

PCMAG field map (cont'd)

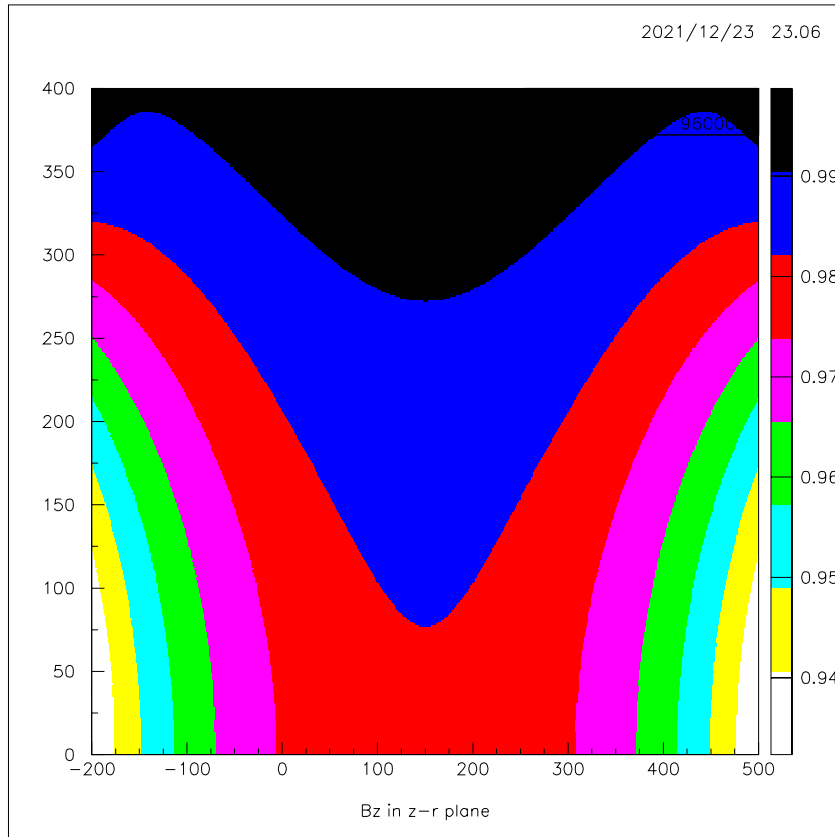
And some effects on curved tracks

/data/lepcol/testbeam_DESY_june21/PCMAG/PCMagFieldMap.dat

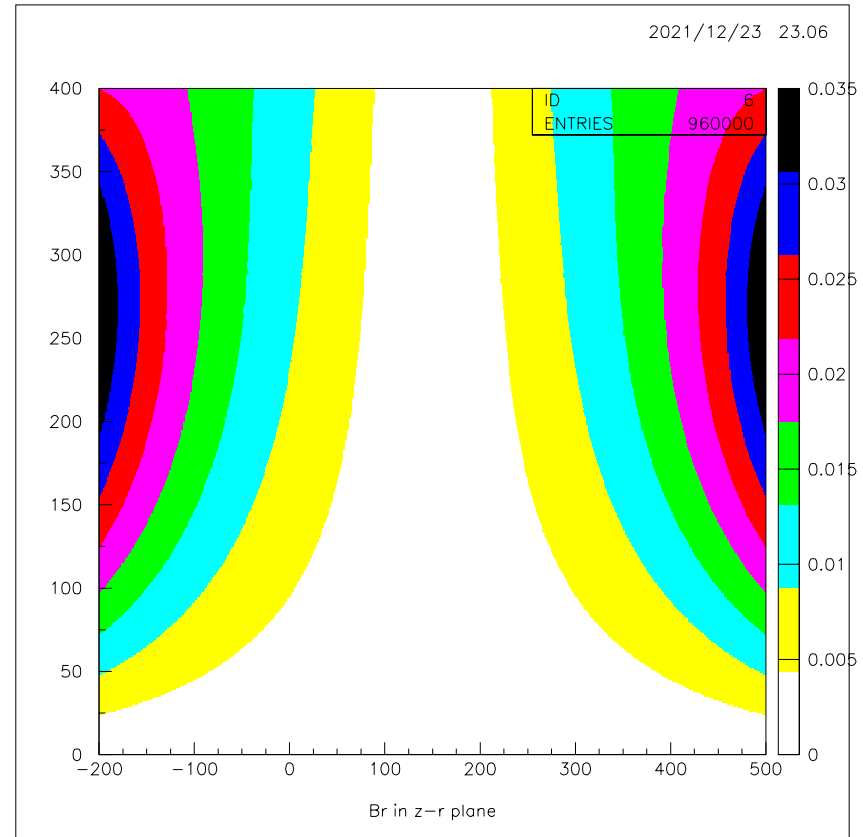
(28.784171 Mb)

