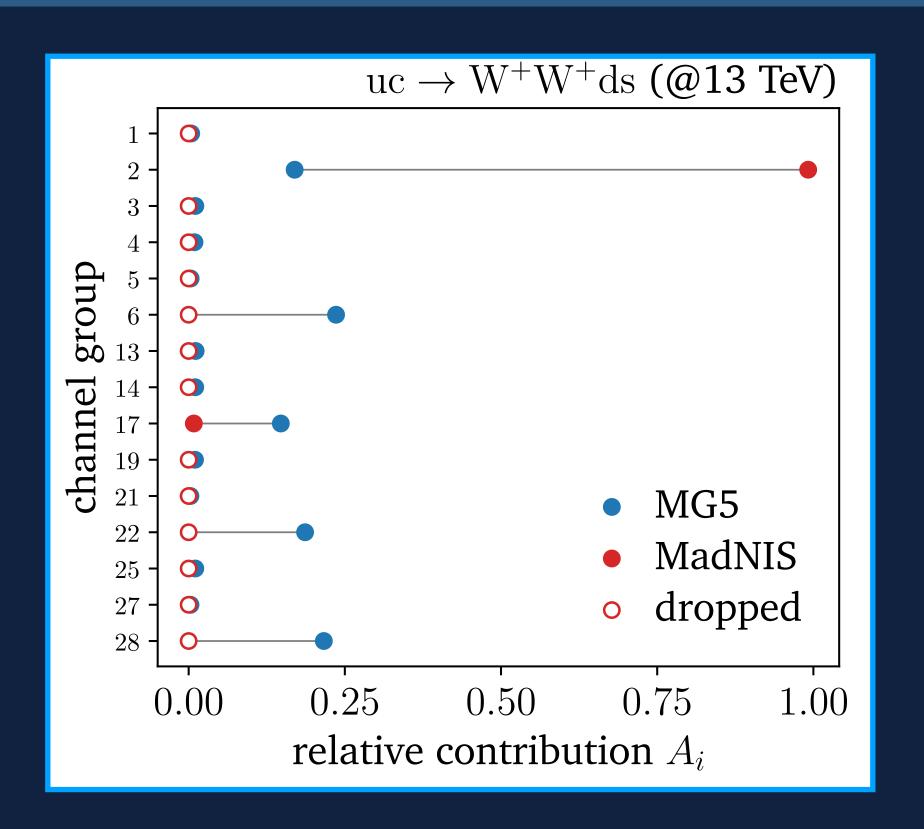


- 1. excellent results with all improvements
- 2. same performance with buffered training
- 3. Larger improvements for processes with large interference terms

