

## ROOT practicalities

- Practical workflow:
  - You can run on your laptop (if you installed it yourself), or run on stoomboot
  - You need ROOT version 5.34.21 or higher, preferably 5.34.36
  - I have tested all exercise macros with ROOT 5.34.36, which I installed on stoomboot. You can use this version as follows:

```
source /project/atlas/user/verkerke/root-53436/bin/thisroot.sh
(or .csh)
```
- Input files for exercises (ex1.C etc) can be found in directory `~verkerke/stat2016/` on stoomboot or login.nikhef.nl
- Annotations in exercises:
  - 'CODE' – means that you need to write some code
  - 'EXEC' – means that you need to run your code and interpret its output
- Macros have been tested with ROOT 5.34/21 & 5.34.36
  - Problems? Please ask (I didn't test everything on all platforms)

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## Exercise 11 – A sideband measurement

- We will now explore the similarity between subsidiary measurements and sideband measurements
  - In the model of Ex9 the background rate was constrained by a Gaussian subsidiary measurement that measurement  $B=20$  with an uncertainty of 5
- Run macro `ex11.C`
- This macro does the following for you
  - It rebuild the model of Ex 10 in a compact syntax, and fits it to the data
- Now we rebuild the model assuming that B is measurement in a control region, rather than describing an 'abstract' Gaussian uncertainty
  - Construct a Poisson model for a fictitious control region that measures the model parameter B from an observed number of event  $N_{CTL}=20$  in the control region (Hint: name this model 'control\_model', and name the observable for this control region 'Nctl' and set it to a constant value of 20
  - Once the control measurement is made, construct a new product (name it 'model3' of the original measurement 'model' and 'control\_model')
  - Fit `model3` to the data, compared the results

## Exercise 11– continued

- Comparing the results
  - You will find that the uncertainty on  $\mu$  between the fit to `model2` and `model3` is somewhat different. This is driven by the fact that the uncertainty on  $B$  in both models is also somewhat different: `model2` implements a Gaussian uncertainty of width 5, whereas the sideband measurement with `Nctl` measures and uncertainty of  $\sqrt{20}$ .
  - We have so far assumed that the control region measures the same  $B$  as 'model', but it could very well be that the control region is larger, and would effectively measure twice the rate (i.e. if `Nctl` =40 then  $B=20$ ). To introduce this effect of the 'size' of the control region, we introduce an extra (constant) parameter in the model that expresses this rescaling: Construct a new sideband model (name it `model_control2`) that implements  $\text{Poisson}(Nctl|\tau*B)$  where  $\tau$  is a constant parameter with value 2.  
Hint: you can use an `expr::tauxb('tau*b', tau, b)` function expression to construct an object that represents the product 'tau\*b'.
  - Once this is done, construct a new full model (named `model4`) that is the product of 'model' and 'model\_control2' and fit this again to the data. What happens to the uncertainty on  $B$  and  $\mu$ ?
  - What value of  $\tau$  should you use to obtain uncertainties on  $B$  and  $\tau$  that are identical to those of `model2`?

## Exercise 12

- Template fits
  - We will now construct a first template fit, where a signal and a background model are described by a histogram obtained from MC simulation
- Run `ex12.C`
  - Note that this macro uses input file `ex12.root`
- This macro does the following for you
  - It opens `ex12.root` and uses the a template histogram in `ex12.root` to construct a probability model for 'signal' in an observable  $x$
- Performing a simple template fit
  - Open first `ex12.root` and look at the `TH1` histograms stored in here: there is a signal template, a background template and a 'data' histogram
  - In a new root session, run macro `ex12.C`. You now see the signal histogram used to construct a yield function (a `RooHistFunc`) in. Add code to also do this for the background template (the `TH1` is called `h_bkg`, name the corresponding `RooDataHist` and `RooHistFunc` `dh_bkg` and `fh_bkg` respectively)

## Exercise 12 - continued

- Performing a simple template fit
  - Now construct from the sum of two yield functions a probability model as follows (in the workspace factory)

```
ASUM::model(mu[1,0,5]*hf_sig,nu[1]*hf_bkg)
```

This class takes two yield histograms and turns the weighted sum of these in a probability model that can be fitted.
  - Fit the model to the data, make a plot of the data overlaid with the fitted model (hint: first call `data.plotOn(frame)` and then `model.plotOn(frame)`). You can also overlay the background component of the model using

```
pdf("model")->plotOn(frame,
    Components("hf_bkg"),LineStyle(kDashed));
```
  - OPTIONAL: repeat this exercise with different templates and datasets to observe how signal/background shape and yields affect the fitted signal rate  $\mu$ . To make these modified inputs, copy file `makeinput_ex10.C`, adjust the parameters inside it, and run it to regenerate `ex10.root`