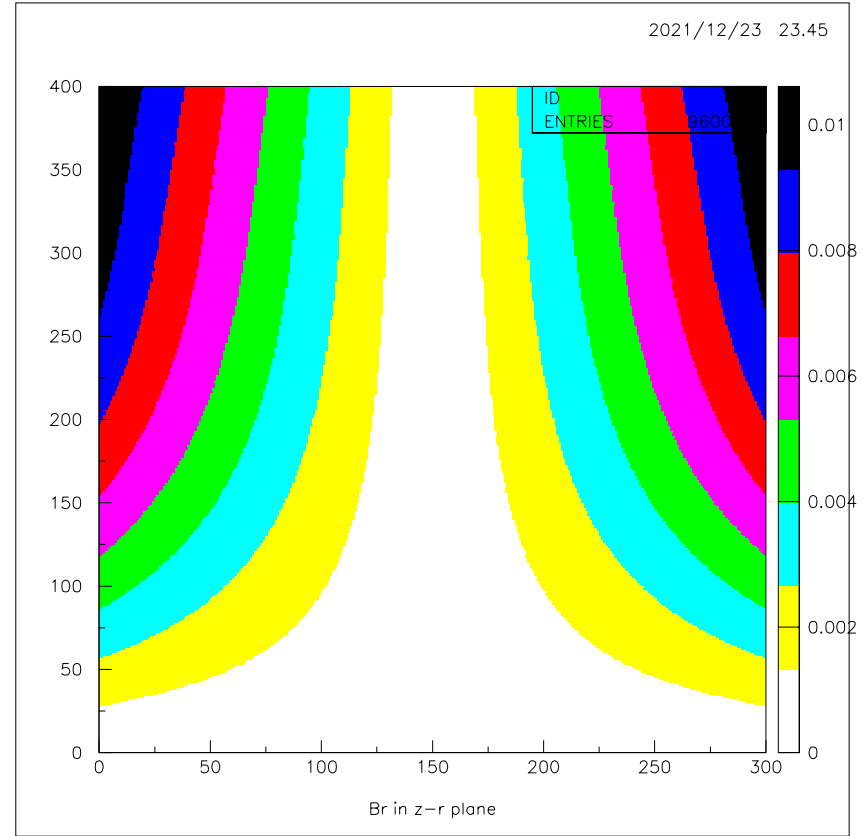
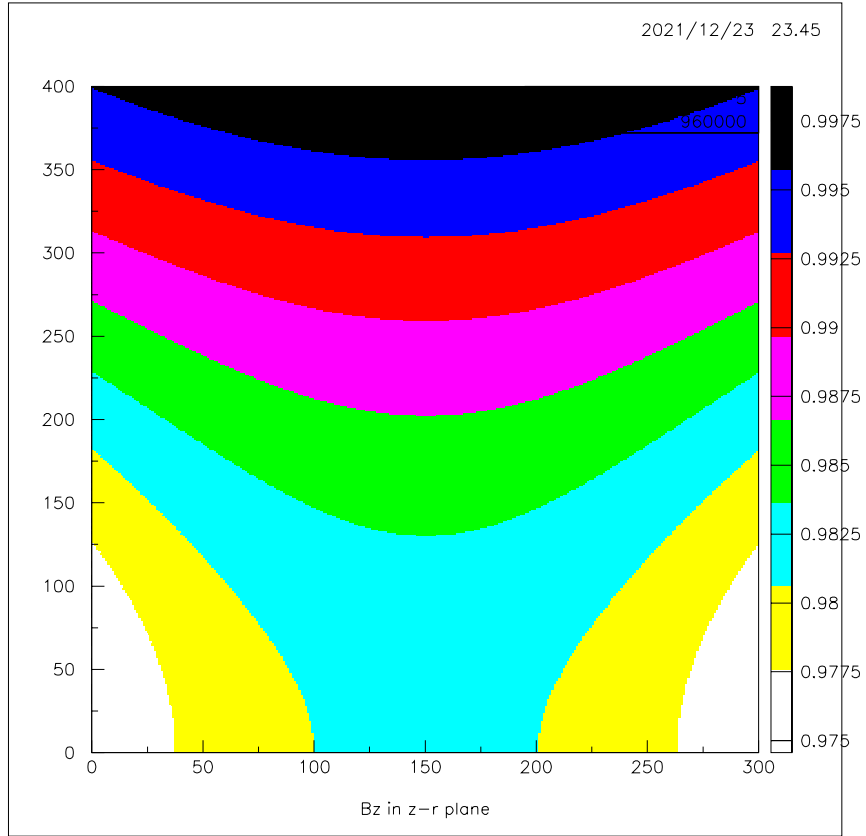
- Solenoidal field (cylindrical symmetry)
- Simple textfile, 960000 data point lines: r, z, B_r, B_z (r, z in mm; B_r, B_z in Tesla)
- 1600 points along z from -799.5 to +799.5 in steps of 1 mm
- 600 groups with r from 0.5 to 599.5 in steps of 1 mm
- $r=0$ magnet axis
- $z=0$ does NOT correspond to maximum in B_z ; B_{\max} approx. at $z = +150.5$

