



Ameliorating transient noise bursts in gravitational-wave searches for intermediate-mass black holes

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# What is a compact binary coalescence (CBC)?

Credits: Max Planck Institute



Binary systems consisting on compact objects in a compact orbit around each other.

#### GW simulation parameters:

 $m_1, m_2$ : component masses  $s_1, s_2$ : angular momentum or spin





# Modelled searches: matched filtering (MF) for CBC







# Transient noise burst (glitches)

- Caused by instruments or environment Ο (known or unknown)
- Diminish scientific data available 0
- Hinder GW detection (mask and/or mimic) Ο



Example of a blip glitch (left) and a intermediate-mass black hole (right)





### Motivation

**Context:** intermediate-mass black holes (IMBH) are the missing link between stellar black holes and supermassive black holes, but they are hard to detect!

**Idea:** use triggers from matched filtering (free information) from detection algorithms to learn the background (glitches) and foreground (GW signals) with ML



Example of a blip glitch (left) and a IMBH (right)

- MF searches use *strict* conditions for detection.
- Can we *relax* the search with the interpolation ability of ML?

#### Similar ideas with cWB:

- Gayathri et al. 2020 (XGBoost)
- Lopez et al. 2021 (GMM)

#### VIRCE

# A simulated GW through a detection pipeline

 $\Delta t$ : time when trigger happened – time when GW signal was added to the noise

Strain





Melissa Lope

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# A glitch through a detection pipeline





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# Methodology

**Task:** Distinguish IMBH from different glitch classes in single detector  $\rightarrow$  we have 3 detectors!

**Data:** reproduce IMBH search GstLAL O3 but truncate it  $\rightarrow$  only matched filtering

Algorithm: Multi-layer perceptron (MLP)

**Input:** Adding time is hard, so let's simplify the problem. Each template is defined by  $m_1, m_2, s_{1z}, s_{2z}, \chi^2, SNR$ . We weight average by SNR to get the feature vector

 $\mu(m_1, m_2, s_{1z}, s_{2z}, \chi^2, SNR)$ 

Output: class probability



**Idea:** MLP differentiates **6 classes**: 5 different types of background (glitches) and single foreground (GW signals). It uses only **6 parameters** in **single detector** 





# Methodology

1. Accounting for imbalanced data (boostrapping with replacement)



We avoid unbalanced data and overfitting



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#### Results: diving into the known (controlled data set)







## Results: diving into the known (time coincidence)





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### Results: diving into the (un)known – GWOSC catalogue



It has learnt to identify GW simulations. Can we see real GW signals?

WARNING: this is *not* a detection, i.e. **no** background estimation

#### Results: diving into the (un)known – Other catalogues

WARNING: this is not a detection, i.e. **no** background estimation



Olsen et al. 2023, Phys. Rev. D 106, 043009



### Conclusions & future work

We can differentiate signals from glitches with MF triggers & neural networks

- ✓ We learned O3a and explored generalization power in O3b
- Identified GW190521 and other GW signals
- Paper out soon. Stay tuned!
- Background estimation
- Include time component: ordering might be relevant
- Extend to other template banks and/or pipelines

Thank you for listening! Questions?



### Extra slides

# Results: diving into the (un)known - GW190521

#### LIGO Hanford (H1)



Niklhef

#### LIGO Livingston (L1







#### Virgo (V1)



### What does the dynamic SNR pattern look like?

Taking time interval: -1s < event time < 1s



Not all glitches produce many injections/triggers



