Toy MC vertex fit

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Recap: single vertex fit (nueCC)

M-estimator vs likelihood with timing information

Distance along shower axis



Why do we stick at 1-2 m perpendicular to the shower axis? Nanosecond precision —> ~cm precision!

Distance perpendicular to shower axis



Toy experiment

- Place a neutrino in the origin
 [0, 0, 0]
- Loop through ARCA detector file and generate hits by random pulling from the PDF

• Reconstruct and plot the likelihood and see what resolutions we get



- True vertex = [0, 0, 0], dir = [-1, 0, 0]
- $D_along = 0.6 \text{ cm}, D_perp = 0.8 \text{ cm}$



- True vertex = [0, 0, 0], dir = [-1, 0, 0]
- Fit likelihood pos: [0.006, -0.006, 0.006]+-0.03
- $D_along = 0.6 \text{ cm}, D_perp = 0.8 \text{ cm}$





Hits generated: 1145

- True pos = [0, 0, 0], dir = [-1, 0, 0]
- $D_along = 23 \text{ cm}, D_perp = 30 \text{ cm}$





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Shower elongation

• Resolutions are now in the order of cm (as expected)

• What about shower elongation?

- Vertex at [0, 0, 0,], dir = [1, 0, 0]
 - Light not emitted at vertex, but along shower axis



Taken from Claudio Kopper's thesis

- True pos = [0, 0, 0], dir = [-1, 0, 0]
- Expectation from shower max = [-5.08, 0, 0]





Ζ 800 -5.276 4.066

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- True pos = [0, 0, 0], dir = [-1, 0, 0]
- Expectation from shower max = [-5.08, 0, 0]
- Vertex from likelihood: [-6.27,0.26,1.89]+-0.03
- $D_along = 6.27 \text{ m}$, $D_perp = 1.90 \text{ m}$



8 step elongation, all hits **Time hit residuals**



- Likelihood: very early hits are 'impossible'
- But.. Sometimes it goes OK





- True pos = [0, 0, 0], dir = [0, 0, 1]
- Expectation from shower max = [0, 0, 5.08]



- True pos = [0, 0, 0], dir = [0, 0, 1]
- Expectation from shower max = [0, 0, 5.08]
- Vertex from likelihood: [-0.29,0.13,6.89]+-0.03
- $D_along = 6.89 \text{ m}, D_perp = 0.32 \text{ m}$



Likelihood scan along x-axis, pos=[0.0,0.0,5.084432934806439]

8 step elongation, all hits Hit time residuals

Residues with respect to: [0.0,0.0,5.084432934806439] idues with respect to: [0.0.0.0.5.084432934806439]:r 500 **Entries** Mean Std Dev 400 Shower maximum 300 200 100 <u> ||__________________</u> $\mathbf{0}$ -20 20 80 100 -400 60 40 r[ns]

• This one looks better





Residues with respect to: [-0.28749999999999989,0.1375,6.889374999999999]



• Shower elongation generally messes up the position fit

Include shower elongation in reconstruction

• Hopefully that increases the resolution

Next step

- True pos = [0, 0, 0], dir = [0, 0, 1]
- Expectation from shower max = [0, 0, 5.08]



- True pos = [0, 0, 0], dir = [0, 0, 1]
- Expectation from shower max = [0, 0, 5.08]
- Vertex from likelihood: [-0.01, 0.16, 8.36]+-0.03
- $D_along = 8.36 \text{ m}, D_perp = 0.16 \text{ m}$



Likelihood scan along x-axis, pos=[0.0,0.0,5.084432934806439]