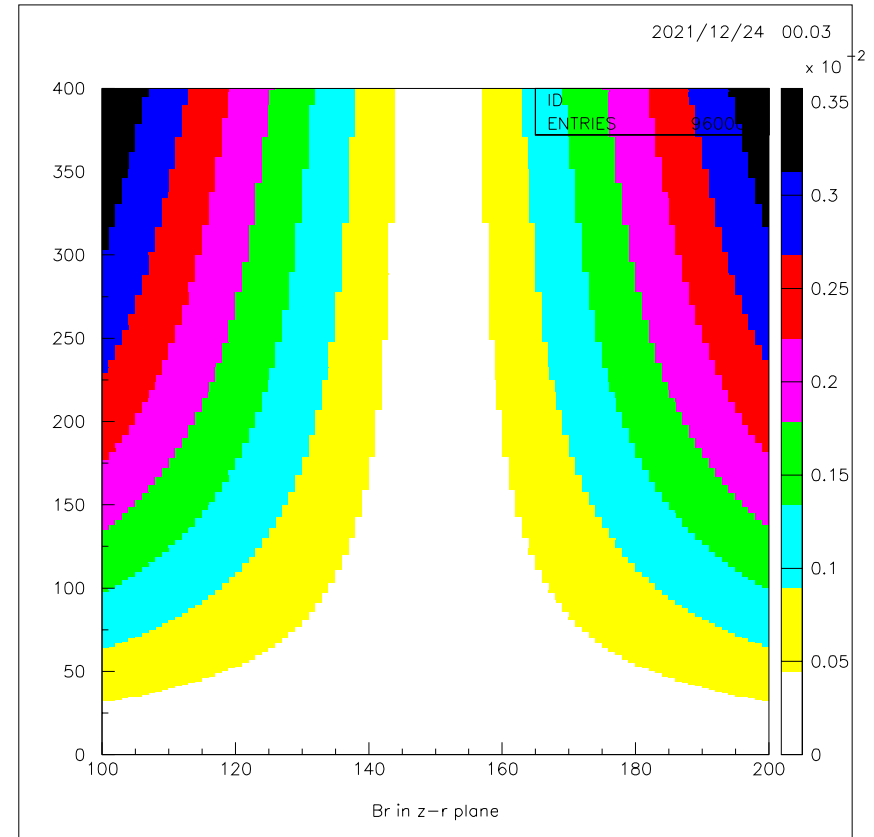
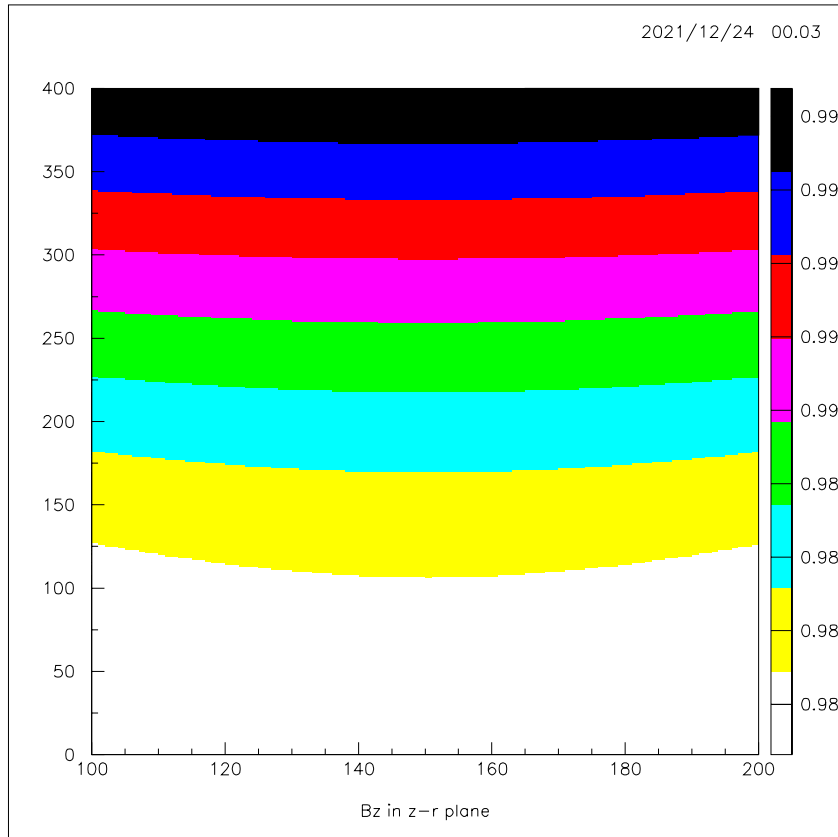
B_z



