

Simulation of the gravitational-wave emission of core-collapse supernovae

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1 Simulations and gravitational waves

GR simulations \longrightarrow waveform templates \longrightarrow detection + PE





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Credit: LIGO-Virgo / Aaron Geller / Northwestern University

1 The Einstein Telescope



Credit: Nikhef / Marco Kraan

New sources \Rightarrow we need to be ready!

2 Simulation of the gravitational-wave emission of core-collapse supernovae

1 Goal

Simulation of yet unobserved systems generating gravitational waves



 \Rightarrow Need accurate simulations to understand the system + detect signal and interpret the data

1 Need for simulations, but...

Simulations are expensive and challenging!

Typically multi-scale (length + time) problems. *E.g.* supernovae:

- ▶ Turbulence $\sim \mathcal{O}(1)$ m, radius of core $\sim \mathcal{O}(10^6)$ m
- ▶ Small time steps required, but simulation $\sim O(1)$ s



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Challenges:

- Many simulations to span the parameter space
- Need very accurate simulations
- Systems to simulate (multi-scale, ...)
- \Rightarrow cost and reliability/accuracy of the simulations

2 Physics model

$$\begin{split} R_{\mu\nu} &- \frac{1}{2} g_{\mu\nu} R = T_{\mu\nu}, \\ \nabla_{\mu} \left(\rho u^{\mu} \right) &= 0, \\ \nabla_{\mu} T^{\mu\nu} &= 0, \\ p &= p \left(\rho, \epsilon, \cdots \right), \\ \left\{ \begin{array}{c} \nabla_{\mu} F^{\mu\nu} &= \mathcal{J}^{\nu}, \\ \nabla_{\mu}^{*} F^{\mu\nu} &= 0, \\ \left(p^{\mu} \frac{\partial}{\partial x^{\mu}} - \Gamma^{\mu}_{\alpha\beta} p^{\alpha} p^{\beta} \frac{\partial}{\partial p^{\mu}} \right) f = \left(\frac{\partial f}{\partial \tau} \right)_{\text{coll}} \\ \vdots \end{split}$$

(Einstein equation)
(cons. rest mass)
(cons. energy/momentum)
(equation of state)

(Maxwell equations)

(Boltzmann equation)

2 Gmunu solver

1-2-3D general-relativistic (magneto)hydrodynamics (GR(M)HD) (Cheong et al 2020, 2021, 2022, 2023; Ng et al 2023)

30 t = 0.0 s t = 1.0 ms 10^{-5} 2015 10^{-8} 10 Example: rapidly rotating 10^{-11} neutron star 30 t = 5.0 ms t = 9.0 ms 10^{-14} Noticeable achievement: NS 20 with $B \sim 10^{17}$ G (Leung et al N 2022) 10^{-17} 10 10^{-20} 20 20 0 r rTaken from (Cheong et al 2021)

Collapse of a star when gravity > pressure



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Collapse of a star when gravity > pressure

Creation of a shock when the core cannot contract anymore = core bounce



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- Collapse of a star when gravity > pressure
- Creation of a shock when the core cannot contract anymore = core bounce
- Propagation of the shock outwards
- Remnant = neutron star (or black hole)
- \Rightarrow Extreme event: very bright, but only $\lesssim 1\%$ of energy in light! $\sim 99\%$ of energy in neutrinos

3 Simulation of core-collapse supernovae

Get gravitational wave signal \rightarrow 2D or 3D simulation to at least few ms after the core bounce

In Gmunu

- Simplest 1D simulation (16 cpus): < 1h to core bounce (~ 213ms), ~ 23h to 250ms
- Simplest 2D simulation (64 cpus): $\sim 14h$ to core bounce

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Advantages of Gmunu

- Simulation of the neutron star
- Recently improved microphysics (Ng et al 2023)

3 Simplifcations

Very expensive simulation \rightarrow simplifications needed

- No magnetic field
- Approximation of Boltzmann equation $(6D!) \rightarrow M1$ scheme
- Limited simulation domain $\sim 10^4$ km (~ 100 NS radius)

Several different codes with different levels of approximation: 1-2-3D, with or without B, Newtonian + GR corrections, ... (see *e.g.* [1–4])

But what do we lose with these approximations?

4 Conclusion

- We need simulations to detect new sources + interpret data
- Many simulations to span parameter space, but expensive
- Use the code Gmunu to simulate core-collapse supernovae
- ► Simplifications → what do we lose ?

6 References I

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Back-up slides

7 Finite volume discretization

General-relativistic version of conserved equation:

$$\partial_t oldsymbol{q} + rac{1}{\sqrt{\hat{\gamma}}} \partial_j \left[\sqrt{\hat{\gamma}} oldsymbol{f}^j
ight] = oldsymbol{s} + oldsymbol{s}_{\mathsf{geom}}$$

volume-average $\langle \bullet \rangle \equiv \frac{1}{\Delta V} \int_{\rm cell} \bullet \sqrt{\hat{\gamma}} dx^1 dx^2 dx^3$,

$$\frac{d}{dt} \left\langle \boldsymbol{q} \right\rangle_{\mathbf{i},\mathbf{j},\mathbf{k}} = \frac{-1}{\Delta V_{\mathbf{i},\mathbf{j},\mathbf{k}}} \left\{ \left[\left(\left\langle \boldsymbol{f} \right\rangle^1 \Delta A^1 \right) \Big|_{\mathbf{i}+1/2,\mathbf{j},\mathbf{k}} - \left(\left\langle \boldsymbol{f} \right\rangle^1 \Delta A^1 \right) \Big|_{\mathbf{i}-1/2,\mathbf{j},\mathbf{k}} \right] + \cdots \right\} \\ + \left\langle \boldsymbol{s} \right\rangle_{\mathbf{i},\mathbf{j},\mathbf{k}} + \left\langle \boldsymbol{s}_{\text{geom}} \right\rangle_{\mathbf{i},\mathbf{j},\mathbf{k}},$$