Learned channel weights







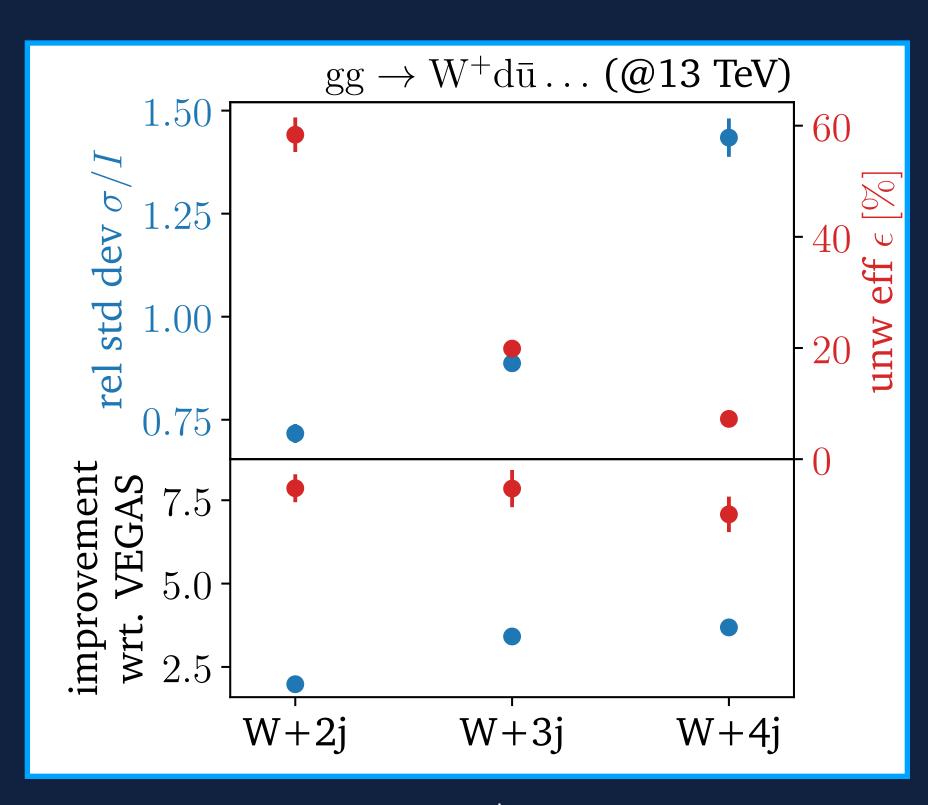
In MadNIS many channels are zero

that droppig channels

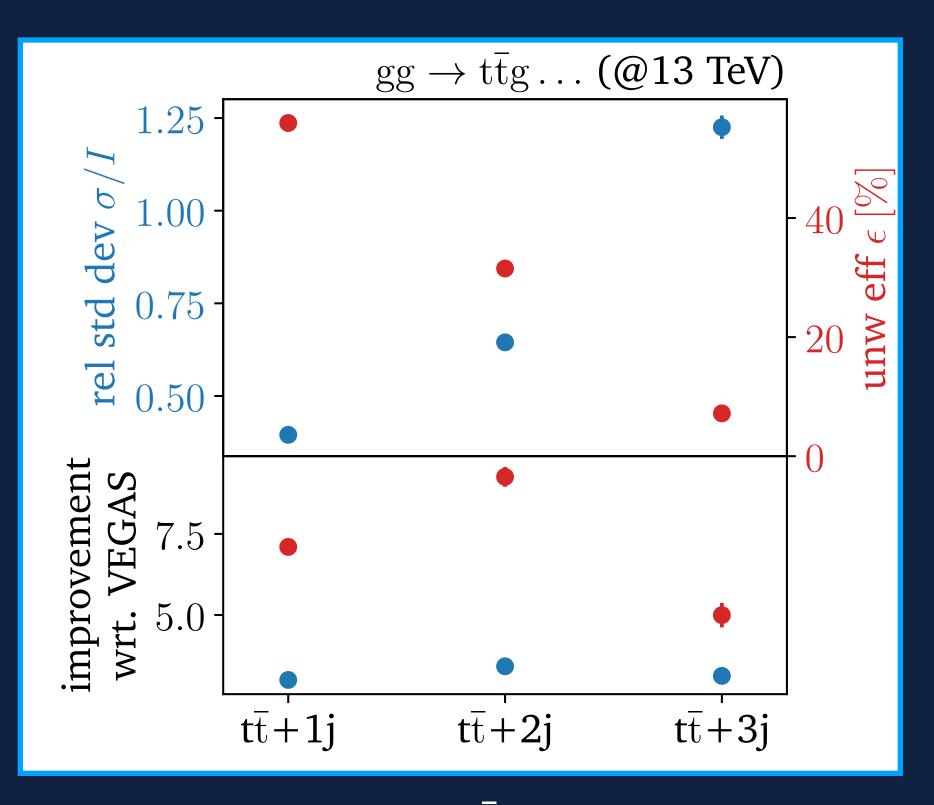
more efficient training and event generation

Scaling with multiplicity





 $gg \rightarrow W^+ d\bar{u}gg$ 384 channels, 108 symm. 7x better than VEGAS



 $gg \rightarrow t\bar{t}ggg$ 945 channels, 119 symm. 5x better than VEGAS

Large improvements compared to VEGAS even for high multiplicities and many channels!

Outlook



The MadNIS Reloaded

Large improvements, even for high multiplicites and complicated processes!



Future plans

Make MadNIS part of next MadGraph version