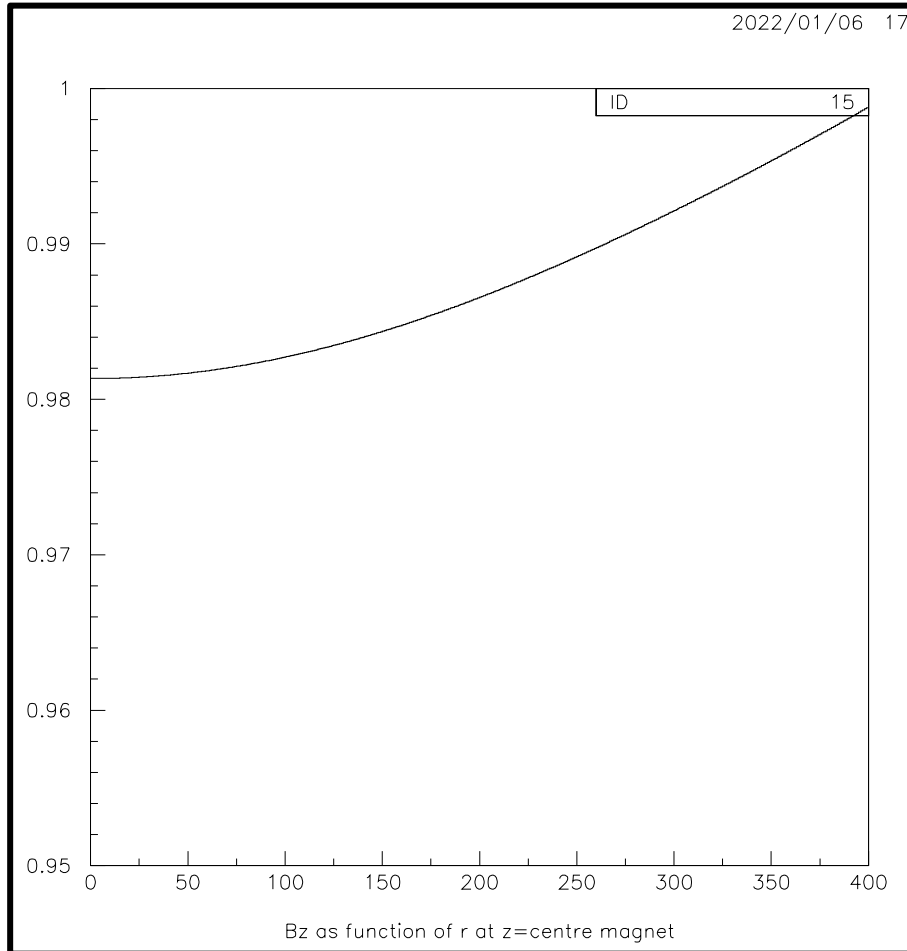
B_r







B_z as function of r at z =centre-of-magnet; B_r at this z is 0 T



14/02/2022

Jan Timmermans -- LEPCOL meeting

Give B_z value in Tesla:

B-value = 1.0000, 0.9900, 0.9800 Tesla

momentum: p= 1. p= 2. p= 3. p= 4. p= 5. p= 6.