## Exercise 13

- Constructing a template morphing model that accounts for a 'jet energy scale' (JES) uncertainty in the signal template
- Run macro `ex13.C`
- What does this macro do for you?
  - It opens `ex13.root` and uses the a template histogram in `ex13.root` to construct a probability model for 'signal plus background' in an observable  $x$
  - Note that we switched back to 100 bins for a more 'dramatic' visualization
- Constructing a template morphing model
  - Run the macro as provided and observe the fit result and plotted result.
  - The first step towards setting up a template morphing model is constructing `HistFunc` objects for the JES-up and JES-down variation templates (the datasets are already imported by the macro)
  - The next step is to make a template morphing signal model. The 'magic' class to do this is called `PiecewiseInterpolation`. The workspace factory string to make such an object is

```
PiecewiseInterpolation::pi_sig(Fnom,Flo,Fhi,NP)
```

where `Fnom/lo/hi` are the `RoohistFuncs` representing the nominal, down and up templates and `NP` is the nuisance parameter associated with the systematic uncertainty. Construct the `PiecewiseInterpolation` function, and the nuisance parameter (call that one 'alpha' with a range `[-5,5]`).

## Exercise 13 - continued

- Constructing a template morphing model
  - Make a 2D plot of the template morphing signal model in the observable  $x$  and the nuisance parameter  $\alpha$ 

```
w->function("pi_sig")->createHistogram("x,alpha")->Draw("SURF")
```
  - You will clearly see that in the default configuration the signal model is allowed to extrapolate to negative signal yields. Disable this feature (`w->function("pi_sig")->setPositiveDefinite(kTRUE)`) and remake the above plot
  - You also clearly see the kinks in the predictions at  $\alpha=0$ , as the model by default implements a piece-wise linear model. Switch this to polynomial interpolation model (`w->function("pi_sig")->setAllInterpCodes(4)`) and remake the above plot.
  - Finally construct the full template morphing model by
    - 1) replacing in the 'model', the simple signal model 'hf\_sig' with the morphing model 'pi\_sig'
    - 2) constructing the full likelihood 'model2' as the product of 'model1' and Gaussian subsidiary measurement on  $\alpha$  (with observed value 0 and width 1)
  - Fit the template morphing model to the data and observe the effect of the introduction of the JES uncertainty on  $\mu$ .
  - Also look at the fitted value of  $\alpha$  and its uncertainty. Is the physics measurement able to constrain the JES uncertainty beyond the 'input' of the subsidiary measurement?

## Exercise 15 – (Optional, skip if you are short on time!)

- Performing a template fit accounting for MC statistical uncertainties 'Beeston-Barlow-style'
- Run macro `ex15.C`
  - Note that this macro uses input file `ex15.root`
- This macro does the following for you
  - It opens `ex15.root` and uses the template histograms in `ex15.root` to construct a probability model for 'signal plus background' in an observable  $x$
  - Note that the number of bins has changed from 100 to 20
- A template fit accounting for statistical uncertainties
  - Perform a fit of the 'model' to the 'data' dataset and plot the dataset and model overlaid, following the example of `ex12`.
  - Now change the 'rigid' template for signal and background in a 'flexible' template for signal and background as follows:: change class `HistFunc` in class `RooParamHistFunc`
  - When you fit again you will that result is (still) the same, as parameters that can change each bin the templates are initially constant.

## Exercise 15 – (Optional, skip if you are short on time!)

- A template fit accounting for statistical uncertainties
  - Now we need to construct the classes that introduces the subsidiary Poisson measurements that constrain the parameters of the flexible template parameters to the “measured” MC event counts:

```
HistConstraint::hc_sig(hf_sig)
```

The only constructor argument is the template function (`RooParamHistFunc`, named `'hf_sig'` in the code example above) for which it makes subsidiary measurement.

(The construction of this subsidiary measurement will ‘automagically’ make all parameters of the `RooHistFunc` floating)

Construct objects of type for both the signal and background template (name them `hc_sig` and `hc_bkg`)

Finally, construct the full model multiplying the template model and the two `HistConstraint` objects (use `PROD::model2(...)` to construct the product.

- Note that you can use one `PROD()` object to multiply any number of models
- Fit the template ‘model2’ that now includes Beeston-Barlow MC statistical uncertainty treatment. Look at the values of all fit parameters and in particular compare the uncertainty on  $\mu$  of this fit w.r.t. the earlier fit to the rigid template model. Is the difference between  $\mu$  uncertainties consistent with your expectation?