Solved with *high-resolution shock-capturing* (*HRSC*) method



7 Primitive and conservative (ideal MHD)

Primitive:
$$\rho, v_j, e, B^i$$

Conservative: $D, S_j, \tau, \mathcal{B}^i$
 $D \propto \rho W$
 $S_j \propto \rho h^* W^2 v_j - \alpha b^0 b_j$
 $\tau \propto \rho h^* W^2 - p^* - (\alpha b^0)^2 - D$

with

$$W = \frac{1}{\sqrt{1 - v^2}}$$
$$p^* = p + \frac{b^2}{2}$$
$$h^* = 1 + \epsilon + \frac{p + b^2}{\rho}$$

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7 Divergence-free magnetic field

One of Maxwell's equations is $\nabla \cdot \mathbf{B} = 0$. To satisfy this constrain equation, *Gmunu* can use elliptic divergence cleaning by soling Poisson's equation

$$\nabla^2 \Phi = \nabla \cdot \mathcal{B}_{\mathsf{old}},$$

and then using the resulting Φ to enforce a divergence-free magnetic field with

$$\mathcal{B}_{\mathsf{new}} = \mathcal{B}_{\mathsf{old}} - \nabla \Phi$$

Indeed, taking the divergence we get

$$\nabla \cdot \mathcal{B}_{\mathsf{new}} = \nabla \cdot \mathcal{B}_{\mathsf{old}} - \nabla^2 \Phi,$$

which is 0 by definition of Φ .

7 Boltzmann equation (Cardall et al 2013)

$$\begin{split} S_{N} &+ M_{N} = C[f] \\ S_{N} &= \frac{-p_{\hat{0}}}{\alpha\sqrt{\gamma}} \left[\frac{\partial}{\partial t} \left(\frac{\gamma}{-p_{\hat{0}}} \mathcal{L}_{\hat{\mu}} p^{\hat{\mu}} f \right) + \frac{\partial}{\partial x^{i}} \left(\frac{\sqrt{\gamma}}{\left(-p_{\hat{0}}\right)} \left(\alpha \ell^{i}{}_{\hat{\mu}} - \beta^{i} \mathcal{L}_{\hat{\mu}} \right) p^{\hat{\mu}} f \right) \right] \\ M_{N} &= \frac{1}{\alpha\sqrt{\gamma}} \frac{\left(-p_{\hat{0}}\right)}{\sqrt{\lambda}} \frac{\partial}{\partial p^{i}} \left\{ \sqrt{\lambda} \frac{Q^{i} \left(-p_{\hat{0}}\right)}{p} \left[(R_{N})^{\hat{0}} + (O_{N})^{\hat{0}} \right] \right. \\ &\left. + \sqrt{\lambda} U^{i}{}_{i} \left[(R_{N})^{\hat{i}} + (O_{N})^{\hat{i}} \right] \right\} \\ (R_{N})^{\hat{\rho}} &= \frac{\alpha\sqrt{\gamma}}{\left(-p_{\hat{0}}\right)} p^{\hat{\nu}} p^{\hat{\mu}} f \left[\mathcal{L}^{\hat{\rho}} \ell^{j}{}_{\hat{\nu}} \left(\frac{\mathcal{L}_{\hat{\mu}}}{\alpha} \frac{\partial \alpha}{\partial x^{j}} - \ell^{k}{}_{\hat{\mu}} K_{jk} \right) \right. \\ &\left. - \ell^{\hat{\rho}j} \left(\frac{\mathcal{L}_{\hat{\nu}} \mathcal{L}_{\hat{\mu}}}{\alpha} \frac{\partial \alpha}{\partial x^{j}} - \frac{\ell_{k\hat{\nu}} \mathcal{L}_{\hat{\mu}}}{\alpha} \frac{\partial \beta^{k}}{\partial x^{j}} - \frac{\ell^{k}{\hat{\nu}} \ell^{i}{}_{\hat{\mu}}}{\partial x^{j}} \right) \right] \\ (O_{N})^{\hat{\rho}} &= \frac{\sqrt{\gamma}}{\left(-p_{\hat{0}}\right)} p^{\hat{\nu}} p^{\hat{\mu}} f \left\{ \mathcal{L}^{\hat{\rho}} \left[\mathcal{L}_{\hat{\mu}} \frac{\partial \mathcal{L}_{\hat{\nu}}}{\partial t} + \left(\alpha \ell^{j}{}_{\hat{\mu}} - \beta^{j} \mathcal{L}_{\hat{\mu}} \right) \frac{\partial \mathcal{L}_{\hat{\nu}}}{\partial x^{j}} \right] \right\} \end{split}$$

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7 Neutrino interactions

6 different species of neutrinos, only n=3 considered. Each neutrino has an energy \rightarrow energy space divided in m bins. Different ways to treat interactions

► Simplest: no interaction between neutrinos: "ss sg" → Each species and energy evolved independently: n × m systems of (D + 1) equations

Intermediate: interactions between neutrinos of same species and different energy: "ss mg"

 \rightarrow Each species evolved independently, energies coupled: n systems of $m\times (D+1)$ equations

► Complete: interactions between all species: "ms mg" → Species and energies coupled: 1 system of n × m × (D + 1) equations