y= 0.0 beam posit. =	0.000	0.000	0.000	0.000	0.000	0.000
y= 0.0 beam posit. =	0.000	0.000	0.000	0.000	0.000	0.000
y= 0.0 beam posit. =	0.000	0.000	0.000	0.000	0.000	0.000

y= 156.5 beam posit. =	3.676	1.837	1.225	0.918	0.735	0.612
y= 156.5 beam posit. =	3.639	1.819	1.212	0.909	0.727	0.606
y= 156.5 beam posit. =	3.602	1.800	1.200	0.900	0.720	0.600

y= 182.0 beam posit. =	4.972	2.485	1.656	1.242	0.994	0.828
y= 182.0 beam posit. =	4.923	2.460	1.640	1.230	0.984	0.820
y= 182.0 beam posit. =	4.873	2.435	1.623	1.217	0.974	0.812

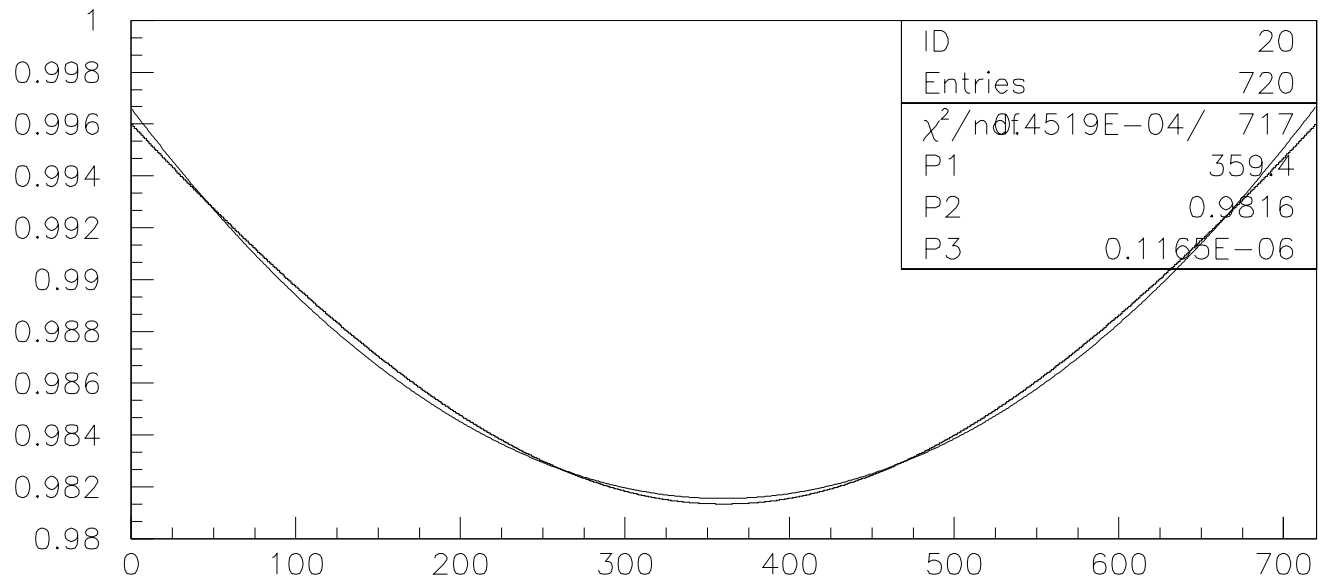
y= 207.5 beam posit. =	6.465	3.230	2.153	1.615	1.292	1.076
y= 207.5 beam posit. =	6.400	3.198	2.132	1.599	1.279	1.066
y= 207.5 beam posit. =	6.335	3.165	2.110	1.582	1.266	1.055

y= 360.0 beam posit. =	19.497	9.727	6.482	4.861	3.888	3.240
y= 360.0 beam posit. =	19.301	9.630	6.417	4.812	3.850	3.208
y= 360.0 beam posit. =	19.105	9.532	6.352	4.764	3.811	3.175

y= 512.5 beam posit. =	39.634	19.728	13.141	9.853	7.882	6.567
y= 512.5 beam posit. =	39.233	19.531	13.010	9.755	7.803	6.502
y= 512.5 beam posit. =	38.832	19.333	12.878	9.656	7.724	6.436

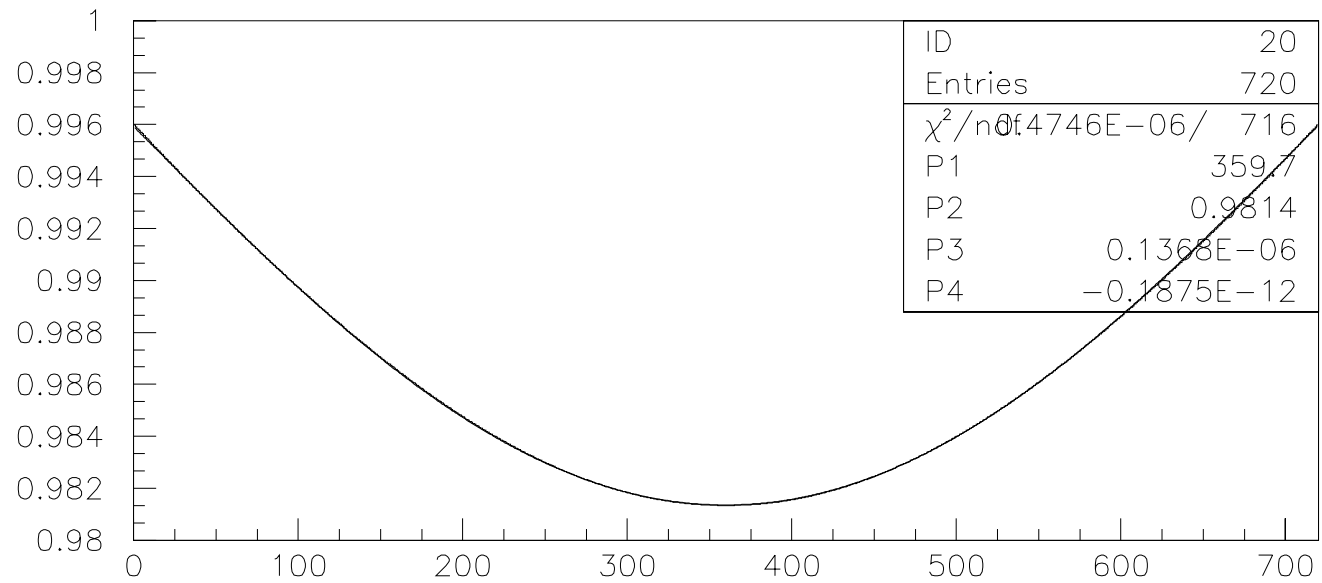
y= 538.0 beam posit. =	43.703	21.744	14.483	10.859	8.686	7.237
y= 538.0 beam posit. =	43.260	21.526	14.338	10.750	8.599	7.165
y= 538.0 beam posit. =	42.818	21.308	14.193	10.641	8.512	7.093

y= 563.5 beam posit. =	47.975	23.858	15.889	11.913	9.529	7.940
y= 563.5 beam posit. =	47.488	23.618	15.730	11.794	9.433	7.860
y= 563.5 beam posit. =	47.002	23.379	15.571	11.674	9.338	7.781



(symmetric) Quadratic fit to B-field

Bz as function of detector z



**(symmetric) Quartic fit to B-field
So only z^2 and z^4 terms**

Bz as function of detector z

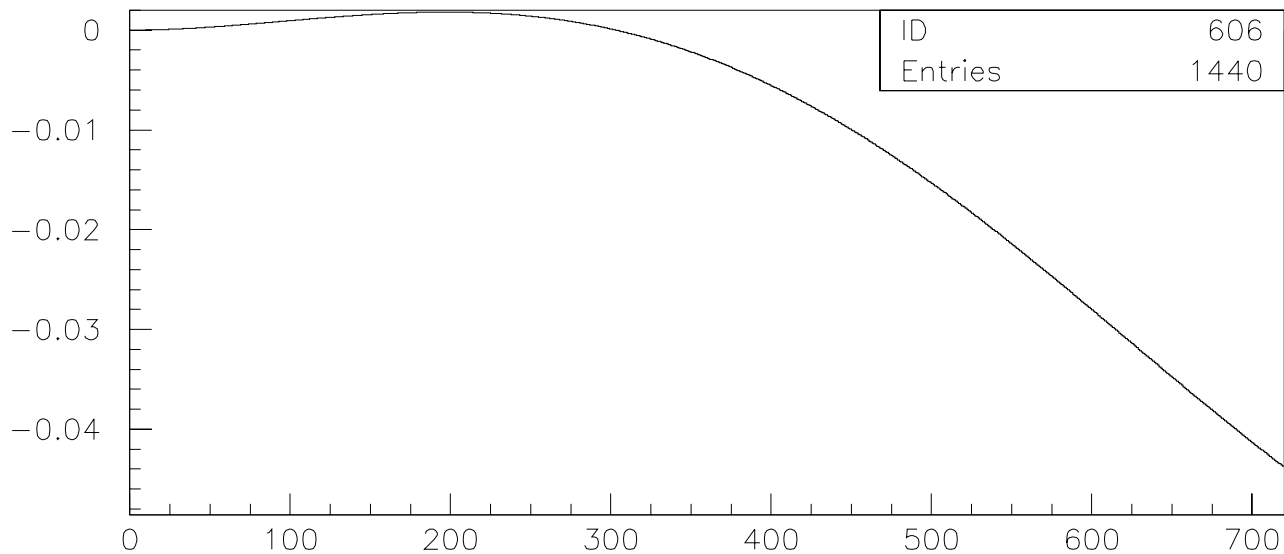
Detector name/positions:

Entr 0.00
Mim0 156.50
Mim1 182.00
Mim2 207.50
TpxE 280.00
TpxC 360.00
TpxB 440.00
Mim3 512.50
Mim4 538.00
Mim5 563.50

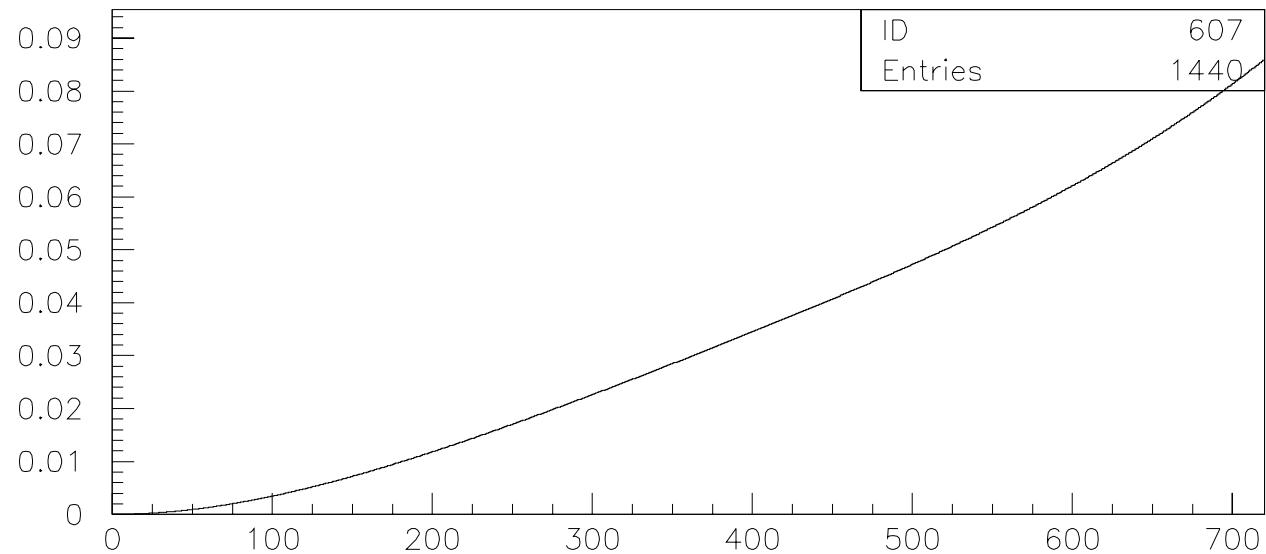
Beam deflections at the various detectors:

1. B=1.000 T
2. B=0.990 T
3. B=0.980 T
4. Use B-map info

Entr	B=1.000T	z= 0.00	beam posit. =	-0.000	-0.000	-0.000	-0.000	-0.000	-0.000
	B=0.990T	z= 0.00	beam posit. =	-0.000	-0.000	-0.000	-0.000	-0.000	-0.000
	B=0.980T	z= 0.00	beam posit. =	-0.000	-0.000	-0.000	-0.000	-0.000	-0.000
	Buse_map	z= 0.00	beam posit. =	0.000	0.000	0.000	0.000	0.000	0.000
Mim0	B=1.000T	z= 156.50	beam posit. =	-3.676	-1.837	-1.225	-0.919	-0.735	-0.612
	B=0.990T	z= 156.50	beam posit. =	-3.640	-1.819	-1.213	-0.909	-0.728	-0.606
	B=0.980T	z= 156.50	beam posit. =	-3.603	-1.801	-1.200	-0.900	-0.720	-0.600
	Buse_map	z= 156.50	beam posit. =	-3.649	-1.824	-1.216	-0.912	-0.729	-0.608
Mim1	B=1.000T	z= 182.00	beam posit. =	-5.000	-2.499	-1.666	-1.249	-0.999	-0.833
	B=0.990T	z= 182.00	beam posit. =	-4.950	-2.474	-1.649	-1.237	-0.989	-0.824
	B=0.980T	z= 182.00	beam posit. =	-4.900	-2.449	-1.632	-1.224	-0.979	-0.816
	Buse_map	z= 182.00	beam posit. =	-4.961	-2.479	-1.653	-1.239	-0.991	-0.826
Mim2	B=1.000T	z= 207.50	beam posit. =	-6.465	-3.230	-2.153	-1.615	-1.292	-1.077
	B=0.990T	z= 207.50	beam posit. =	-6.401	-3.198	-2.132	-1.599	-1.279	-1.066
	B=0.980T	z= 207.50	beam posit. =	-6.336	-3.166	-2.110	-1.583	-1.266	-1.055
	Buse_map	z= 207.50	beam posit. =	-6.411	-3.203	-2.135	-1.601	-1.281	-1.068
TpxE	B=1.000T	z= 280.00	beam posit. =	-11.824	-5.904	-3.935	-2.951	-2.361	-1.967
	B=0.990T	z= 280.00	beam posit. =	-11.705	-5.845	-3.896	-2.922	-2.337	-1.948
	B=0.980T	z= 280.00	beam posit. =	-11.587	-5.786	-3.856	-2.892	-2.314	-1.928
	Buse_map	z= 280.00	beam posit. =	-11.710	-5.847	-3.897	-2.923	-2.338	-1.948
TpxC	B=1.000T	z= 360.00	beam posit. =	-19.552	-9.755	-6.500	-4.875	-3.899	-3.249
	B=0.990T	z= 360.00	beam posit. =	-19.356	-9.657	-6.435	-4.826	-3.860	-3.217
	B=0.980T	z= 360.00	beam posit. =	-19.159	-9.559	-6.370	-4.777	-3.821	-3.184
	Buse_map	z= 360.00	beam posit. =	-19.339	-9.649	-6.430	-4.822	-3.857	-3.214
TpxB	B=1.000T	z= 440.00	beam posit. =	-29.236	-14.570	-9.707	-7.279	-5.822	-4.852
	B=0.990T	z= 440.00	beam posit. =	-28.941	-14.424	-9.610	-7.206	-5.764	-4.803
	B=0.980T	z= 440.00	beam posit. =	-28.646	-14.278	-9.513	-7.133	-5.706	-4.755
	Buse_map	z= 440.00	beam posit. =	-28.885	-14.396	-9.592	-7.192	-5.753	-4.794
Mim3	B=1.000T	z= 512.50	beam posit. =	-39.636	-19.729	-13.142	-9.854	-7.882	-6.568
	B=0.990T	z= 512.50	beam posit. =	-39.235	-19.531	-13.010	-9.755	-7.803	-6.502
	B=0.980T	z= 512.50	beam posit. =	-38.834	-19.333	-12.879	-9.656	-7.724	-6.436
	Buse_map	z= 512.50	beam posit. =	-39.131	-19.481	-12.977	-9.730	-7.783	-6.485
Mim4	B=1.000T	z= 538.00	beam posit. =	-43.787	-21.785	-14.510	-10.879	-8.702	-7.251
	B=0.990T	z= 538.00	beam posit. =	-43.343	-21.567	-14.365	-10.770	-8.615	-7.179
	B=0.980T	z= 538.00	beam posit. =	-42.900	-21.348	-14.220	-10.661	-8.528	-7.106
	Buse_map	z= 538.00	beam posit. =	-43.220	-21.506	-14.325	-10.740	-8.591	-7.159
Mim5	B=1.000T	z= 563.50	beam posit. =	-47.977	-23.858	-15.890	-11.913	-9.529	-7.940
	B=0.990T	z= 563.50	beam posit. =	-47.490	-23.619	-15.731	-11.794	-9.434	-7.861
	B=0.980T	z= 563.50	beam posit. =	-47.004	-23.380	-15.572	-11.675	-9.338	-7.781
	Buse_map	z= 563.50	beam posit. =	-47.347	-23.549	-15.684	-11.759	-9.406	-7.838



Difference track position
for B=0.990 T and B-map
at p=6 GeV



Difference track position
for B=0.980 T and B-map
at p=6 GeV

Next step(s):

- fit circle through Mimosa detector positions (in dependence) of which/how many detectors participate in track and compare with actual track (and ofcourse also in our TPX detector)